



# ABB i-bus<sup>®</sup> KNX Interface IP IPS/S 3.1.1 Manuel produit



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## 1 Général

L'interface IP IPS/S 3.1.1 ABB i-bus® permet de connecter le bus KNX à un réseau Ethernet. Le réseau permet l'envoi ou la réception de télégrammes KNX vers ou depuis d'autres appareils.

L'interface peut être utilisée comme interface de programmation (ETS) et des clients, p. ex. des programmes de visualisation, peuvent accéder au bus KNX via l'IPS/S 3.1.1.

### 1.1 Utilisation du manuel produit

Le présent manuel vous donne des informations techniques détaillées sur le fonctionnement, le montage et la programmation de l'appareil ABB i-bus® KNX. L'utilisation de l'appareil est décrite au moyen d'exemples.

Le manuel comprend les chapitres suivants :

|            |                                     |
|------------|-------------------------------------|
| Chapitre 1 | Général                             |
| Chapitre 2 | Description technique de l'appareil |
| Chapitre 3 | Mise en service                     |
| Chapitre 4 | Programmation et mise en œuvre      |
| Chapitre A | Annexe                              |

### 1.1.1

#### Remarques

Les remarques et consignes de sécurité de ce manuel sont présentées de la façon suivante :

| Remarque                                               |
|--------------------------------------------------------|
| Astuces destinées à la simplification de l'utilisation |

| Exemples                                                               |
|------------------------------------------------------------------------|
| Exemples d'utilisation, exemples de montage, exemples de programmation |

| Important                                                                                                                                                                |
|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Cette consigne de sécurité est utilisée dès qu'il existe un risque de perturbation d'une fonction, sans pour autant engendrer un risque de détérioration ou de blessure. |

| Attention                                                                                                                                                                |
|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Cette consigne de sécurité est utilisée dès qu'il existe un risque de perturbation d'une fonction, sans pour autant engendrer un risque de détérioration ou de blessure. |

|  Danger                                        |
|----------------------------------------------------------------------------------------------------------------------------------|
| Cette consigne de sécurité est utilisée dès qu'une utilisation inappropriée expose à un danger la vie ou l'intégrité corporelle. |

|   Danger |
|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Cette consigne de sécurité est utilisée dès qu'une utilisation inappropriée expose à un danger de mort.                                                                        |

## 1.2 Cyber Security (sécurité réseau)

Le secteur est de plus en plus confronté à des risques liés à la sécurité sur Internet. Dans le cadre du processus de développement de produits, ABB a officiellement présenté des tests de résistance liés à la sécurité sur Internet afin de garantir stabilité, sécurité et résistance à ses solutions.

Les informations suivantes servent en outre de consigne et décrivent les mécanismes pouvant être utilisés afin d'améliorer la sécurité des installations KNX.

## 1.3 Limitation de l'accès aux différents média

La base de chaque processus de protection assure l'isolement attentif du système contre tout accès non autorisé. Dans le cas d'une installation KNX, seules les personnes autorisées (installateur, gardien, utilisateur) peuvent accéder de manière physique à l'installation KNX. Lors de la planification et de l'installation, les points critiques doivent être protégés de manière optimale pour chaque medium KNX.

De manière générale, les applications et appareils doivent être installés de façon permanente afin d'empêcher tout démontage facile et par la même occasion l'accès de personnes non autorisées à l'installation KNX. Les sous-répartitions avec des appareils KNX doivent être fermées ou situées dans des pièces auxquelles seules les personnes autorisées ont accès.

## 1.4 Câblage à paires torsadées (Twisted Pair)

- ▶ Les extrémités du câble à paires torsadées KNX ne doivent pas être visibles ni sortir du mur que ce soit dans ou en dehors du bâtiment.
- ▶ Dans la mesure où ils sont disponibles, utiliser les dispositifs de protections contre le vol des modules d'applications.
- ▶ Les câbles bus dans la zone extérieure représentent un risque élevé. L'accès physique au câble à paires torsadées KNX doit ici être particulièrement difficile.
- ▶ Les appareils obstrués dans les zones protégées limitées (zone extérieure, parking souterrain, WC, etc.) peuvent être exécutés en tant que protection supplémentaire dans une ligne à part entière. L'activation des tables de filtrage dans le coupleur de ligne (KNX uniquement) permet d'empêcher l'accès par un agresseur à l'installation complète.

### 1.5 Câblage IP au sein du bâtiment

Un réseau WLAN ou LAN séparé doit être utilisé de paire avec du matériel propre (routeur, commutateurs, etc.) pour le système d'automatisation du bâtiment.

Les mécanismes de sécurité habituels doivent impérativement être utilisés pour les réseaux IP, indépendamment de l'installation KNX. Par exemple :

- Filtrage MAC
- Cryptage de réseaux mobiles
- Utilisation de mots de passe forts et protection de ces derniers contre les personnes non autorisées.

| Remarque                                                                                                                                                                                                                                                             |
|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Pendant une saturation IP, TCP ou UDP (accès depuis Internet), l'appareil est inaccessible. Afin d'éviter cette réaction du système, un débit de données maximal doit être configuré au niveau du réseau. Veuillez consulter votre administrateur réseau à ce sujet. |

### 1.6 Connexion à Internet

L'appareil n'est pas prévu pour une utilisation publique sur Internet. Ainsi, aucun port de routeurs ne doit être ouvert en direction d'Internet. Cela rend la communication KNX sur Internet invisible.

Un accès à une installation depuis Internet peut être utilisé de la manière suivante :

- Accès aux installations KNX via des connexions VPN ; cela implique néanmoins l'utilisation d'un routeur avec fonctionnalité du serveur VPN.
- Utilisation de solutions ou visualisations spécifiques au fabricant, par ex. avec un accès via https.

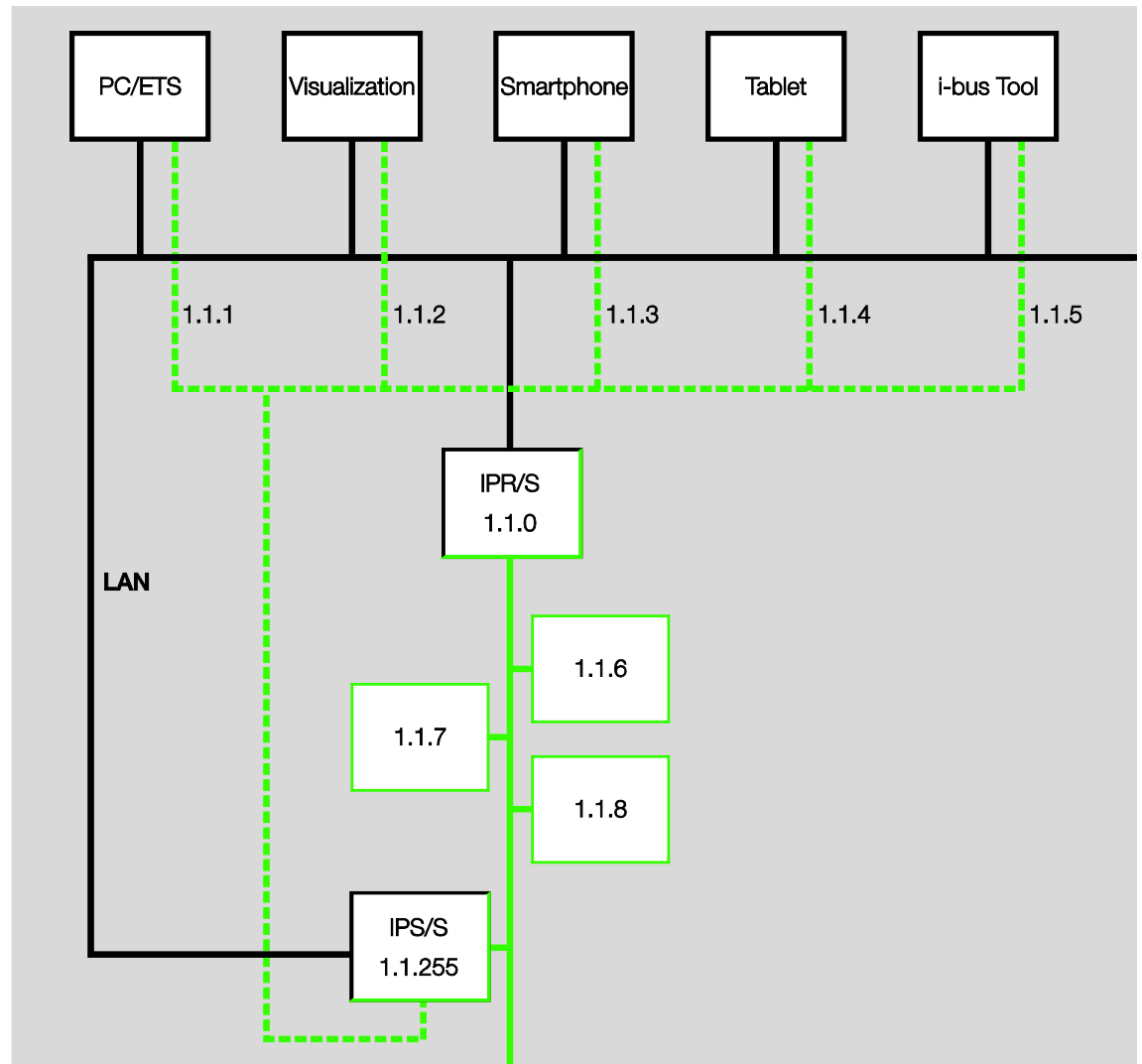
## 1.7

### Vue d'ensemble du produit et de son fonctionnement

L'interface IP IPS/S 3.1.1 ABB i-bus® permet de connecter le bus KNX à un réseau Ethernet. Le réseau permet l'envoi ou la réception de télégrammes KNX vers ou depuis d'autres appareils.

L'interface peut être utilisée comme interface de programmation (ETS) et des clients, p. ex. des programmes de visualisation, peuvent accéder au bus KNX via l'IPS/S 3.1.1.

L'appareil communique à l'aide du protocole KNXnet/IP de l'Association KNX (tunneling).



L'interface dispose de 5 serveurs de tunneling, voir chapitre [Utilisation des serveurs de tunneling intégrés](#), p. 25. Ceux-ci prennent en charge aussi bien le moniteur de bus que le mode moniteur de groupe (comme alternative).

L'appareil peut être alimenté en tension par câble Ethernet (Power over Ethernet - PoE) conformément à la norme IEEE 802.3af classe 1 ou par une tension auxiliaire.

L'utilisation de l'ABB i-bus® Tool avec l'interface IP permet de détecter les interfaces présentes sur le réseau (IP Discovery) et, si nécessaire, de mettre à jour le firmware, voir chapitre [L'i-bus® Tool](#) p. 31.

1.7.1 Vue d'ensemble des versions

Le tableau suivant propose une vue d'ensemble des fonctions offertes par les appareils IPS/S 2.1 et IPS/S 3.1.1 et les programmes d'application *Interface IP/1.0* (ETS 3 et ETS 4), *Interface IP/1.1* (ETS 3) et *Interface IP/2.0* (ETS 4).

| Appareil                              | IPS/S 2.1        | IPS/S 3.1.1      | IPS/S 3.1.1      |
|---------------------------------------|------------------|------------------|------------------|
| Application                           | Interface IP/1.0 | Interface IP/1.1 | Interface IP/2.0 |
| ETS                                   | ETS 3/ETS 4      | ETS 3            | ETS 4/ETS 5      |
|                                       |                  |                  |                  |
| Caractéristiques <i>Interface IP</i>  |                  |                  |                  |
| Nombre de serveurs de tunneling       | 1                | 1                | 5                |
| IP Discovery (i-bus® Tool)            | ■                | ■                | ■                |
| Mise à jour du firmware (i-bus® Tool) | -                | ■                | ■                |
|                                       |                  |                  |                  |
| Tension par câble Ethernet (PoE)      | -                | ■                | ■                |

■ = La caractéristique s'applique  
- = La caractéristique ne s'applique pas

|                                                                                                                                                     |
|-----------------------------------------------------------------------------------------------------------------------------------------------------|
| Remarque                                                                                                                                            |
| L'application <i>Interface IP/2.0</i> n'est prise en charge par ETS 4 qu'à partir de la version 4.1.7 et par ETS 5 qu'à partir de la version 5.0.4. |

|                                                                                     |
|-------------------------------------------------------------------------------------|
| Remarque                                                                            |
| Vous trouverez une description des fonctions dans l'aide en ligne de l'i-bus® Tool. |

# ABB i-bus® KNX

## Description technique de l'appareil

### 2 Description technique de l'appareil



L'interface IP 3.1.1 assure l'interface entre des installations KNX et des réseaux IP. ETS permet de programmer des appareils KNX via le réseau LAN et des clients comme des programmes de visualisation peuvent accéder au bus KNX via l'IPS/S 3.1.1 (5 serveurs de tunneling sont disponibles avec ETS 4 ou version ultérieure).

L'appareil utilise le protocole KNXnet/IP de l'Association KNX (tunneling). L'appareil est alimenté par une tension de 12 à 30 V CC ou par une tension par câble Ethernet (Power over Ethernet - PoE).

#### 2.1 Caractéristiques techniques

|                                     |                                              |                                                                        |
|-------------------------------------|----------------------------------------------|------------------------------------------------------------------------|
| Alimentation                        | Tension auxiliaire $U_s$                     | 12...30 V CC (+10 % / -15 %) ou PoE (IEEE 802.3af classe 1)            |
|                                     | Puissance dissipée                           | Maximum 1,8 W                                                          |
|                                     | Courant consommé tension auxiliaire          | Maximum 120 mA à 12 V                                                  |
|                                     | Tension nominale $U_N$                       | 12 V CC                                                                |
|                                     | Courant consommé KNX                         | < 10 mA                                                                |
| Raccordement                        | KNX                                          | Borne de raccordement du bus                                           |
|                                     | Borne enfichable pour tension d'alimentation | Borne enfichable                                                       |
|                                     | LAN                                          | Prise RJ45 pour réseaux 10/100BaseT, IEEE 802.3, détection automatique |
| Éléments de commande et d'affichage | LED rouge et bouton                          | Pour affectation de l'adresse physique                                 |
|                                     | LED verte « On »                             | Indication prêt à fonctionner                                          |
|                                     | LED jaune « LAN/Link »                       | Indication connexion réseau                                            |
|                                     | LED jaune « Telegram »                       | Indication transmission de télégrammes KNX                             |
| Indice de protection                | IP 20                                        | Selon DIN EN 60 529                                                    |
| Classe de protection                | II                                           | Selon DIN EN 61 140                                                    |
| Classe d'isolation                  | Classe de surtension                         | III selon DIN EN 60 664-1                                              |
|                                     | Degré de contamination                       | 2 selon DIN EN 60 664-1                                                |
| Basse tension de sécurité KNX       | TBTS 30 V CC                                 |                                                                        |
| Plage de température                | Fonctionnement                               | -5 °C...+45 °C                                                         |
|                                     | Stockage                                     | -25 °C...+55 °C                                                        |
|                                     | Transport                                    | -25 °C...+70 °C                                                        |
| Conditions ambiantes                | Humidité relative maximale                   | 95 %, aucune condensation admissible                                   |
|                                     | Pression atmosphérique                       | Atmosphère jusqu'à 2 000 m                                             |

# ABB i-bus® KNX

## Description technique de l'appareil

|                         |                                              |                                 |
|-------------------------|----------------------------------------------|---------------------------------|
| <b>Design</b>           | Encliquetable sur rail DIN (MRD)             | Appareil modulaire, design ProM |
|                         | Dimensions                                   | 90 x 36 x 64 mm (H x L x P)     |
|                         | Largeur de montage                           | 2 modules de 18 mm              |
|                         | Profondeur de montage                        | 68 mm                           |
| <b>Montage</b>          | Sur rail 35 mm                               | Selon DIN EN 60 715             |
| <b>Sens de montage</b>  | Indifférent                                  |                                 |
| <b>Poids</b>            | 0,1 kg                                       |                                 |
| <b>Coffret, couleur</b> | Plastique, sans halogène, gris               |                                 |
| <b>Homologation</b>     | KNX selon EN 50 090-1, -2                    |                                 |
| <b>Sigle CE</b>         | Conforme aux directives CEM et basse tension |                                 |

| Type d'appareil | Application       | Nombre maximum d'objets de communication | Nombre maximum d'adresses de groupe | Nombre maximum d'affectations |
|-----------------|-------------------|------------------------------------------|-------------------------------------|-------------------------------|
| IPS/S 3.1.1     | Interface IP/...* | 0                                        | 0                                   | 0                             |

\* ... = numéro de la version actuelle de l'application. **Pour plus de détails, veuillez consulter les informations relatives à l'application sur notre site Internet.**

### Remarque

ETS et la dernière version de l'application de l'appareil sont nécessaires pour la programmation de l'appareil.

La dernière version de l'application ainsi que les informations correspondantes peuvent être téléchargées en ligne sur [www.abb.com/knx](http://www.abb.com/knx). Après l'importation dans ETS, vous trouverez l'application dans la fenêtre *Catalogues* sous *Fabricants/ABB/Appareils système/Interfaces*.

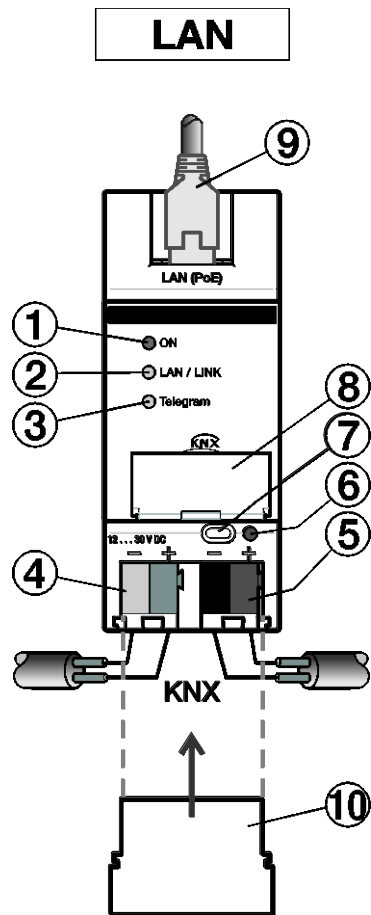
L'appareil ne prend pas en charge la fonction de fermeture d'un appareil KNX dans ETS. L'interdiction d'accès à tous les appareils d'un projet au moyen d'une *clé BCU* n'a aucun effet sur cet appareil. Celui-ci peut encore être lu et programmé.

# ABB i-bus® KNX

## Description technique de l'appareil

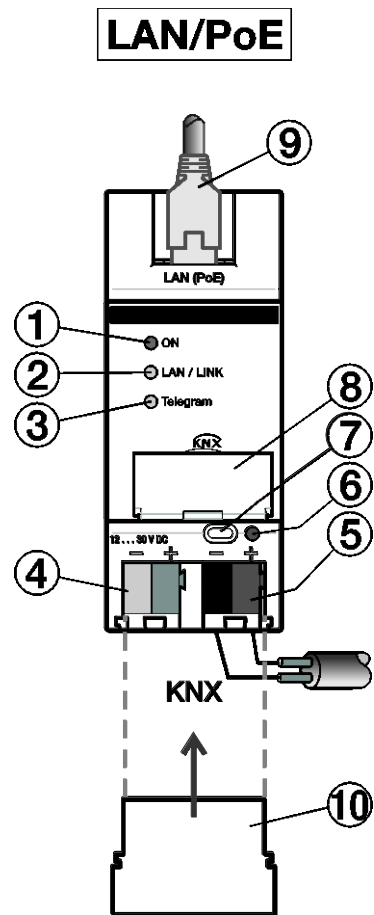
### 2.2

### Schéma de raccordement



#### IPS/S 3.1.1

- 1 LED ON
- 2 LED LAN/LINK
- 3 LED Telegram
- 4 Raccord d'alimentation en tension
- 5 Connexion KNX

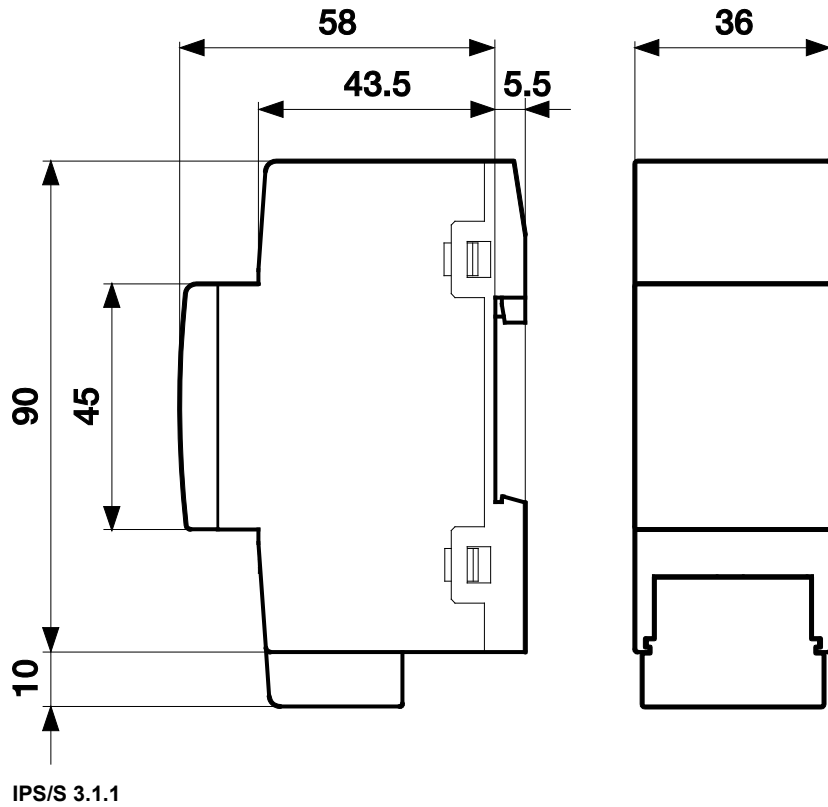


- 6 LED Programmation
- 7 Bouton Programmation
- 8 Porte-étiquette
- 9 Connexion LAN ou LAN/PoE
- 10 Couverture

# ABB i-bus® KNX

## Description technique de l'appareil

### 2.3 Plan coté



2CDC072020F0015

# ABB i-bus® KNX

## Description technique de l'appareil

### 2.4 Montage et installation

L'appareil est encliquetable sur rail DIN de 35 mm selon DIN EN 60 715, destiné à être monté rapidement dans un coffret de distribution.

L'appareil peut être monté dans n'importe quelle position désirée.

Le raccordement au bus est réalisé via la borne de raccordement du bus fournie. Les bornes sont identifiées sur le boîtier.

L'appareil est prêt à fonctionner dès le raccordement de la tension du bus et de la tension auxiliaire.

L'accessibilité de l'appareil pour le fonctionnement, la supervision, l'entretien et la réparation doit être assurée conformément à la norme DIN VDE 0100-520.

#### Conditions de mise en service

La mise en service de l'appareil nécessite un PC avec le programme ETS (ETS 3 V3.0f ou ultérieure) ainsi qu'une tension d'alimentation de 12 à 30 V CC. L'appareil peut également être alimenté via tension par câble Ethernet (Power over Ethernet - PoE).

L'appareil est prêt à fonctionner dès l'application de la tension du bus et de la tension auxiliaire.

Le montage et la mise en service ne doivent être effectués que par des électriciens qualifiés. Lors de la planification et de la construction d'installations électriques, d'installations relatives à la sécurité, intrusion et protection incendie, les normes, directives, réglementations et dispositions pertinentes en vigueur dans le pays concerné doivent être respectées.

- Protéger l'appareil contre la poussière, l'humidité et les risques de dommages lors du transport, du stockage et de l'utilisation !
- N'utiliser l'appareil que dans le cadre des données techniques spécifiées !
- N'utiliser l'appareil que dans un boîtier fermé (coffret) !
- L'appareil doit être mis hors tension avant les travaux de montage.



#### Danger

En cas de modification ou d'extension de l'installation, il est indispensable de mettre hors tension tous les équipements de l'installation afin d'éviter tout risque de contact avec un élément ou un conducteur sous tension.

#### État à la livraison

L'appareil est livré avec l'adresse physique 15.15.255 et 5 autres adresses physiques 15.15.100 pour les connexions de tunneling.

L'adresse IP est paramétrée en mode attribution automatique (DHCP/AutoIP).

#### Affectation de l'adresse physique

L'affectation et la programmation des adresses physiques et des paramètres sont effectuées dans ETS.

L'appareil dispose d'un bouton *Programmation* pour l'affectation de l'adresse physique. Après actionnement du bouton, la LED rouge *Programmation* s'allume. Elle s'éteint dès qu'ETS a affecté l'adresse physique ou que le bouton *Programmation* est actionné à nouveau.

# ABB i-bus® KNX

## Description technique de l'appareil

### **Comportement lors du téléchargement**

L'appareil peut être programmé de différentes façons : via l'un des serveurs de tunneling intégrés (« téléchargement local ») ou via une autre interface de programmation (USB ou IP).

Pour que l'appareil puisse être programmé, celui-ci doit être connecté au KNX TP (Twisted Pair).

Environ 10 secondes après la fin du téléchargement, l'appareil redémarre et ferme toutes les connexions de tunneling ouvertes. Si l'adresse IP de l'appareil a été changée lors du téléchargement, les connexions de tunneling doivent être configurées manuellement dans les clients de tunneling. Les clients de tunneling établissent la connexion avec le serveur via l'adresse IP.

Les données paramétrées avec ETS sont transférées de 30 à 60 secondes après le téléchargement.

### **Nettoyage**

L'appareil doit être mis hors tension avant le nettoyage. Les appareils encrassés peuvent être nettoyés avec un chiffon sec ou un chiffon humidifié dans de l'eau savonneuse. L'usage d'agents caustiques ou de solvants est absolument proscrit.

### **Maintenance**

L'appareil ne nécessite aucun entretien. En cas de dommages provoqués par exemple pendant le transport ou le stockage, aucune réparation ne doit être effectuée.

# ABB i-bus® KNX

## Description technique de l'appareil

### 2.5 Description des entrées et des sorties

#### Entrée de tension d'alimentation 12 à 30 V CC

Seule une tension continue de 12 à 30 V doit être raccordée à l'entrée de tension d'alimentation. Nous recommandons d'utiliser les modules d'alimentation NT/S de notre gamme de produits

#### Attention

La tension d'alimentation doit être entre 12 et 30 V CC, ou l'appareil doit être alimenté via tension par câble Ethernet (Power over Ethernet - PoE) conformément à la norme IEEE 802.3af classe 1. Le raccordement d'une tension de 230 V peut détruire l'appareil !

#### Raccordement KNX

L'appareil est raccordé au bus KNX à l'aide de la borne de raccordement de bus fournie.

#### Remarque

ETS 3 version 3.0f ou ultérieure est nécessaire pour la programmation de l'appareil.

#### Connexion LAN

La connexion au réseau s'effectue via une interface Ethernet RJ45 pour réseaux LAN. L'interface réseau peut être utilisée à une vitesse de transmission de 10/100 Mbit/s. La LED LAN/LINK située à l'avant du boîtier indique l'activité réseau.

# ABB i-bus® KNX

## Description technique de l'appareil

### 2.6 Éléments de commande

L'interface IP ne dispose d'aucun élément de commande.

### 2.7 Éléments d'affichage

La face avant de l'IPS/S est muni de trois LED d'affichage :



ON



LAN/LINK



Telegram

#### ON

- La LED s'allume pendant quelques secondes après l'enclenchement de la tension d'alimentation.
- La LED s'allume en continu après l'enclenchement de la tension d'alimentation.  
Après env. 40 secondes, la LED commence à clignoter jusqu'à la fin du processus de démarrage, après quoi elle s'allume à nouveau en continu. Ce processus peut prendre entre 5 et 60 secondes.

#### LAN/LINK

- La LED s'allume lorsque la tension auxiliaire est présente et que l'interface est connectée à un réseau Ethernet.
- La LED clignote lorsque l'appareil détecte une activité sur le réseau, p. ex. lors d'échanges de données.

#### Telegram

- La LED clignote lorsque l'interface est connectée à un réseau TP et que le processus de démarrage (voir LED « On ») est terminé.
- La LED clignote lorsque l'appareil détecte une activité sur la sous-ligne KNX TP1 (Twisted Pair 1), p. ex. lors d'échanges de données.

### 3 Mise en service

Le paramétrage de l'IPS/S s'effectue à l'aide de l'application et du logiciel Engineering Tool Software ETS.

L'application se trouve sous *ABB/Appareils système/Interfaces*.

Un PC ou un ordinateur portable avec le logiciel ETS ainsi qu'une connexion KNX sont nécessaires pour le paramétrage de l'appareil.

#### 3.1 Aperçu

Le paramétrage de l'interface IP s'effectue à l'aide du logiciel Engineering Tool Software ETS 3 version 3.0f ou ultérieure.

##### Important

Les applications pour ETS 3 à partir de la version 3.0f et ETS 4 version 4.1.7 ou ultérieure divergent en raison des différents éventails de fonctions offerts (voir [Vue d'ensemble des versions](#), p. 8).  
Aucune conversion n'est possible.

##### Remarque

L'application *Interface IP/2.0* n'est prise en charge par ETS 4 qu'à partir de la version 4.1.7 et par ETS 5 qu'à partir de la version 5.0.4.

##### Remarque

Vous trouverez une description des fonctions dans l'aide en ligne de l'i-bus® Tool.

### 3.2 Paramètres

Le chapitre suivant décrit les paramètres de l'interface IP accessibles depuis les fenêtres de paramétrage.

Les fenêtres de paramétrage sont dynamiques, de sorte que, selon le paramétrage et la fonction des sorties, d'autres paramètres ou d'autres fenêtres de paramétrage sont déverrouillés.

Les valeurs par défaut des paramètres sont soulignées, p. ex. :

Options :      Oui  
                  Non

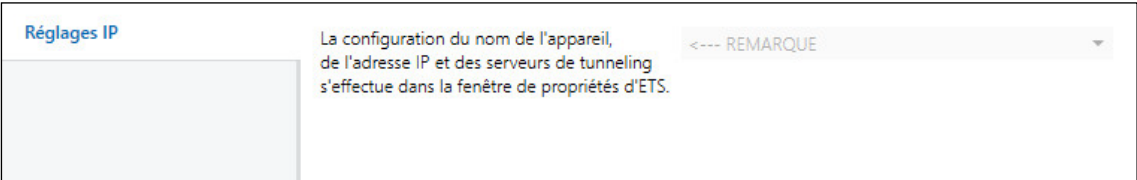
| Remarque                                                                                                                                                                                                     |
|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Les captures d'écran ont été réalisées dans ETS 5 et sont utilisées pour toutes les applications (ETS 3, ETS 4 et ETS 5). L'affichage peut varier légèrement. Les paramètres et les options sont identiques. |

# ABB i-bus® KNX

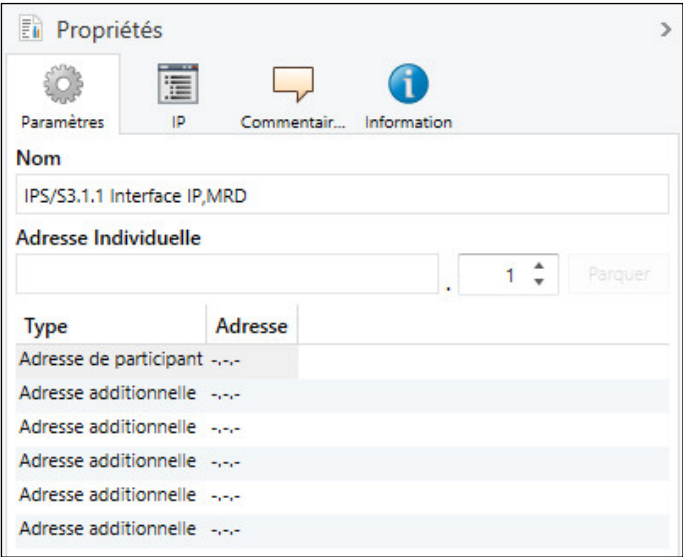
## Mise en service

### 3.2.1 Application pour ETS 4 et ETS 5 (Interface IP/2.0)

#### 3.2.1.1 Fenêtre de paramétrage *Réglages IP*



La configuration des paramètres IP (nom de l'appareil, affectation de l'adresse IP par DHCP ou de manière fixe) s'effectue dans la fenêtre de propriétés d'ETS correspondante.



La fenêtre de propriétés *Paramètres* permet de définir le nom de l'appareil. Le champ *Nom* permet de modifier le nom chargé dans l'appareil.

Le nom de l'appareil sert à identifier celui-ci sur le réseau LAN. Lors d'une demande de recherche, p. ex. par ETS, chaque appareil KNXnet/IP signale son nom et peut être désigné par celui-ci. L'usage de noms comme IPS/S, EG, UV7 permet par exemple de communiquer le lieu d'installation de l'appareil.

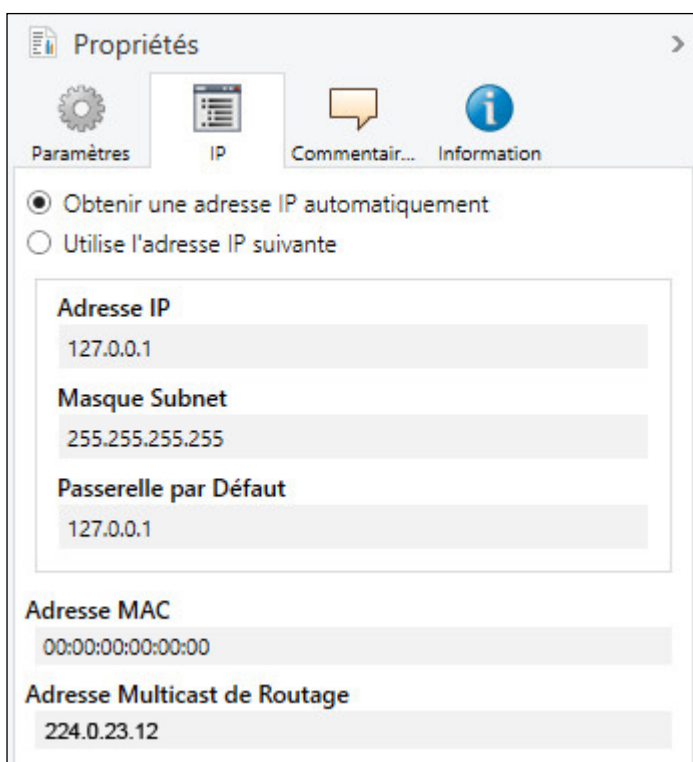
| Remarque                                                                                                                                                                                         |
|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| À la livraison, le nom d'appareil par défaut est « IP Interface ». Le nom d'appareil défini dans la fenêtre de propriétés d'ETS n'est chargé dans l'appareil qu'après le premier téléchargement. |

| Attention                                                                                              |
|--------------------------------------------------------------------------------------------------------|
| Seuls les 30 premiers caractères du nom d'appareil sont chargés. Les caractères restants sont ignorés. |

# ABB i-bus® KNX

## Mise en service

La fenêtre de propriétés *IP* permet de définir l'adresse IP de l'appareil.



**Propriétés**

Paramètres IP Commentair... Information

☒ Obtenir une adresse IP automatiquement  
☐ Utilise l'adresse IP suivante

**Adresse IP**  
127.0.0.1

**Masque Subnet**  
255.255.255.255

**Passerelle par Défaut**  
127.0.0.1

**Adresse MAC**  
00:00:00:00:00:00

**Adresse Multicast de Routage**  
224.0.23.12

Les options suivantes sont disponibles pour la configuration de l'adresse IP :

Options : Obtenir une adresse IP automatiquement  
Utilise l'adresse IP suivante

- *Obtenir une adresse IP automatiquement* : Selon le réglage par défaut, l'interface IP attend l'affectation d'une adresse IP par un serveur DHCP (dynamic host configuration protocol). Ce serveur attribue sur demande une adresse IP libre à l'appareil. Si aucun serveur DHCP n'est disponible sur le réseau ou que le serveur ne répond pas, l'appareil initie une procédure d'IP automatique. L'appareil s'auto-attribue une adresse dans la plage réservée aux adresses IP automatiques (169.254.xxx.yyy).

Pour plus de détails sur le DHCP, voir le chapitre [Affectation de l'adresse IP](#), p. 29.

- *Utilise l'adresse IP suivante* : Si le réseau ne dispose d'aucun serveur DHCP ou si l'adresse IP doit toujours être la même, celle-ci peut également être affectée de manière fixe.

### Adresse IP

Options : 192.168.0.3

### Masque de sous-réseau

Options : 255.255.255.0

### Passerelle par défaut

Options : 192.168.0.1

### Adresse MAC

Options : 00.00.00:00.00.00

# ABB i-bus® KNX

## Mise en service

| Remarque                                                                                                                                                              |
|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| L'adresse MAC est lue depuis l'appareil après un téléchargement.<br>L'adresse MAC est également transmise à l'appareil et peut aussi être détectée par l'i-bus® Tool. |

L'i-bus® Tool peut être téléchargé gratuitement depuis notre site ([www.abb.com/knx](http://www.abb.com/knx)).

L'utilisation de l'i-bus® Tool ne requiert ni ETS ni l'installation de Falcon.

Configuration système requise : Système Windows version Windows 7 (Service Pack 3) ou ultérieure et .NET Framework 4.0.

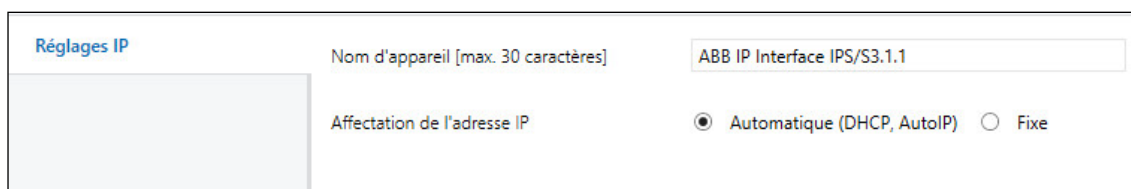
La librairie intégrée Falcon 5.x ne prend en charge que les interfaces USB et IP (RS232 non prise en charge).

| Remarque                                                                            |
|-------------------------------------------------------------------------------------|
| Vous trouverez une description des fonctions dans l'aide en ligne de l'i-bus® Tool. |

### 3.2.2 Application pour ETS 3 (Interface IP/1.1)

#### 3.2.2.1 Fenêtre de paramétrage *Réglages IP*

La fenêtre de paramétrage *Réglages IP* permet de définir tous les réglages IP de l'interface IP.



#### **Nom d'appareil [max. 30 caractères]**

Options :      ABB IP Interface IPS/S3.1.1

Le nom de l'appareil sert à identifier celui-ci sur le réseau LAN. Lors d'une demande de recherche, p. ex. par ETS, chaque appareil KNXnet/IP signale son nom et peut être désigné par celui-ci. L'usage de noms comme IPS/S, EG, UV7 permet par exemple de communiquer le lieu d'installation de l'appareil.

Le texte ne doit pas dépasser 30 caractères. Ce nom est également affiché lorsque l'appareil est détecté comme interface de communication dans ETS.

#### **Remarque**

À la livraison, le nom d'appareil par défaut est « IP interface ». Le nom d'appareil défini dans l'application n'est appliqué qu'après le premier téléchargement.

Pour plus d'informations, voir [Utilisation des serveurs de tunneling intégrés](#), p. 25.

#### **Affectation de l'adresse IP**

Options :      Automatique (DHCP, AutoIP)  
Fixe

- *Automatique (DHCP, AutoIP)* : Avec le réglage par défaut, l'interface IP attend l'affectation d'une adresse IP par un serveur DHCP (dynamic host configuration protocol). Ce serveur attribue sur demande une adresse IP libre à l'appareil. Si aucun serveur DHCP n'est disponible sur le réseau ou que le serveur ne répond pas, l'appareil initie une procédure d'IP automatique. L'appareil s'auto-attribue une adresse dans la plage réservée aux adresses IP automatiques (169.254.xxx.yyy).
- *Fixe* : Si le réseau ne dispose d'aucun serveur DHCP ou si l'adresse IP doit toujours être la même, celle-ci peut également être affectée de manière fixe.

La fenêtre de paramétrage s'agrandit pour afficher les paramètres de réglage de l'adresse IP.

# ABB i-bus® KNX

## Mise en service

Ces paramètres ne sont visibles que lorsque l'option *Fixe* est sélectionnée pour le paramètre *Affectation de l'adresse IP*.

|                    |                                     |                                                                                        |
|--------------------|-------------------------------------|----------------------------------------------------------------------------------------|
| <b>Réglages IP</b> | Nom d'appareil [max. 30 caractères] | ABB IP Interface IPS/S3.1.1                                                            |
|                    | Affectation de l'adresse IP         | <input type="radio"/> Automatique (DHCP, AutoIP) <input checked="" type="radio"/> Fixe |
|                    | Adresse IP                          |                                                                                        |
|                    | Octet 1                             | 192                                                                                    |
|                    | Octet 2                             | 168                                                                                    |
|                    | Octet 3                             | 0                                                                                      |
|                    | Octet 4                             | 222                                                                                    |
|                    | Masque de sous-réseau IP            |                                                                                        |
|                    | Octet 1                             | 255                                                                                    |
|                    | Octet 2                             | 255                                                                                    |
|                    | Octet 3                             | 255                                                                                    |
|                    | Octet 4                             | 0                                                                                      |
|                    | Passerelle par défaut               |                                                                                        |
|                    | Octet 1                             | 0                                                                                      |
|                    | Octet 2                             | 0                                                                                      |
|                    | Octet 3                             | 0                                                                                      |
|                    | Octet 4                             | 0                                                                                      |

### Adresse IP

#### Octet x

Options : 0...255

L'adresse IP est l'adresse unique de l'interface IP sur le LAN.

L'adresse doit être saisie par octet, p. ex. comme suit pour l'adresse 192.168.0.222 :

|           |     |
|-----------|-----|
| Octet 1 : | 192 |
| Octet 2 : | 168 |
| Octet 3 : | 0   |
| Octet 4 : | 222 |

# ABB i-bus® KNX

## Mise en service

### Masque de sous-réseau

#### Octet x

Options : 0...255

Le *Masque de sous-réseau* détermine la classe du réseau. Le masque de sous-réseau doit être défini en fonction du nombre et de la structure des sous-réseaux. Dans le cas le plus simple, c.-à-d. sur un petit réseau, le masque de sous-réseau 255.255.255.0 doit être défini comme suit :

|           |     |
|-----------|-----|
| Octet 1 : | 255 |
| Octet 2 : | 255 |
| Octet 3 : | 255 |
| Octet 4 : | 0   |

### Passerelle par défaut

#### Octet x

Options : 0...255

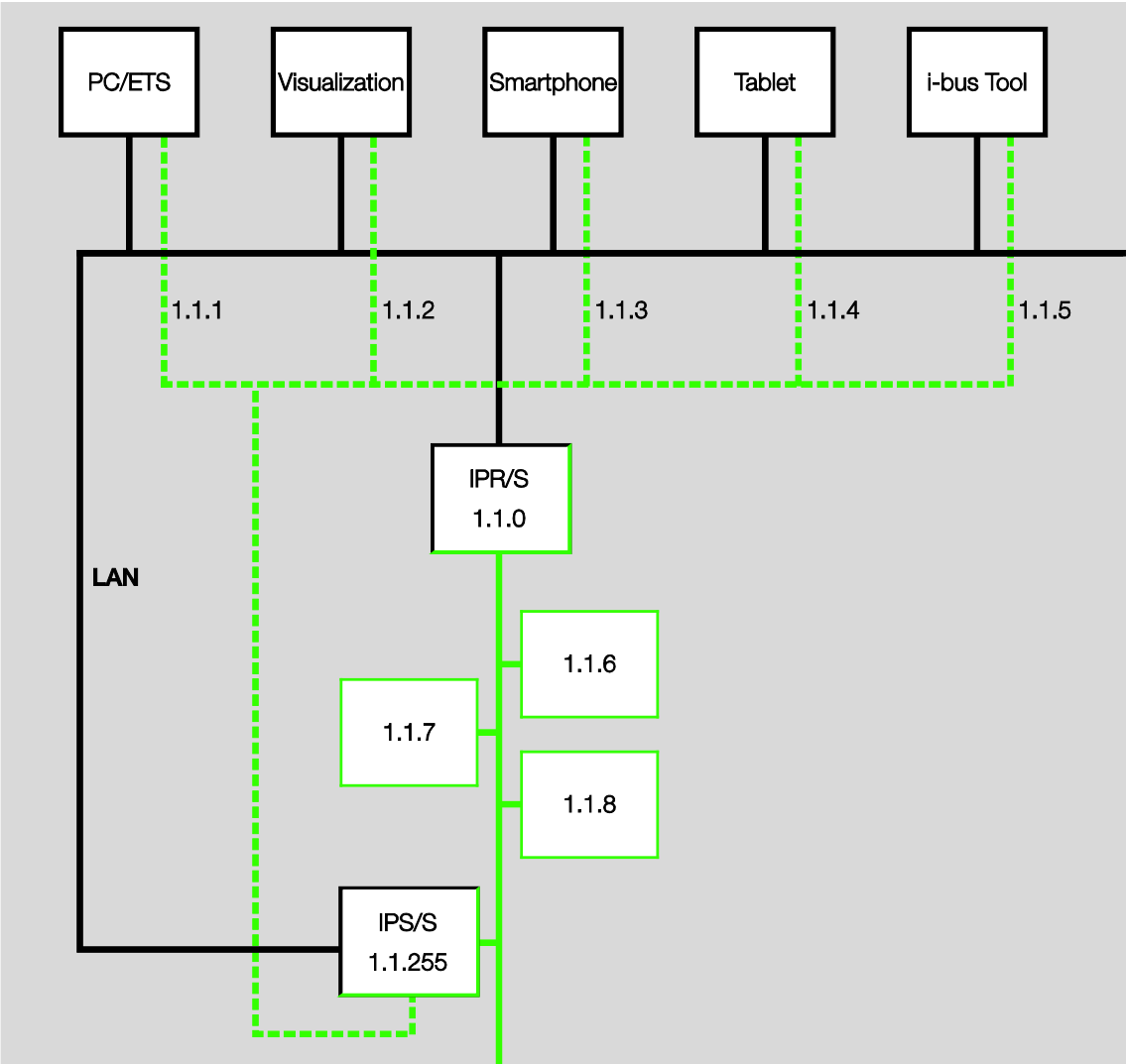
Le paramètre *Passerelle par défaut* indique le point de connexion par lequel les télégrammes IP doivent être transmis, p. ex. l'adresse IP d'un routeur entre des réseaux. Ces passerelles n'existent que sur les plus grands réseaux. Pour les petits réseaux, le paramètre 0.0.0.0 peut être conservé.

3.3 Objets de communication

L'interface IP IPS/S n'a aucun objet de communication KNX.

3.4 Utilisation des serveurs de tunneling intégrés

L'interface IP offre 5 adresses physiques supplémentaires pouvant être utilisées pour une connexion de tunneling. Ces soi-disant serveurs de tunneling peuvent être utilisés avec ETS comme interfaces de programmation ou encore avec un autre client, p. ex. un programme de visualisation.



Lors du tunneling, un client se connecte à une ligne de bus. Le processus de tunneling utilise le protocole UDP, mais conserve une couche de liaison de données afin que les télégrammes soient répétés en cas d'erreur.

| Remarque                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             |
|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| <p>L'adresse physique pour la connexion de tunneling doit correspondre à la topologie. C'est pourquoi les adresses doivent être choisies dans la plage d'adresses de la ligne. À la livraison de l'appareil, tous les serveurs de tunneling ont l'adresse 15.15.100.</p> <p>Le paramétrage des connexions de tunneling dépend de la version d'ETS utilisée.</p> <ul style="list-style-type: none"><li>• Dans ETS 4 et ETS 5, les 5 premières adresses libres de la ligne sont affectées une fois l'interface ajoutée sur une ligne.</li><li>• Dans ETS 3, une seule connexion de tunneling est disponible.</li></ul> |

# ABB i-bus® KNX

## Mise en service

### 3.4.1 Paramètres dans ETS 4/ETS 5

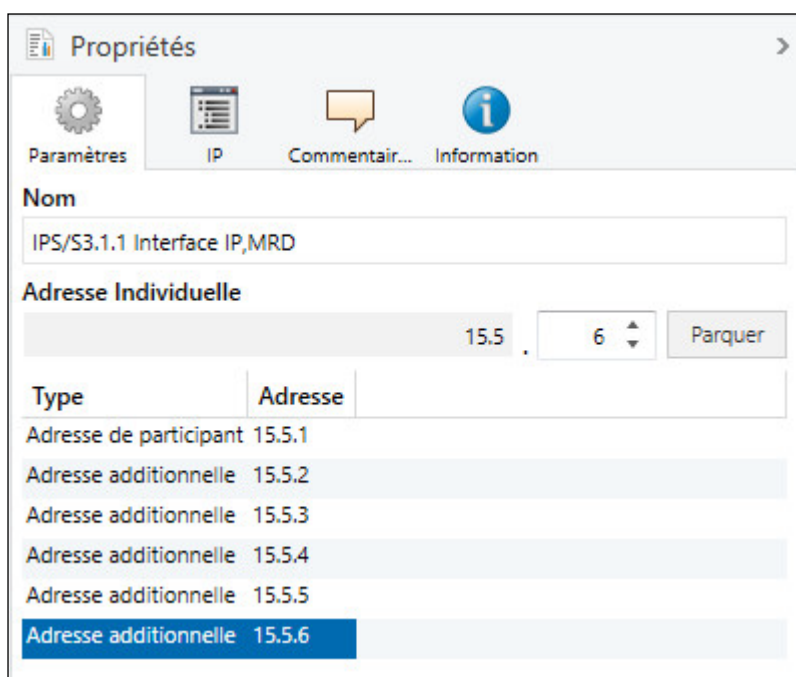
Dans ETS 4 ou toute version ultérieure, une fenêtre de propriétés supplémentaire est disponible pour la configuration des autres adresses physiques (à partir de l'application *Interface IP/2.0*).

Après l'ajout de l'interface sur la ligne, ETS réserve automatiquement les 5 premières adresses libres de cette ligne pour les serveurs de tunneling de l'interface (ETS 4 et ETS 5). Il s'agit là d'une fonction de base d'ETS qui ne peut pas être modifiée.

Bien que les 5 adresses par défaut à la livraison soient 15.15.100, les adresses sont remplacées par les premières adresses libres dans le projet après le premier téléchargement.

Si ce réglage n'est pas désiré, il est possible de le modifier manuellement dans la fenêtre de propriétés.

#### Modification de l'adresse



| Type                   | Adresse |
|------------------------|---------|
| Adresse de participant | 15.5.1  |
| Adresse additionnelle  | 15.5.2  |
| Adresse additionnelle  | 15.5.3  |
| Adresse additionnelle  | 15.5.4  |
| Adresse additionnelle  | 15.5.5  |
| Adresse additionnelle  | 15.5.6  |

Pour modifier l'adresse, surligner l'adresse actuelle de l'appareil ou l'adresse supplémentaire et cliquer sur la flèche vers le haut ou la flèche vers le bas pour sélectionner le chiffre souhaité. L'adresse modifiée est enregistrée lorsque vous surlignez une autre adresse.

Les adresses modifiées ne sont appliquées qu'après un téléchargement.

#### Parquer

Lorsque l'option *Parquer* est activée pour un tunnel, ce tunnel n'est pas utilisé.

Si l'option *Parquer* est sélectionnée pour tous les serveurs de tunneling, ceux-ci reçoivent tous l'adresse 15.15.255. Un seul serveur de tunneling est alors disponible.

### 3.4.2 Paramètres dans ETS 3

Dans ETS 3, l'affectation d'une adresse physique supplémentaire s'effectue via l'élément de menu *Extras*  
→ *Options* → *Communication* → *Paramètres*.



# ABB i-bus® KNX

## Programmation et mise en œuvre

## 4 Programmation et mise en œuvre

### 4.1 L'interface IP sur le réseau

L'interface IP est conçue pour l'utilisation sur les réseaux 10/100BaseT conformes à la norme IEEE 802.3. L'appareil dispose d'une fonction de détection automatique et définit automatiquement la vitesse de transmission (10 ou 100 Mbit).

#### 4.1.1 Affectation de l'adresse IP

##### DHCP/AutoIP

L'adresse IP peut être attribuée par un serveur DHCP. Pour cela, l'affectation automatique de l'adresse IP doit être configurée dans ETS, voir [Fenêtre de paramétrage Réglages IP](#), p. 19 (pour l'application *Interface IP/2.0*) ou [Fenêtre de paramétrage Réglages IP](#), p. 22 (pour l'application *Interface IP/1.1*). Si aucun serveur DHCP n'est trouvé alors que cette option est sélectionnée, l'appareil lance une procédure AutoIP et s'auto-attribue une adresse dans la plage 169.254.xxx.yyy.

L'appareil conserve l'adresse IP qu'il reçoit au démarrage (par DHCP ou AutoIP) jusqu'au prochain redémarrage (mise hors tension/sous tension ou reprogrammation) ou jusqu'à ce qu'un serveur DHCP soit disponible.

##### Si aucun serveur DHCP n'est disponible au démarrage :

Si aucun serveur DHCP n'est disponible au démarrage de l'interface IP, l'appareil s'auto-attribue une adresse AutoIP. L'interface cherche ensuite un serveur DHCP de manière cyclique (3 télégrammes à intervalles de 3 secondes suivis d'une pause de 20 secondes). Dès qu'un serveur est à nouveau disponible, l'adresse affectée par le serveur DHCP est utilisée.

##### Le serveur DHCP cesse de fonctionner (l'appareil a déjà reçu une adresse IP du DHCP) :

Les demandes de prolongation des droits d'utilisation de cette adresse IP demeurent sans réponse jusqu'à la fin de la durée du bail (la période de validité de l'adresse IP est définie par le serveur DHCP lors de l'affectation). L'interface continue d'utiliser la même adresse IP.

À la fin de la durée du bail ou après un téléchargement, les appareils s'auto-attribuent une adresse AutoIP.

##### Adresse IP fixe

Si l'adresse IP de l'IPS/S doit être affectée de manière fixe, il est possible de définir une adresse IP fixe (ainsi qu'un masque de sous-réseau et une passerelle par défaut) dans ETS. Voir [Fenêtre de paramétrage Réglages IP](#), p. 19 (pour l'application *Interface IP/2.0*) ou [Fenêtre de paramétrage Réglages IP](#), p. 22 (pour l'application *Interface IP/1.1*).

# ABB i-bus® KNX

## Programmation et mise en œuvre

### 4.1.2

#### Télégrammes KNX sur le réseau

| Remarque                                                                                                                                                                                                                                                                                                                                                    |
|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Pendant une saturation IP, TCP ou UDP (accès depuis Internet), l'interface IP est inaccessible. Tous les services deviennent à nouveau disponibles dès la fin de la saturation. Afin d'éviter cette réaction du système, un débit de données maximal doit être configuré au niveau du réseau.<br>Veuillez consulter votre administrateur réseau à ce sujet. |

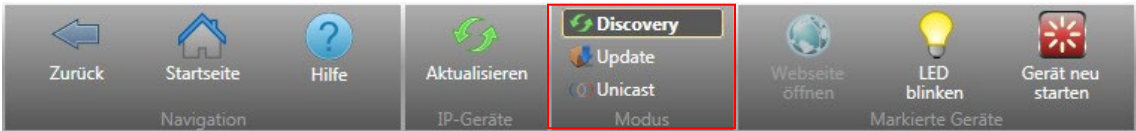
# ABB i-bus® KNX

## Programmation et mise en œuvre

### 4.2 L'i-bus® Tool

Les boutons *Connecter*  et *Appareils IP*  permettent d'accéder aux paramètres IP de l'interface.

**Barre multifonction : Commutation entre les modes Discovery, Mise à jour du firmware et Unicast**



Cliquez sur le bouton correspondant pour sélectionner le mode *Discovery*, *Mettre à jour* ou *Unicast*.  
La fonction « Unicast » n'est pas disponible sur l'interface.

#### Discovery

Sélectionner le mode *Discovery* dans la barre multifonction.  
Cette fonction sert à détecter et afficher les appareils IP ABB présents sur le réseau.

| Remarque                                                                            |
|-------------------------------------------------------------------------------------|
| Vous trouverez une description des fonctions dans l'aide en ligne de l'i-bus® Tool. |

#### Mise à jour de firmware

Sélectionnez le mode *Mettre à jour* dans la barre multifonction.  
Cette fonction permet de mettre à jour le firmware si cela s'avère nécessaire.

| Important                                                                                                                                                                                                                                                                                                                   |
|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Le firmware doit d'abord être téléchargé depuis Internet ( <a href="http://www.abb.com/knx">www.abb.com/knx</a> ). Pour ce faire, l'i-bus® Tool se connecte à un serveur <b>si une connexion Internet est disponible</b> .<br>La mise à jour des appareils de l'installation ne requiert ensuite aucune connexion Internet. |

| Important                                                                                                                                                                                                              |
|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Pendant le processus de mise à jour, le bus KNX (TP) doit également être connecté au réseau IP (LAN) afin que les paramètres KNX puissent être restaurés correctement, sans quoi le processus de mise à jour échouera. |

| Remarque                                                                            |
|-------------------------------------------------------------------------------------|
| Vous trouverez une description des fonctions dans l'aide en ligne de l'i-bus® Tool. |

| Remarque                                                                                            |
|-----------------------------------------------------------------------------------------------------|
| Pour le processus de mise à jour, l'i-bus® Tool doit être exécuté avec les droits d'administration. |



A                   Annexe

A.1                   Pour passer commande

| Type d'appareil | Nom du produit    | Référence commerciale | bbn 40 16779 EAN | Poids<br>1 pce.<br>[kg] | Unité d'emb.<br>[pce.] |
|-----------------|-------------------|-----------------------|------------------|-------------------------|------------------------|
| IPS/S 3.1.1     | Interface IP, MRD | 2CDG110177R0011       | 906 51 7         | 0,1                     | 1                      |



# ABB i-bus® KNX

## Third party software components, notices and OSS license texts

### Third party software components, notices and OSS license texts

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## Third party software components, notices and OSS license texts

### Software components structured by applicable license:

This document contains Open Source Software (“OSS”) subject to OSS license terms as follows:

The software contains **open source software components** as follows:

#### **under General Public Licence (GPL):**

- buildroot (v2012-05)
- memstat (v0.8)

#### **under General Public License (GPL) Version 2:**

- abbpower (v1.0)
- at91ft12 (v1.0)
- at91gpbr (v1.0)
- buildroot (v2012-05)
- busybox (v1.20.1)
- gdbserver (v7.2.50.20100908-cvs)
- glibc (v2.11.1)
- kmod (v8)
- libgcc (v4.5.1)
- Linux (v3.2.26)
- mtd-utils (v1.4.9)
- U-Boot (v2010.09)
- udev (v058)
- util Linux (v2.20.1)

#### **under General Public License (GPL) Version 3:**

- binutils (v2.21)
- gdbserver (v7.2.50.20100908-cvs)
- gzip (v1.5)

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## Third party software components, notices and OSS license texts

- libgcc (v4.5.1)
- tar (v1.17)
- util Linux (v2.20.1)

### **under Library General Public License (LGPL) Version 2:**

- binutils (v2.21)
- gdbserver (v7.2.50.20100908-cvs)
- glib (libglib2) (v2.30.2)
- util Linux (v2.20.1)

### **under Lesser General Public License (LGPL) Version 2.1:**

- glibc (v2.11.1)
- libgcc (v4.5.1)
- libkmod (v8)
- uclibc (v0.9.31.1)
- XML-RPC++ (v0.7)

### **under Lesser General Public License (LGPL) Version 3:**

- binutils (v2.21)
- gdbserver (v7.2.50.20100908-cvs)
- gmp (v5.0.4)
- libgcc (v4.5.1)
- uclibc (v0.9.31.1)

### **under GNU FDLv1.3**

- popt (v1.16)

### **under GNU GCC Runtime Library Exception**

- libgcc (v4.5.1)

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- AT91Bootstrap 1.9 (v1.9)
- dropbear sshd (v2012.55)

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- libpcap (v1.2.1)
- libxml2 (v2.7.8)
- lsof (v4.85)
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- Pcre (v8.30)
- util Linux (v2.20.1)
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Buildroot is a simple, efficient and easy-to-use tool to generate embedded  
Linux systems through cross-compilation.

The documentation can be found in docs/manual. You can generate a text  
document with 'make manual-text' and read output/docs/manual/manual.text.

Online documentation can be found at <http://buildroot.org/docs.html>

To build and use the buildroot stuff, do the following:

- 1) run 'make menuconfig'
- 2) select the target architecture and the packages you wish to compile
- 3) run 'make'
- 4) wait while it compiles
- 5) find the kernel, bootloader, root filesystem, etc. in output/images

You do not need to be root to build or run buildroot. Have fun!

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Buildroot comes with a basic configuration for a number of boards. Run  
'make list-defconfigs' to view the list of provided configurations.

Please feed suggestions, bug reports, insults, and bribes back to the  
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You can also find us on #buildroot on Freenode IRC.

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---

### Dropbear sshd (v2012.55):

Dropbear contains a number of components from different sources, hence there are a few licenses and authors involved. All licenses are fairly non-restrictive.

The majority of code is written by Matt Johnston, under the license below.

Portions of the client-mode work are (c) 2004 Mihnea Stoenescu, under the same license:

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=====

LibTomCrypt and LibTomMath are written by Tom St Denis, and are Public Domain.

=====

sshpty.c is taken from OpenSSH 3.5p1,

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"As far as I am concerned, the code I have written for this software  
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software must be clearly marked as such, and if the derived work is  
incompatible with the protocol description in the RFC file, it must be  
called by a name other than "ssh" or "Secure Shell". "

=====

loginrec.c

loginrec.h

atomicio.h

atomicio.c

and strlcat() (included in util.c) are from OpenSSH 3.6.1p2, and are licensed  
under the 2 point BSD license.

loginrec is written primarily by Andre Lucas, atomicio.c by Theo de Raadt.

strlcat() is (c) Todd C. Miller

=====

Import code in keyimport.c is modified from PuTTY's import.c, licensed as  
follows:

PuTTY is copyright 1997-2003 Simon Tatham.

Portions copyright Robert de Bath, Joris van Rantwijk, Delian

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Delchev, Andreas Schultz, Jeroen Massar, Wez Furlong, Nicolas Barry,  
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### Gdbserver (v7.2.50.20100908-cvs):

README for GNU development tools

This directory contains various GNU compilers, assemblers, linkers, debuggers, etc., plus their support routines, definitions, and documentation.

If you are receiving this as part of a GDB release, see the file gdb/README.

If with a binutils release, see binutils/README; if with a libg++ release, see libg++/README, etc. That'll give you info about this package -- supported targets, how to use it, how to report bugs, etc.

It is now possible to automatically configure and build a variety of tools with one command. To build all of the tools contained herein, run the ``configure" script here, e.g.:

```
./configure  
make
```

To install them (by default in /usr/local/bin, /usr/local/lib, etc), then do:

```
make install
```

(If the configure script can't determine your type of computer, give it the name as an argument, for instance ``./configure sun4". You can use the script ``config.sub" to test whether a name is recognized; if it is, config.sub translates it to a triplet specifying CPU, vendor, and OS.)

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If you have more than one compiler on your system, it is often best to explicitly set CC in the environment before running configure, and to also set CC when running make. For example (assuming sh/bash/ksh):

```
CC=gcc ./configure  
  
make
```

A similar example using csh:

```
setenv CC gcc  
  
./configure  
  
make
```

Much of the code and documentation enclosed is copyright by the Free Software Foundation, Inc. See the file COPYING or COPYING.LIB in the various directories, for a description of the GNU General Public License terms under which you can copy the files.

REPORTING BUGS: Again, see gdb/README, binutils/README, etc., for info on where and how to report problems.

---

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### Glib (v2.30.2):

#### General Information

---

This is GLib version 2.30.2. GLib is the low-level core library that forms the basis for projects such as GTK+ and GNOME. It provides data structure handling for C, portability wrappers, and interfaces for such runtime functionality as an event loop, threads, dynamic loading, and an object system.

The official ftp site is:

<ftp://ftp.gtk.org/pub/glib>

The official web site is:

<http://www.gtk.org/>

Information about mailing lists can be found at

<http://www.gtk.org/mailling-lists.html>

To subscribe: `mail -s subscribe gtk-list-request@gnome.org < /dev/null`

(Send mail to [gtk-list-request@gnome.org](mailto:gtk-list-request@gnome.org) with the subject "subscribe")

#### Installation

---

See the file 'INSTALL'

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### Notes about GLib 2.30

---

\* GObject includes a generic marshaller, `g_cclosure_marshal_generic`.

To use it, simply specify NULL as the marshaller in `g_signal_new()`.

The generic marshaller is implemented with libffi, and consequently

GObject depends on libffi now.

### Notes about GLib 2.28

---

\* The GApplication API has changed compared to the version that was included in the 2.25 development snapshots. Existing users will need adjustments.

### Notes about GLib 2.26

---

\* Nothing noteworthy.

### Notes about GLib 2.24

---

\* It is now allowed to call `g_thread_init(NULL)` multiple times, and to call glib functions before `g_thread_init(NULL)` is called (although the later is mainly a change in docs as this worked before too). See the GThread reference documentation for the details.

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\* GObject now links to GThread and threads are enabled automatically

when `g_type_init()` is called.

\* GObject no longer allows to call `g_object_set()` on construct-only properties

while an object is being initialized. If this behavior is needed, setting a

custom constructor that just chains up will re-enable this functionality.

\* GMappedFile on an empty file now returns NULL for the contents instead of

returning an empty string. The documentation specifically states that code

may not rely on nul-termination here so any breakage caused by this change

is a bug in application code.

### Notes about GLib 2.22

=====

\* Repeated calls to `g_simple_async_result_set_op_res_gpointer` used

to leak the data. This has been fixed to always call the provided

destroy notify.

### Notes about GLib 2.20

=====

\* The functions for launching applications (e.g. `g_app_info_launch()` +

friends) now passes a FUSE `file://` URI if possible (requires gvfs

with the FUSE daemon to be running and operational). With gvfs 2.26,

FUSE `file://` URIs will be mapped back to gio URIs in the GFile

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constructors. The intent of this change is to better integrate POSIX-only applications, see bug #528670 for the rationale. The only user-visible change is when an application needs to examine an URI passed to it (e.g. as a positional parameter). Instead of looking at the given URI, the application will now need to look at the result of `g_file_get_uri()` after having constructed a `GFile` object with the given URI.

### Notes about GLib 2.18

=====

\* The recommended way of using GLib has always been to only include the toplevel headers `glib.h`, `glib-object.h` and `gio.h`. GLib enforces this by generating an error when individual headers are directly included. To help with the transition, the enforcement is not turned on by default for GLib headers (it is turned on for `GObject` and `GIO`). To turn it on, define the preprocessor symbol `G_DISABLE_SINGLE_INCLUDES`.

### Notes about GLib 2.16

=====

\* GLib now includes `GIO`, which adds optional dependencies against `libattr` and `libselinux` for extended attribute and SELinux support. Use `--disable-xattr` and `--disable-selinux` to build without these.

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Notes about GLib 2.10

=====

\* The functions `g_snprintf()` and `g_vsnprintf()` have been removed from the `gprintf.h` header, since they are already declared in `glib.h`. This doesn't break documented use of `gprintf.h`, but people have been known to include `gprintf.h` without including `glib.h`.

\* The Unicode support has been updated to Unicode 4.1. This adds several new members to the `GUnicodeBreakType` enumeration.

\* The support for Solaris threads has been retired. Solaris has provided POSIX threads for long enough now to have them available on every Solaris platform.

\* 'make check' has been changed to validate translations by calling `msgfmt` with the `-c` option. As a result, it may fail on systems with older `gettext` implementations (GNU `gettext` < 0.14.1, or Solaris `gettext`). 'make check' will also fail on systems where the C compiler does not support ELF visibility attributes.

\* The `GMemChunk` API has been deprecated in favour of a new 'slice allocator'. See the `g_slice` documentation for more details.

\* A new type, `GInitiallyUnowned`, has been introduced, which is intended to serve as a common implementation of the 'floating reference' concept that is e.g. used by `GtkObject`. Note that changing the

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inheritance hierarchy of a type can cause problems for language bindings and other code which needs to work closely with the type system. Therefore, switching to `GInitiallyUnowned` should be done carefully. `g_object_compat_control()` has been added to GLib 2.8.5 to help with the transition.

Notes about GLib 2.6.0

=====

\* GLib 2.6 introduces the concept of 'GLib filename encoding', which is the on-disk encoding on Unix, but UTF-8 on Windows. All GLib functions returning or accepting pathnames have been changed to expect filenames in this encoding, and the common POSIX functions dealing with pathnames have been wrapped. These wrappers are declared in the header `<glib/gstdio.h>` which must be included explicitly; it is not included through `<glib.h>`.

On current (NT-based) Windows versions, where the on-disk file names are Unicode, these wrappers use the wide-character API in the C library. Thus applications can handle file names containing any Unicode characters through GLib's own API and its POSIX wrappers, not just file names restricted to characters in the system codepage.

To keep binary compatibility with applications compiled against older versions of GLib, the Windows DLL still provides entry points with the old semantics using the old names, and applications compiled against GLib 2.6 will actually use new names for the

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functions. This is transparent to the programmer.

When compiling against GLib 2.6, applications intended to be portable to Windows must take the UTF-8 file name encoding into consideration, and use the gstdio wrappers to access files whose names have been constructed from strings returned from GLib.

\* Likewise, `g_get_user_name()` and `g_get_real_name()` have been changed to return UTF-8 on Windows, while keeping the old semantics for applications compiled against older versions of GLib.

\* The GLib uses an `'_'` prefix to indicate private symbols that must not be used by applications. On some platforms, symbols beginning with prefixes such as `_g` will be exported from the library, on others not. In no case can applications use these private symbols. In addition to that, GLib+ 2.6 makes several symbols private which were not in any installed header files and were never intended to be exported.

\* To reduce code size and improve efficiency, GLib, when compiled with the GNU toolchain, has separate internal and external entry points for exported functions. The internal names, which begin with `IA__`, may be seen when debugging a GLib program.

\* On Windows, GLib no longer opens a console window when printing warning messages if `stdout` or `stderr` are invalid, as they are in "Windows subsystem" (GUI) applications. Simply redirect `stdout` or `stderr` if you need to see them.

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- \* The child watch functionality tends to reveal a bug in many thread implementations (in particular the older LinuxThreads implementation on Linux) where it's not possible to call `waitpid()` for a child created in a different thread. For this reason, for maximum portability, you should structure your code to fork all child processes that you want to wait for from the main thread.
- \* A problem was recently discovered with `g_signal_connect_object()`; it doesn't actually disconnect the signal handler once the object being connected to dies, just disables it. See the API docs for the function for further details and the correct workaround that will continue to work with future versions of GLib.

### How to report bugs

=====

Bugs should be reported to the GNOME bug tracking system.

(<http://bugzilla.gnome.org>, product glib.) You will need to create an account for yourself.

In the bug report please include:

- \* Information about your system. For instance:

- What operating system and version
- For Linux, what version of the C library

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And anything else you think is relevant.

\* How to reproduce the bug.

If you can reproduce it with one of the test programs that are built in the tests/ subdirectory, that will be most convenient. Otherwise, please include a short test program that exhibits the behavior.

As a last resort, you can also provide a pointer to a larger piece of software that can be downloaded.

\* If the bug was a crash, the exact text that was printed out when the crash occurred.

\* Further information such as stack traces may be useful, but is not necessary.

### Patches

=====

Patches should also be submitted to [bugzilla.gnome.org](https://bugzilla.gnome.org). If the patch fixes an existing bug, add the patch as an attachment to that bug report.

Otherwise, enter a new bug report that describes the patch, and attach the patch to that bug report.

Patches should be in unified diff form. (The -up option to GNUdiff.)

-----

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### Gzip (v1.5):

This is the file README for the gzip distribution.

The GNU gzip home page is <http://www.gnu.org/software/gzip>.

gzip (GNU zip) is a compression utility designed to be a replacement for 'compress'. Its main advantages over compress are much better compression and freedom from patented algorithms. The GNU Project uses it as the standard compression program for its system.

gzip currently uses by default the LZ77 algorithm used in zip 1.9 (the portable pkzip compatible archiver). The gzip format was however designed to accommodate several compression algorithms. See below for a comparison of zip and gzip.

gunzip can currently decompress files created by gzip, compress or pack. The detection of the input format is automatic. For the gzip format, gunzip checks a 32 bit CRC. For pack, gunzip checks the uncompressed length. The 'compress' format was not designed to allow consistency checks. However gunzip is sometimes able to detect a bad .Z file because there is some redundancy in the .Z compression format. If you get an error when uncompressing a .Z file, do not assume that the .Z file is correct simply because the standard uncompress does not complain. This generally means that the standard uncompress does not check its input, and happily generates garbage output.

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gzip produces files with a .gz extension. Previous versions of gzip used the .z extension, which was already used by the 'pack' Huffman encoder. gunzip is able to decompress .z files (packed or gzip'ed).

Several planned features are not yet supported (see the file TODO).

See the file NEWS for a summary of changes since the last release.

See the file INSTALL for installation instructions.

WARNING: gzip is sensitive to compiler bugs, particularly when optimizing. Use "make check" to check that gzip was compiled correctly. Try compiling gzip without any optimization if you have a problem.

Please send all comments and bug reports by electronic mail to <bug-gzip@gnu.org>.

Bug reports should ideally include:

- \* The complete output of "gzip -V" (or the contents of revision.h if you can't get gzip to compile)
- \* The hardware and operating system (try "uname -a")
- \* The compiler used to compile (if it is gcc, use "gcc -v")
- \* A description of the bug behavior
- \* The input to gzip, that triggered the bug

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If you send me patches for machines I don't have access to, please test them very carefully. gzip is used for backups, it must be extremely reliable.

The znew and gzexe shell scripts provided with gzip benefit from (but do not require) the (non-GNU) cpmode utility to transfer file attributes.

The sample programs zread.c, sub.c and add.c in subdirectory sample are provided as examples of useful complements to gzip. Read the comments inside each source file. The perl script ztouch is also provided as example (not installed by default since it relies on perl).

gzip is free software, you can redistribute it and/or modify it under the terms of the GNU General Public License, a copy of which is provided under the name COPYING. The latest version of gzip are always available from <ftp://ftp.gnu.org/gnu/gzip> or in any of the gnu mirror sites.

- sources in gzip-\*.tar (or .shar or .tar.gz).
- MSDOS lha self-extracting exe in gzip-msdos-\*.exe. Once extracted, copy gzip.exe to gunzip.exe and zcat.exe, or use "gzip -d" to decompress. gzip386.exe runs much faster but only on 386 and above; it was compiled with djgpp 1.10 available in directory [omnigate.clarkson.edu/pub/msdos/djgpp](http://omnigate.clarkson.edu/pub/msdos/djgpp).

A VMS executable is in [ftp://ftp.spc.edu/\[.macro32.savesets\]gzip-1-\\*.zip](ftp://ftp.spc.edu/[.macro32.savesets]gzip-1-*.zip) (use [.macro32]unzip.exe to extract). A PRIMOS executable is available in <ftp://ftp.lysator.liu.se/pub/primos/run/gzip.run>.

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Some ftp servers can automatically make a tar.Z from a tar file. If you are getting gzip for the first time, you can ask for a tar.Z file instead of the much larger tar file.

Many thanks to those who provided me with bug reports and feedback. See the files THANKS and ChangeLog for more details.

### Note about zip vs. gzip:

The name 'gzip' was a very unfortunate choice, because zip and gzip are two really different programs, although the actual compression and decompression sources were written by the same persons. A different name should have been used for gzip, but it is too late to change now.

zip is an archiver: it compresses several files into a single archive file. gzip is a simple compressor: each file is compressed separately. Both share the same compression and decompression code for the 'deflate' method. unzip can also decompress old zip archives (implode, shrink and reduce methods). gunzip can also decompress files created by compress and pack. zip 1.9 and gzip do not support compression methods other than deflation. (zip 1.0 supports shrink and implode). Better compression methods may be added in future versions of gzip. zip will always stick to absolute compatibility with pkzip, it is thus constrained by PKWare, which is a commercial company. The gzip header format is deliberately different from that of pkzip to avoid such a constraint.

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On Unix, gzip is mostly useful in combination with tar. GNU tar 1.11.2 and later has a -z option to invoke gzip automatically. "tar -z" compresses better than zip, since gzip can then take advantage of redundancy between distinct files. The drawback is that you must scan the whole tar.gz file in order to extract a single file near the end; unzip can directly seek to the end of the zip file. There is no overhead when you extract the whole archive anyway.

If a member of a .zip archive is damaged, other files can still be recovered. If a .tar.gz file is damaged, files beyond the failure point cannot be recovered. (Future versions of gzip will have error recovery features.)

gzip and gunzip are distributed as a single program. zip and unzip are, for historical reasons, two separate programs, although the authors of these two programs work closely together in the Info-ZIP team. zip and unzip are not associated with the GNU project.

See <http://info-zip.org/> for more about zip and unzip.

For any copyright year range specified as YYYY-ZZZZ in this package note that the range specifies every single year in that closed interval.

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### Kmod (v8):

kmod - Linux kernel module handling

#### OVERVIEW

=====

kmod is a set of tools to handle common tasks with Linux kernel modules like insert, remove, list, check properties, resolve dependencies and aliases.

These tools are designed on top of libkmod, a library that is shipped with kmod. See libkmod/README for more details on this library and how to use it.

The aim is to be compatible with tools, configurations and indexes from module-init-tools project.

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### Compilation and installation

---

In order to compile the source code you need following software packages:

- GCC compiler
- GNU C library

Optional dependencies:

- ZLIB library
- LZMA library

Typical configuration:

```
./configure CFLAGS="-g -O2" --prefix=/usr \  
--sysconfdir=/etc --libdir=/usr/lib
```

Configure automatically searches for all required components and packages.

To compile and install run:

```
make && make install
```

### Hacking

---

Run 'bootstrap' script before configure. If you want to accept the recommended flags, you just need to run 'bootstrap-configure'.

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Make sure to read the CODING-STYLE file and the other READMEs: libkmod/README  
and testsuite/README.

### Information

=====

### Signed packages:

<http://www.kernel.org/pub/linux/utils/kernel/kmod/>

### Mailing list:

[linux-modules@vger.kernel.org](mailto:linux-modules@vger.kernel.org)

### Git:

<git://git.kernel.org/pub/scm/utils/kernel/kmod/kmod.git>

<http://git.kernel.org/pub/scm/utils/kernel/kmod/kmod.git>

<https://git.kernel.org/pub/scm/utils/kernel/kmod/kmod.git>

### Gitweb:

<http://git.kernel.org/?p=utils/kernel/kmod/kmod.git>

### Irc:

#kmod on [irc.freenode.org](http://irc.freenode.org)

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### Libffi (3.0.11):

Status

=====

libffi-3.0.11 was released on April 11, 2012. Check the libffi web page for updates: <URL:<http://sourceware.org/libffi/>>.

What is libffi?

=====

Compilers for high level languages generate code that follow certain conventions. These conventions are necessary, in part, for separate compilation to work. One such convention is the "calling convention". The "calling convention" is essentially a set of assumptions made by the compiler about where function arguments will be found on entry to a function. A "calling convention" also specifies where the return value for a function is found.

Some programs may not know at the time of compilation what arguments are to be passed to a function. For instance, an interpreter may be told at run-time about the number and types of arguments used to call a given function. Libffi can be used in such programs to provide a bridge from the interpreter program to compiled code.

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The libffi library provides a portable, high level programming interface to various calling conventions. This allows a programmer to call any function specified by a call interface description at run time.

FFI stands for Foreign Function Interface. A foreign function interface is the popular name for the interface that allows code written in one language to call code written in another language. The libffi library really only provides the lowest, machine dependent layer of a fully featured foreign function interface. A layer must exist above libffi that handles type conversions for values passed between the two languages.

### Supported Platforms

=====

Libffi has been ported to many different platforms.

For specific configuration details and testing status, please refer to the wiki page here:

[http://www.moxielogic.org/wiki/index.php?title=Libffi\\_3.0.11](http://www.moxielogic.org/wiki/index.php?title=Libffi_3.0.11)

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At the time of release, the following basic configurations have been tested:

|-----+-----|

| Architecture | Operating System |

|-----+-----|

| Alpha | Linux |

| Alpha | Tru64 |

| ARM | Linux |

| ARM | iOS |

| AVR32 | Linux |

| HPPA | HPUX |

| IA-64 | Linux |

| M68K | FreeMiNT |

| M68K | RTEMS |

| MIPS | IRIX |

| MIPS | Linux |

| MIPS | RTEMS |

| MIPS64 | Linux |

| PowerPC | AMIGA |

| PowerPC | Linux |

| PowerPC | Mac OSX |

| PowerPC | FreeBSD |

| PowerPC64 | Linux |

| S390 | Linux |

| S390X | Linux |

| SPARC | Linux |

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|             |                |  |
|-------------|----------------|--|
| SPARC       | Solaris        |  |
| SPARC64     | Linux          |  |
| SPARC64     | FreeBSD        |  |
| X86         | FreeBSD        |  |
| X86         | Interix        |  |
| X86         | kFreeBSD       |  |
| X86         | Linux          |  |
| X86         | Mac OSX        |  |
| X86         | OpenBSD        |  |
| X86         | OS/2           |  |
| X86         | Solaris        |  |
| X86         | Windows/Cygwin |  |
| X86         | Windows/MingW  |  |
| X86-64      | FreeBSD        |  |
| X86-64      | Linux          |  |
| X86-64      | Linux/x32      |  |
| X86-64      | OpenBSD        |  |
| X86-64      | Windows/MingW  |  |
| -----+----- |                |  |

Please send additional platform test results to

[libffi-discuss@sourceware.org](mailto:libffi-discuss@sourceware.org) and feel free to update the wiki page  
above.

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### Installing libffi

---

First you must configure the distribution for your particular system. Go to the directory you wish to build libffi in and run the "configure" program found in the root directory of the libffi source distribution.

You may want to tell configure where to install the libffi library and header files. To do that, use the `--prefix` configure switch. Libffi will install under `/usr/local` by default.

If you want to enable extra run-time debugging checks use the `--enable-debug` configure switch. This is useful when your program dies mysteriously while using libffi.

Another useful configure switch is `--enable-purify-safety`. Using this will add some extra code which will suppress certain warnings when you are using Purify with libffi. Only use this switch when using Purify, as it will slow down the library.

It's also possible to build libffi on Windows platforms with Microsoft's Visual C++ compiler. In this case, use the `msvcc.sh` wrapper script during configuration like so:

```
path/to/configure CC=path/to/msvcc.sh LD=link CPP=\"cl -nologo -EP\"
```

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For 64-bit Windows builds, use `CC="path/to/msvcc.sh -m64"`.

You may also need to specify `--build` appropriately. When building with MSVC under a MingW environment, you may need to remove the line in `configure` that sets `'fix_srcfile_path'` to a `'cygpath'` command. (`'cygpath'` is not present in MingW, and is not required when using MingW-style paths.)

For iOS builds, run `generate-ios-source-and-headers.py` and then `libffi.xcodeproj` should work.

`Configure` has many other options. Use `"configure --help"` to see them all.

Once `configure` has finished, type `"make"`. Note that you must be using GNU make. You can ftp GNU make from [prep.ai.mit.edu:/pub/gnu](http://prep.ai.mit.edu:/pub/gnu).

To ensure that `libffi` is working as advertised, type `"make check"`.

This will require that you have `DejaGNU` installed.

To install the library and header files, type `"make install"`.

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### History

---

See the ChangeLog files for details.

#### 3.0.11 Apr-11-12

Add support for variadic functions (`ffi_prep_cif_var`).

Add Linux/x32 support.

Add `thiscall`, `fastcall` and `MSVC cdecl` support on Windows.

Add Amiga and newer MacOS support.

Add m68k FreeMiNT support.

Integration with iOS' xcode build tools.

Fix Octeon and MC68881 support.

Fix code pessimizations.

Lots of build fixes.

#### 3.0.10 Aug-23-11

Add support for Apple's iOS.

Add support for ARM VFP ABI.

Add RTEMS support for MIPS and M68K.

Fix instruction cache clearing problems on

ARM and SPARC.

Fix the N64 build on mips-sgi-irix6.5.

Enable builds with Microsoft's compiler.

Enable x86 builds with Oracle's Solaris compiler.

Fix support for calling code compiled with Oracle's Sparc

Solaris compiler.

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Testsuite fixes for Tru64 Unix.

Additional platform support.

### 3.0.9 Dec-31-09

Add AVR32 and win64 ports. Add ARM softfp support.

Many fixes for AIX, Solaris, HP-UX, \*BSD.

Several PowerPC and x86-64 bug fixes.

Build DLL for windows.

### 3.0.8 Dec-19-08

Add \*BSD, BeOS, and PA-Linux support.

### 3.0.7 Nov-11-08

Fix for ppc FreeBSD.

(thanks to Andreas Tobler)

### 3.0.6 Jul-17-08

Fix for closures on sh.

Mark the sh/sh64 stack as non-executable.

(both thanks to Kaz Kojima)

### 3.0.5 Apr-3-08

Fix libffi.pc file.

Fix #define ARM for IcedTea users.

Fix x86 closure bug.

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### 3.0.4 Feb-24-08

Fix x86 OpenBSD configury.

### 3.0.3 Feb-22-08

Enable x86 OpenBSD thanks to Thomas Heller, and

x86-64 FreeBSD thanks to Björn König and Andreas Tobler.

Clean up test instruction in README.

### 3.0.2 Feb-21-08

Improved x86 FreeBSD support.

Thanks to Björn König.

### 3.0.1 Feb-15-08

Fix instruction cache flushing bug on MIPS.

Thanks to David Daney.

### 3.0.0 Feb-15-08

Many changes, mostly thanks to the GCC project.

Cygnus Solutions is now Red Hat.

[10 years go by...]

### 1.20 Oct-5-98

Raffaele Sena produces ARM port.

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1.19 Oct-5-98

Fixed x86 long double and long long return support.

m68k bug fixes from Andreas Schwab.

Patch for DU assembler compatibility for the Alpha from Richard Henderson.

1.18 Apr-17-98

Bug fixes and MIPS configuration changes.

1.17 Feb-24-98

Bug fixes and m68k port from Andreas Schwab. PowerPC port from Geoffrey Keating. Various bug x86, Sparc and MIPS bug fixes.

1.16 Feb-11-98

Richard Henderson produces Alpha port.

1.15 Dec-4-97

Fixed an n32 ABI bug. New libtool, auto\* support.

1.14 May-13-97

libtool is now used to generate shared and static libraries.

Fixed a minor portability problem reported by Russ McManus  
<mcmannr@eq.gs.com>.

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### 1.13 Dec-2-96

Added --enable-purify-safety to keep Purify from complaining about certain low level code.

Sparc fix for calling functions with < 6 args.

Linux x86 a.out fix.

### 1.12 Nov-22-96

Added missing ffi\_type\_void, needed for supporting void return types. Fixed test case for non MIPS machines. Cygnus Support is now Cygnus Solutions.

### 1.11 Oct-30-96

Added notes about GNU make.

### 1.10 Oct-29-96

Added configuration fix for non GNU compilers.

### 1.09 Oct-29-96

Added --enable-debug configure switch. Clean-ups based on LCLint feedback. ffi\_mips.h is always installed. Many configuration fixes. Fixed ffitest.c for sparc builds.

### 1.08 Oct-15-96

Fixed n32 problem. Many clean-ups.

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1.07 Oct-14-96

Gordon Irlam rewrites v8.S again. Bug fixes.

1.06 Oct-14-96

Gordon Irlam improved the sparc port.

1.05 Oct-14-96

Interface changes based on feedback.

1.04 Oct-11-96

Sparc port complete (modulo struct passing bug).

1.03 Oct-10-96

Passing struct args, and returning struct values works for  
all architectures/calling conventions. Expanded tests.

1.02 Oct-9-96

Added SGI n32 support. Fixed bugs in both o32 and Linux support.

Added "make test".

1.01 Oct-8-96

Fixed float passing bug in mips version. Restructured some  
of the code. Builds cleanly with SGI tools.

1.00 Oct-7-96

First release. No public announcement.

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### Authors & Credits

---

libffi was originally written by Anthony Green <green@moxielogic.com>.

The developers of the GNU Compiler Collection project have made innumerable valuable contributions. See the ChangeLog file for details.

Some of the ideas behind libffi were inspired by Gianni Mariani's free gencall library for Silicon Graphics machines.

The closure mechanism was designed and implemented by Kresten Krab Thorup.

Major processor architecture ports were contributed by the following developers:

|       |                                   |
|-------|-----------------------------------|
| alpha | Richard Henderson                 |
| arm   | Raffaele Sena                     |
| cris  | Simon Posnjak, Hans-Peter Nilsson |
| frv   | Anthony Green                     |
| ia64  | Hans Boehm                        |
| m32r  | Kazuhiro Inaoka                   |
| m68k  | Andreas Schwab                    |
| mips  | Anthony Green, Casey Marshall     |

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|           |                                                                     |
|-----------|---------------------------------------------------------------------|
| mips64    | David Daney                                                         |
| pa        | Randolph Chung, Dave Anglin, Andreas Tobler                         |
| powerpc   | Geoffrey Keating, Andreas Tobler,<br>David Edelsohn, John Hornkvist |
| powerpc64 | Jakub Jelinek                                                       |
| s390      | Gerhard Tonn, Ulrich Weigand                                        |
| sh        | Kaz Kojima                                                          |
| sh64      | Kaz Kojima                                                          |
| sparc     | Anthony Green, Gordon Irlam                                         |
| x86       | Anthony Green, Jon Beniston                                         |
| x86-64    | Bo Thorsen                                                          |

Jesper Skov and Andrew Haley both did more than their fair share of stepping through the code and tracking down bugs.

Thanks also to Tom Tromey for bug fixes, documentation and configuration help.

Thanks to Jim Blandy, who provided some useful feedback on the libffi interface.

Andreas Tobler has done a tremendous amount of work on the testsuite.

Alex Oliva solved the executable page problem for SELinux.

The list above is almost certainly incomplete and inaccurate. I'm happy to make corrections or additions upon request.

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If you have a problem, or have found a bug, please send a note to the  
author at [green@moxielogic.com](mailto:green@moxielogic.com), or the project mailing list at  
[libffi-discuss@sourceware.org](mailto:libffi-discuss@sourceware.org).

---

### Libjpeg (v9a):

The Independent JPEG Group's JPEG software

=====

README for release 8d of 15-Jan-2012

=====

This distribution contains the eighth public release of the Independent JPEG  
Group's free JPEG software. You are welcome to redistribute this software and  
to use it for any purpose, subject to the conditions under LEGAL ISSUES, below.

This software is the work of Tom Lane, Guido Vollbeding, Philip Gladstone,  
Bill Allombert, Jim Boucher, Lee Crocker, Bob Friesenhahn, Ben Jackson,  
Julian Minguillon, Luis Ortiz, George Phillips, Davide Rossi, Ge' Weijers,  
and other members of the Independent JPEG Group.

IJG is not affiliated with the ISO/IEC JTC1/SC29/WG1 standards committee  
(also known as JPEG, together with ITU-T SG16).

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### DOCUMENTATION ROADMAP

=====

This file contains the following sections:

OVERVIEW        General description of JPEG and the IJG software.

LEGAL ISSUES    Copyright, lack of warranty, terms of distribution.

REFERENCES     Where to learn more about JPEG.

ARCHIVE LOCATIONS   Where to find newer versions of this software.

ACKNOWLEDGMENTS   Special thanks.

FILE FORMAT WARS   Software \*not\* to get.

TO DO           Plans for future IJG releases.

Other documentation files in the distribution are:

User documentation:

install.txt     How to configure and install the IJG software.

usage.txt       Usage instructions for cjpeg, djpeg, jpegtran,  
rdjpgcom, and wrjpgcom.

\*.1             Unix-style man pages for programs (same info as usage.txt).

wizard.txt      Advanced usage instructions for JPEG wizards only.

change.log      Version-to-version change highlights.

Programmer and internal documentation:

libjpeg.txt     How to use the JPEG library in your own programs.

example.c       Sample code for calling the JPEG library.

structure.txt   Overview of the JPEG library's internal structure.

filelist.txt     Road map of IJG files.

coderrules.txt   Coding style rules --- please read if you contribute code.

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Please read at least the files `install.txt` and `usage.txt`. Some information can also be found in the JPEG FAQ (Frequently Asked Questions) article. See ARCHIVE LOCATIONS below to find out where to obtain the FAQ article.

If you want to understand how the JPEG code works, we suggest reading one or more of the REFERENCES, then looking at the documentation files (in roughly the order listed) before diving into the code.

### OVERVIEW

=====

This package contains C software to implement JPEG image encoding, decoding, and transcoding. JPEG (pronounced "jay-peg") is a standardized compression method for full-color and gray-scale images.

This software implements JPEG baseline, extended-sequential, and progressive compression processes. Provision is made for supporting all variants of these processes, although some uncommon parameter settings aren't implemented yet. We have made no provision for supporting the hierarchical or lossless processes defined in the standard.

We provide a set of library routines for reading and writing JPEG image files, plus two sample applications "cjpeg" and "djpeg", which use the library to perform conversion between JPEG and some other popular image file formats. The library is intended to be reused in other applications.

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In order to support file conversion and viewing software, we have included considerable functionality beyond the bare JPEG coding/decoding capability; for example, the color quantization modules are not strictly part of JPEG decoding, but they are essential for output to colormapped file formats or colormapped displays. These extra functions can be compiled out of the library if not required for a particular application.

We have also included "jpegtran", a utility for lossless transcoding between different JPEG processes, and "rdjpgcom" and "wrjpgcom", two simple applications for inserting and extracting textual comments in JFIF files.

The emphasis in designing this software has been on achieving portability and flexibility, while also making it fast enough to be useful. In particular, the software is not intended to be read as a tutorial on JPEG. (See the REFERENCES section for introductory material.) Rather, it is intended to be reliable, portable, industrial-strength code. We do not claim to have achieved that goal in every aspect of the software, but we strive for it.

We welcome the use of this software as a component of commercial products. No royalty is required, but we do ask for an acknowledgement in product documentation, as described under LEGAL ISSUES.

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### LEGAL ISSUES

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3. You may not pretend that you wrote this software. If you use it in a program, you must acknowledge somewhere in your documentation that you've used the IJG code.

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(2) If only executable code is distributed, then the accompanying documentation must state that "this software is based in part on the work of the Independent JPEG Group".

(3) Permission for use of this software is granted only if the user accepts full responsibility for any undesirable consequences; the authors accept NO LIABILITY for damages of any kind.

These conditions apply to any software derived from or based on the IJG code, not just to the unmodified library. If you use our work, you ought to acknowledge us.

Permission is NOT granted for the use of any IJG author's name or company name in advertising or publicity relating to this software or products derived from it. This software may be referred to only as "the Independent JPEG Group's software".

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ansi2knr.c is included in this distribution by permission of L. Peter Deutsch, sole proprietor of its copyright holder, Aladdin Enterprises of Menlo Park, CA. ansi2knr.c is NOT covered by the above copyright and conditions, but instead by the usual distribution terms of the Free Software Foundation; principally,

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that you must include source code if you redistribute it. (See the file `ansi2knr.c` for full details.) However, since `ansi2knr.c` is not needed as part of any program generated from the IJG code, this does not limit you more than the foregoing paragraphs do.

The Unix configuration script "configure" was produced with GNU Autoconf.

It is copyright by the Free Software Foundation but is freely distributable.

The same holds for its supporting scripts (`config.guess`, `config.sub`, `ltmain.sh`). Another support script, `install-sh`, is copyright by X Consortium but is also freely distributable.

The IJG distribution formerly included code to read and write GIF files.

To avoid entanglement with the Unisys LZW patent, GIF reading support has been removed altogether, and the GIF writer has been simplified to produce "uncompressed GIFs". This technique does not use the LZW algorithm; the resulting GIF files are larger than usual, but are readable by all standard GIF decoders.

We are required to state that

"The Graphics Interchange Format(c) is the Copyright property of CompuServe Incorporated. GIF(sm) is a Service Mark property of CompuServe Incorporated."

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### REFERENCES

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We recommend reading one or more of these references before trying to understand the innards of the JPEG software.

The best short technical introduction to the JPEG compression algorithm is

Wallace, Gregory K. "The JPEG Still Picture Compression Standard",  
Communications of the ACM, April 1991 (vol. 34 no. 4), pp. 30-44.

(Adjacent articles in that issue discuss MPEG motion picture compression, applications of JPEG, and related topics.) If you don't have the CACM issue handy, a PostScript file containing a revised version of Wallace's article is available at <http://www.iijg.org/files/wallace.ps.gz>. The file (actually a preprint for an article that appeared in IEEE Trans. Consumer Electronics) omits the sample images that appeared in CACM, but it includes corrections and some added material. Note: the Wallace article is copyright ACM and IEEE, and it may not be used for commercial purposes.

A somewhat less technical, more leisurely introduction to JPEG can be found in "The Data Compression Book" by Mark Nelson and Jean-loup Gailly, published by M&T Books (New York), 2nd ed. 1996, ISBN 1-55851-434-1. This book provides good explanations and example C code for a multitude of compression methods including JPEG. It is an excellent source if you are comfortable reading C code but don't know much about data compression in general. The book's JPEG sample code is far from industrial-strength, but when you are ready to look at a full implementation, you've got one here...

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The best currently available description of JPEG is the textbook "JPEG Still Image Data Compression Standard" by William B. Pennebaker and Joan L. Mitchell, published by Van Nostrand Reinhold, 1993, ISBN 0-442-01272-1. Price US\$59.95, 638 pp. The book includes the complete text of the ISO JPEG standards (DIS 10918-1 and draft DIS 10918-2).

Although this is by far the most detailed and comprehensive exposition of JPEG publicly available, we point out that it is still missing an explanation of the most essential properties and algorithms of the underlying DCT technology.

If you think that you know about DCT-based JPEG after reading this book, then you are in delusion. The real fundamentals and corresponding potential of DCT-based JPEG are not publicly known so far, and that is the reason for all the mistaken developments taking place in the image coding domain.

The original JPEG standard is divided into two parts, Part 1 being the actual specification, while Part 2 covers compliance testing methods. Part 1 is titled "Digital Compression and Coding of Continuous-tone Still Images, Part 1: Requirements and guidelines" and has document numbers ISO/IEC IS 10918-1, ITU-T T.81. Part 2 is titled "Digital Compression and Coding of Continuous-tone Still Images, Part 2: Compliance testing" and has document numbers ISO/IEC IS 10918-2, ITU-T T.83.

IJG JPEG 8 introduces an implementation of the JPEG SmartScale extension which is specified in two documents: A contributed document at ITU and ISO with title "ITU-T JPEG-Plus Proposal for Extending ITU-T T.81 for Advanced Image Coding", April 2006, Geneva, Switzerland. The latest version of this document is Revision 3. And a contributed document ISO/IEC JTC1/SC29/WG1 N 5799 with title "Evolution of JPEG", June/July 2011, Berlin, Germany.

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The JPEG standard does not specify all details of an interchangeable file format. For the omitted details we follow the "JFIF" conventions, revision 1.02. JFIF 1.02 has been adopted as an Ecma International Technical Report and thus received a formal publication status. It is available as a free download in PDF format from

<http://www.ecma-international.org/publications/techreports/E-TR-098.htm>.

A PostScript version of the JFIF document is available at

<http://www.ijg.org/files/jfif.ps.gz>. There is also a plain text version at

<http://www.ijg.org/files/jfif.txt.gz>, but it is missing the figures.

The TIFF 6.0 file format specification can be obtained by FTP from <ftp://ftp.sgi.com/graphics/tiff/TIFF6.ps.gz>. The JPEG incorporation scheme found in the TIFF 6.0 spec of 3-June-92 has a number of serious problems.

IJG does not recommend use of the TIFF 6.0 design (TIFF Compression tag 6).

Instead, we recommend the JPEG design proposed by TIFF Technical Note #2 (Compression tag 7). Copies of this Note can be obtained from

<http://www.ijg.org/files/>. It is expected that the next revision

of the TIFF spec will replace the 6.0 JPEG design with the Note's design.

Although IJG's own code does not support TIFF/JPEG, the free libtiff library uses our library to implement TIFF/JPEG per the Note.

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### ARCHIVE LOCATIONS

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The "official" archive site for this software is [www.ijg.org](http://www.ijg.org).

The most recent released version can always be found there in

directory "files". This particular version will be archived as

<http://www.ijg.org/files/jpegsrc.v8d.tar.gz>, and in Windows-compatible

"zip" archive format as <http://www.ijg.org/files/jpegsr8d.zip>.

The JPEG FAQ (Frequently Asked Questions) article is a source of some

general information about JPEG.

It is available on the World Wide Web at <http://www.faqs.org/faqs/jpeg-faq/>

and other news.answers archive sites, including the official news.answers

archive at [rtfm.mit.edu](ftp://rtfm.mit.edu/pub/usenet/news.answers/jpeg-faq/): <ftp://rtfm.mit.edu/pub/usenet/news.answers/jpeg-faq/>.

If you don't have Web or FTP access, send e-mail to [mail-server@rtfm.mit.edu](mailto:mail-server@rtfm.mit.edu)

with body

send usenet/news.answers/jpeg-faq/part1

send usenet/news.answers/jpeg-faq/part2

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### ACKNOWLEDGMENTS

---

Thank to Juergen Bruder for providing me with a copy of the common DCT algorithm article, only to find out that I had come to the same result in a more direct and comprehensible way with a more generative approach.

Thank to Istvan Sebestyen and Joan L. Mitchell for inviting me to the ITU JPEG (Study Group 16) meeting in Geneva, Switzerland.

Thank to Thomas Wiegand and Gary Sullivan for inviting me to the Joint Video Team (MPEG & ITU) meeting in Geneva, Switzerland.

Thank to Thomas Richter and Daniel Lee for inviting me to the ISO/IEC JTC1/SC29/WG1 (also known as JPEG, together with ITU-T SG16) meeting in Berlin, Germany.

Thank to John Korejwa and Massimo Ballerini for inviting me to fruitful consultations in Boston, MA and Milan, Italy.

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Thank to Nico Zschach and Dirk Stelling of the technical support team at the Digital Images company in Halle for providing me with extra equipment for configuration tests.

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Thank to Richard F. Lyon (then of Foveon Inc.) for fruitful communication about JPEG configuration in Sigma Photo Pro software.

Thank to Andrew Finkenzstadt for hosting the [ijg.org](http://ijg.org) site.

Last but not least special thank to Thomas G. Lane for the original design and development of this singular software package.

### FILE FORMAT WARS

=====

The ISO/IEC JTC1/SC29/WG1 standards committee (also known as JPEG, together with ITU-T SG16) currently promotes different formats containing the name "JPEG" which is misleading because these formats are incompatible with original DCT-based JPEG and are based on faulty technologies.

IJG therefore does not and will not support such momentary mistakes (see REFERENCES).

There exist also distributions under the name "OpenJPEG" promoting such kind of formats which is misleading because they don't support original JPEG images.

We have no sympathy for the promotion of inferior formats. Indeed, one of the original reasons for developing this free software was to help force convergence on common, interoperable format standards for JPEG files.

Don't use an incompatible file format!

(In any case, our decoder will remain capable of reading existing JPEG image files indefinitely.)

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Furthermore, the ISO committee pretends to be "responsible for the popular JPEG" in their public reports which is not true because they don't respond to actual requirements for the maintenance of the original JPEG specification.

There are currently distributions in circulation containing the name "libjpeg" which claim to be a "derivative" or "fork" of the original libjpeg, but don't have the features and are incompatible with formats supported by actual IJG libjpeg distributions. Furthermore, they violate the license conditions as described under LEGAL ISSUES above.

We have no sympathy for the release of misleading and illegal distributions derived from obsolete code bases.

Don't use an obsolete code base!

TO DO

=====

Version 8 is the first release of a new generation JPEG standard to overcome the limitations of the original JPEG specification. More features are being prepared for coming releases...

Please send bug reports, offers of help, etc. to [jpeg-info@jpegclub.org](mailto:jpeg-info@jpegclub.org).

-----

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### Libkmod (v8):

libkmod - linux kernel module handling library

#### ABSTRACT

=====

libkmod was created to allow programs to easily insert, remove and list modules, also checking its properties, dependencies and aliases.

there is no shared/global context information and it can be used by multiple sites on a single program, also being able to be used from threads, although it's not thread safe (you must lock explicitly).

#### OVERVIEW

=====

Every user should create and manage it's own library context with:

```
struct kmod_ctx *ctx = kmod_new(kernel_dirname);  
  
kmod_unref(ctx);
```

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Modules can be created with by various means:

```
struct kmod_module *mod;

int err;

err = kmod_module_new_from_path(ctx, path, &mod);

if (err < 0) {

    /* code */

} else {

    /* code */

    kmod_module_unref(mod);

}

err = kmod_module_new_from_name(ctx, name, &mod);

if (err < 0) {

    /* code */

} else {

    /* code */

    kmod_module_unref(mod);

}
```

Or could be resolved from a known alias to a list of alternatives:

```
struct kmod_list *list, *itr;

int err;

err = kmod_module_new_from_lookup(ctx, alias, &list);
```

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```
if (err < 0) {  
  
    /* code */  
  
} else {  
  
    kmod_list_foreach(itr, list) {  
  
        struct kmod_module *mod = kmod_module_get_module(itr);  
  
        /* code */  
  
    }  
  
}
```

---

### Libxml2 (v2.7.8):

Except where otherwise noted in the source code (e.g. the files hash.c, list.c and the trio files, which are covered by a similar licence but with different Copyright notices) all the files are:

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### LibPcap (v1.2.1):

License: BSD

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### Linux (v3.2.26):

Linux kernel release 3.x <<http://kernel.org/>>

These are the release notes for Linux version 3. Read them carefully,  
as they tell you what this is all about, explain how to install the  
kernel, and what to do if something goes wrong.

#### WHAT IS LINUX?

Linux is a clone of the operating system Unix, written from scratch by  
Linus Torvalds with assistance from a loosely-knit team of hackers across  
the Net. It aims towards POSIX and Single UNIX Specification compliance.

It has all the features you would expect in a modern fully-fledged Unix,  
including true multitasking, virtual memory, shared libraries, demand  
loading, shared copy-on-write executables, proper memory management,  
and multistack networking including IPv4 and IPv6.

It is distributed under the GNU General Public License - see the  
accompanying COPYING file for more details.

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### ON WHAT HARDWARE DOES IT RUN?

Although originally developed first for 32-bit x86-based PCs (386 or higher), today Linux also runs on (at least) the Compaq Alpha AXP, Sun SPARC and UltraSPARC, Motorola 68000, PowerPC, PowerPC64, ARM, Hitachi SuperH, Cell, IBM S/390, MIPS, HP PA-RISC, Intel IA-64, DEC VAX, AMD x86-64, AXIS CRIS, Xtensa, Tilera TILE, AVR32 and Renesas M32R architectures.

Linux is easily portable to most general-purpose 32- or 64-bit architectures as long as they have a paged memory management unit (PMMU) and a port of the GNU C compiler (gcc) (part of The GNU Compiler Collection, GCC). Linux has also been ported to a number of architectures without a PMMU, although functionality is then obviously somewhat limited.

Linux has also been ported to itself. You can now run the kernel as a userspace application - this is called UserMode Linux (UML).

### DOCUMENTATION:

- There is a lot of documentation available both in electronic form on the Internet and in books, both Linux-specific and pertaining to general UNIX questions. I'd recommend looking into the documentation subdirectories on any Linux FTP site for the LDP (Linux Documentation Project) books. This README is not meant to be documentation on the system: there are much better sources available.
- There are various README files in the Documentation/ subdirectory: these typically contain kernel-specific installation notes for some

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drivers for example. See Documentation/00-INDEX for a list of what is contained in each file. Please read the Changes file, as it contains information about the problems, which may result by upgrading your kernel.

- The Documentation/DocBook/ subdirectory contains several guides for kernel developers and users. These guides can be rendered in a number of formats: PostScript (.ps), PDF, HTML, & man-pages, among others. After installation, "make psdocs", "make pdfdocs", "make htmldocs", or "make mandocs" will render the documentation in the requested format.

INSTALLING the kernel source:

- If you install the full sources, put the kernel tarball in a directory where you have permissions (eg. your home directory) and unpack it:

```
gzip -cd linux-3.X.tar.gz | tar xvf -
```

or

```
bzip2 -dc linux-3.X.tar.bz2 | tar xvf -
```

Replace "XX" with the version number of the latest kernel.

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Do NOT use the /usr/src/linux area! This area has a (usually incomplete) set of kernel headers that are used by the library header files. They should match the library, and not get messed up by whatever the kernel-du-jour happens to be.

- You can also upgrade between 3.x releases by patching. Patches are distributed in the traditional gzip and the newer bzip2 format. To install by patching, get all the newer patch files, enter the top level directory of the kernel source (linux-3.x) and execute:

```
gzip -cd ../patch-3.x.gz | patch -p1
```

or

```
bzip2 -dc ../patch-3.x.bz2 | patch -p1
```

(repeat xx for all versions bigger than the version of your current source tree, `_in_order_`) and you should be ok. You may want to remove the backup files (`xxx~` or `xxx.orig`), and make sure that there are no failed patches (`xxx#` or `xxx.rej`). If there are, either you or me has made a mistake.

Unlike patches for the 3.x kernels, patches for the 3.x.y kernels (also known as the `-stable` kernels) are not incremental but instead apply directly to the base 3.x kernel. Please read [Documentation/applying-patches.txt](#) for more information.

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Alternatively, the script patch-kernel can be used to automate this process. It determines the current kernel version and applies any patches found.

```
linux/scripts/patch-kernel linux
```

The first argument in the command above is the location of the kernel source. Patches are applied from the current directory, but an alternative directory can be specified as the second argument.

- If you are upgrading between releases using the stable series patches (for example, patch-3.x.y), note that these "dot-releases" are not incremental and must be applied to the 3.x base tree. For example, if your base kernel is 3.0 and you want to apply the 3.0.3 patch, you do not and indeed must not first apply the 3.0.1 and 3.0.2 patches. Similarly, if you are running kernel version 3.0.2 and want to jump to 3.0.3, you must first reverse the 3.0.2 patch (that is, patch -R) before applying the 3.0.3 patch.

You can read more on this in Documentation/applying-patches.txt

- Make sure you have no stale .o files and dependencies lying around:

```
cd linux
```

```
make mrproper
```

You should now have the sources correctly installed.

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### SOFTWARE REQUIREMENTS

Compiling and running the 3.x kernels requires up-to-date versions of various software packages. Consult Documentation/Changes for the minimum version numbers required and how to get updates for these packages. Beware that using excessively old versions of these packages can cause indirect errors that are very difficult to track down, so don't assume that you can just update packages when obvious problems arise during build or operation.

BUILD directory for the kernel:

When compiling the kernel all output files will per default be stored together with the kernel source code.

Using the option "make O=output/dir" allow you to specify an alternate place for the output files (including .config).

Example:

kernel source code: /usr/src/linux-3.N

build directory:           /home/name/build/kernel

To configure and build the kernel use:

```
cd /usr/src/linux-3.N
```

```
make O=/home/name/build/kernel menuconfig
```

```
make O=/home/name/build/kernel
```

```
sudo make O=/home/name/build/kernel modules_install install
```

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Please note: If the 'O=output/dir' option is used then it must be used for all invocations of make.

### CONFIGURING the kernel:

Do not skip this step even if you are only upgrading one minor version. New configuration options are added in each release, and odd problems will turn up if the configuration files are not set up as expected. If you want to carry your existing configuration to a new version with minimal work, use "make oldconfig", which will only ask you for the answers to new questions.

- Alternate configuration commands are:

- "make config" Plain text interface.
- "make menuconfig" Text based color menus, radiolists & dialogs.
- "make nconfig" Enhanced text based color menus.
- "make xconfig" X windows (Qt) based configuration tool.
- "make gconfig" X windows (Gtk) based configuration tool.
- "make oldconfig" Default all questions based on the contents of your existing `./config` file and asking about new config symbols.
- "make silentoldconfig"  
Like above, but avoids cluttering the screen with questions already answered.  
Additionally updates the dependencies.
- "make defconfig" Create a `./config` file by using the default symbol values from either `arch/$ARCH/defconfig`

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or arch/\$ARCH/configs/\${PLATFORM}\_defconfig,

depending on the architecture.

"make \${PLATFORM}\_defconfig"

Create a `./config` file by using the default

symbol values from

arch/\$ARCH/configs/\${PLATFORM}\_defconfig.

Use "make help" to get a list of all available

platforms of your architecture.

"make allyesconfig"

Create a `./config` file by setting symbol

values to 'y' as much as possible.

"make allmodconfig"

Create a `./config` file by setting symbol

values to 'm' as much as possible.

"make allnoconfig" Create a `./config` file by setting symbol

values to 'n' as much as possible.

"make randconfig" Create a `./config` file by setting symbol

values to random values.

You can find more information on using the Linux kernel config tools  
in `Documentation/kbuild/kconfig.txt`.

NOTES on "make config":

- having unnecessary drivers will make the kernel bigger, and can under some circumstances lead to problems: probing for a nonexistent controller card may confuse your other controllers
- compiling the kernel with "Processor type" set higher than 386

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will result in a kernel that does NOT work on a 386. The

kernel will detect this on bootup, and give up.

- A kernel with math-emulation compiled in will still use the coprocessor if one is present: the math emulation will just never get used in that case. The kernel will be slightly larger, but will work on different machines regardless of whether they have a math coprocessor or not.
- the "kernel hacking" configuration details usually result in a bigger or slower kernel (or both), and can even make the kernel less stable by configuring some routines to actively try to break bad code to find kernel problems (kmallocc()). Thus you should probably answer 'n' to the questions for "development", "experimental", or "debugging" features.

### COMPILING the kernel:

- Make sure you have at least gcc 3.2 available.

For more information, refer to Documentation/Changes.

Please note that you can still run a.out user programs with this kernel.

- Do a "make" to create a compressed kernel image. It is also possible to do "make install" if you have lilo installed to suit the kernel makefiles, but you may want to check your particular lilo setup first.

To do the actual install you have to be root, but none of the normal build should require that. Don't take the name of root in vain.

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- If you configured any of the parts of the kernel as 'modules', you will also have to do "make modules\_install".

- Verbose kernel compile/build output:

Normally the kernel build system runs in a fairly quiet mode (but not totally silent). However, sometimes you or other kernel developers need to see compile, link, or other commands exactly as they are executed.

For this, use "verbose" build mode. This is done by inserting

"V=1" in the "make" command. E.g.:

```
make V=1 all
```

To have the build system also tell the reason for the rebuild of each target, use "V=2". The default is "V=0".

- Keep a backup kernel handy in case something goes wrong. This is especially true for the development releases, since each new release contains new code which has not been debugged. Make sure you keep a backup of the modules corresponding to that kernel, as well. If you are installing a new kernel with the same version number as your working kernel, make a backup of your modules directory before you do a "make modules\_install".

Alternatively, before compiling, use the kernel config option

"LOCALVERSION" to append a unique suffix to the regular kernel version.

LOCALVERSION can be set in the "General Setup" menu.

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- In order to boot your new kernel, you'll need to copy the kernel image (e.g. .../linux/arch/i386/boot/bzImage after compilation) to the place where your regular bootable kernel is found.
- Booting a kernel directly from a floppy without the assistance of a bootloader such as LILO, is no longer supported.

If you boot Linux from the hard drive, chances are you use LILO which uses the kernel image as specified in the file `/etc/lilo.conf`. The kernel image file is usually `/vmlinuz`, `/boot/vmlinuz`, `/bzImage` or `/boot/bzImage`. To use the new kernel, save a copy of the old image and copy the new image over the old one. Then, you MUST RERUN LILO to update the loading map!! If you don't, you won't be able to boot the new kernel image.

Reinstalling LILO is usually a matter of running `/sbin/lilo`.

You may wish to edit `/etc/lilo.conf` to specify an entry for your old kernel image (say, `/vmlinux.old`) in case the new one does not work. See the LILO docs for more information.

After reinstalling LILO, you should be all set. Shutdown the system, reboot, and enjoy!

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If you ever need to change the default root device, video mode, ramdisk size, etc. in the kernel image, use the 'rdev' program (or alternatively the LILO boot options when appropriate). No need to recompile the kernel to change these parameters.

- Reboot with the new kernel and enjoy.

### IF SOMETHING GOES WRONG:

- If you have problems that seem to be due to kernel bugs, please check the file MAINTAINERS to see if there is a particular person associated with the part of the kernel that you are having trouble with. If there isn't anyone listed there, then the second best thing is to mail them to me ([torvalds@linux-foundation.org](mailto:torvalds@linux-foundation.org)), and possibly to any other relevant mailing-list or to the newsgroup.

- In all bug-reports, *\*please\** tell what kernel you are talking about, how to duplicate the problem, and what your setup is (use your common sense). If the problem is new, tell me so, and if the problem is old, please try to tell me when you first noticed it.

- If the bug results in a message like

```
unable to handle kernel paging request at address C0000010
```

```
Oops: 0002
```

```
EIP: 0010:XXXXXXXX
```

```
eax: xxxxxxxx ebx: xxxxxxxx ecx: xxxxxxxx edx: xxxxxxxx
```

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```
esi: xxxxxxxx  edi: xxxxxxxx  ebp: xxxxxxxx
```

```
ds: xxxx  es: xxxx  fs: xxxx  gs: xxxx
```

```
Pid: xx, process nr: xx
```

```
xx xx xx xx xx xx xx xx xx xx
```

or similar kernel debugging information on your screen or in your system log, please duplicate it *\*exactly\**. The dump may look incomprehensible to you, but it does contain information that may help debugging the problem. The text above the dump is also important: it tells something about why the kernel dumped code (in the above example it's due to a bad kernel pointer). More information on making sense of the dump is in [Documentation/oops-tracing.txt](#)

- If you compiled the kernel with CONFIG\_KALLSYMS you can send the dump as is, otherwise you will have to use the "ksymoops" program to make sense of the dump (but compiling with CONFIG\_KALLSYMS is usually preferred).

This utility can be downloaded from

<ftp://ftp.<country>.kernel.org/pub/linux/utils/kernel/ksymoops/> .

Alternately you can do the dump lookup by hand:

- In debugging dumps like the above, it helps enormously if you can look up what the EIP value means. The hex value as such doesn't help me or anybody else very much: it will depend on your particular kernel setup. What you should do is take the hex value from the EIP line (ignore the "0010:"), and look it up in the kernel namelist to see which kernel function contains the offending address.

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To find out the kernel function name, you'll need to find the system binary associated with the kernel that exhibited the symptom. This is the file 'linux/vmlinux'. To extract the namelist and match it against the EIP from the kernel crash, do:

```
nm vmlinux | sort | less
```

This will give you a list of kernel addresses sorted in ascending order, from which it is simple to find the function that contains the offending address. Note that the address given by the kernel debugging messages will not necessarily match exactly with the function addresses (in fact, that is very unlikely), so you can't just 'grep' the list: the list will, however, give you the starting point of each kernel function, so by looking for the function that has a starting address lower than the one you are searching for but is followed by a function with a higher address you will find the one you want. In fact, it may be a good idea to include a bit of "context" in your problem report, giving a few lines around the interesting one.

If you for some reason cannot do the above (you have a pre-compiled kernel image or similar), telling me as much about your setup as possible will help. Please read the REPORTING-BUGS document for details.

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- Alternately, you can use gdb on a running kernel. (read-only; i.e. you cannot change values or set break points.) To do this, first compile the kernel with -g; edit arch/i386/Makefile appropriately, then do a "make clean". You'll also need to enable CONFIG\_PROC\_FS (via "make config").

After you've rebooted with the new kernel, do "gdb vmlinux /proc/kcore".

You can now use all the usual gdb commands. The command to look up the point where your system crashed is "l \*0XXXXXXXX". (Replace the XXXes with the EIP value.)

gdb'ing a non-running kernel currently fails because gdb (wrongly) disregards the starting offset for which the kernel is compiled.

---

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### Lsof (v4.85):

lsof (LiSt Open Files) version 4

(revision 4.85)

\*\*\*\*\*

| The latest release of lsof is always available via anonymous ftp |

| from lsof.itap.purdue.edu. Look in pub/tools/unix/lsof. |

\*\*\*\*\*

\*\*\*\*\*

| CHECK THE PATCHES/ SUBDIRECTORY FOR FIXES TO THE LATEST LSOF DISTRIBUTION. |

\*\*\*\*\*

\*\*\*\*\*

| AVOID USING PRE-BUILT LSOF BINARIES: SEE THE "PRE-BUILT LSOF BINARIES" |

| SECTION IN 00README FOR AN EXPLANATION. |

\*\*\*\*\*

\*\*\*\*\*

| READ 00LSOF-L FOR INFORMATION ON THE LSOF-L LISTSERV MAILING LIST. |

\*\*\*\*\*

\*\*\*\*\*

| CHECK 00FAQ BEFORE REPORTING BUGS TO <abe@purdue.edu>. |

| 00FAQ ALSO AT: ftp://lsof.itap.purdue.edu/pub/tools/unix/lsof/FAQ |

\*\*\*\*\*

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\*\*\*\*\*

| IMPORTANT! This README file explains how the lsof tar archive |  
| is assembled -- it's a "wrapper" tar archive. Please read the |  
| explanation of its naming and construction, immediately |  
| following the initial list of supported dialects. |

\*\*\*\*\*

Lsof version 4 lists open files for running UNIX processes. It is a  
descendent of ofiles, fstat, and lsof versions 1, 2, and 3. It has  
been tested recently on these UNIX dialects.

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AIX 5.3

Apple Darwin 9 and Mac OS X 10.[56]

FreeBSD 4.9 and 6.4 for x86-based systems

FreeBSD 8.[02] and 9.0 for AMD64-based systems

Linux 2.1.72 and above for x86-based systems

Solaris 9, 10 and 11

Lsof 4 may work on other versions of these dialects, but hasn't been tested there recently. Lsof versions 2 and 3 are still available and may provide older dialect version support. See the notes on them in this file.

The pub/tools/unix/lsof/contrib directory on [lsof.itap.purdue.edu](http://lsof.itap.purdue.edu) also contains information on other ports.

Version 4 of lsof is distributed as bzip2'd, gzip'd and compressed tar archives in the files:

<ftp://lsof.itap.purdue.edu/pub/tools/unix/lsof/lsof.tar.bz2>

and

<ftp://lsof.itap.purdue.edu/pub/tools/unix/lsof/lsof.tar.gz>

and

<ftp://lsof.itap.purdue.edu/pub/tools/unix/lsof/lsof.tar.Z>

These files are links to the current distribution, whose name includes the revision number:

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`ftp://lsof.itap.purdue.edu/pub/tools/unix/lsof_<rev>.tar.bz2`

and

`ftp://lsof.itap.purdue.edu/pub/tools/unix/lsof_<rev>.tar.gz`

and

`ftp://lsof.itap.purdue.edu/pub/tools/unix/lsof_<rev>.tar.Z`

<rev> is the revision number -- e.g., 4.85. These archives are called wrappers, because the lsof source tar archive, its GPG certificate (lsof\_<rev>\_src.tar.sig), and some documentation files are wrapped together inside them. (The GPG certificate authenticates the source tar archive.) A tar archive with: a ``.bz2" suffix has been compressed with bzip2; ``.gz", with gzip; and ``.Z", with compress.

When the wrapper tar is gunzip'd or uncompressed, and its tar archive contents are extracted, an lsof\_4.85 subdirectory is created in the directory where the extraction was performed. The lsof\_4.85 subdirectory contains these files:

00.README.FIRST            contains introductory distribution information.

README.lsof\_4.85    contains instructions for the security-conscious on how to be sure that no one has tampered with the distribution.

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RELEASE\_SUMMARY\_4.85 is this file.

lsof\_4.85\_src.tar is a tar archive, containing the  
lsof sources. When extracted with  
tar it creates a subdirectory named  
lsof\_4.85\_src in the directory  
where the extraction was performed.  
The lsof source files will be found  
in lsof\_4.85\_src.

lsof\_4.85\_src.tar.sig is a GPG certificate, authenticating  
the lsof\_4.85\_src.tar archive. See the  
README.lsof\_4.85 file for more  
information on GPG authentication of  
lsof\_4.85\_src.tar.

If you've obtained this file and an lsof distribution from a mirror  
site, please be aware that THE LATEST VERSION OF LSOF IS AVAILABLE VIA  
ANONYMOUS FTP FROM LSOF.ITAP.PURDUE.EDU IN THE PUB/TOOLS/UNIX/LSOF  
DIRECTORY.

Patches to lsof distributions may be found in the patches/ sub-  
directory where you found lsof.tar.bz2, lsof.tar.gz or lsof.tar.Z.

If there are any patches to the current distribution, they will be  
found in the patches/4.85/ branch.

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(If you need a copy of gunzip, look for it at [prep.ai.mit.edu](http://prep.ai.mit.edu) in  
`pub/gnu/gzip*`.)

\* The September 27, 2011 revision (4.85): adds an automatic work-around for  
an `lgrp_root` conflict in some Solaris 9 and 10 versions; supports FreeBSD  
7.4 and 8.[12] (8.1 not tested); adds fixes for Solaris 11 kernel module  
path determination; picked lint for Linux; added more Linux cross  
configuration support; adds support for Mac OS X 10.6; tested on FreeBSD  
6.4; adapts to FreeBSD ZFS update; drops support for FreeBSD 7.x; adjusts  
for Solaris 10 with patch 144488-10; added Linux `+|-e` option support;  
adjusts for a FreeBSD 9 change; fixes a Linux `AF_UNIX` path reporting bug;  
adjusts for dropping of RPC headers from Linux Glibc 2.14; adds Linux  
Netlink protocol support; corrects UDP6-lite Linux path.

Read the 00.README.FIRST in the lsof distribution first.

Read the 00DIST distribution file for more details on feature additions  
and bug fixes.

The 00README distribution file has build instructions, dialect  
descriptions, special feature discussions, and installation hints.

The 00FAQ file contains a list of frequently asked questions and their  
answers.

The 00DCACHE file explains device cache file path formation.

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The 00PORTING file contains information on porting lsof to other UNIX dialects.

The 00QUICKSTART file gives a quick introduction to using lsof.

The distribution files lsof.8 (nroff source) and lsof.man (nroff formatted output) contain the manual page for lsof; it is the only other documentation besides the source code (it's included).

### Version 4 Binaries

=====

Version 4 binaries for some revisions, dialects, and platforms may be found in pub/tools/unix/lsof/binaries. Check the README files for exact descriptions. Check the dialect-specific Makefiles for installation instructions. CHECKSUMS and GPG certificates are provided for authentication.

Please think very carefully before you decide to use a pre-built binary instead of making your own from the sources. Here are some points to consider:

1. Lsof must run setgid or setuid. Are you willing to trust that power to a binary you didn't construct yourself?

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2. Lsof binaries may be generated on a system whose configuration header files differ from yours. Under Digital UNIX (DEC OSF/1), for example, lsof includes header files from the machine's configuration directory, /sys/<name>. Are you willing to gamble that your configuration directory's header files match the ones used to compile lsof?

3. Lsof is often configured with specific options that are determined from the configuration of the system on which it is configured -- e.g., Solaris patch level, dynamic loader libraries, etc. Are you sure that the lsof binary you retrieve will have been configured for your system? If you get a binary that is misconfigured for you, it may not work at all.

If you haven't already guessed, I believe firmly that you should retrieve sources and build your own binary. If you still want to use the distribution binaries, please authenticate what you retrieved with the GPG certificates; please compare checksums, too.

### Version 4 Checksums

=====

Security checksums -- both MD5 and sum(1) -- for revisions of lsof version 4 are contained in the README.lsof\_<rev> files in the wrapper tar archives of pub/tools/unix/lsof.

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The CHECKSUMS file, found with the distribution archives, contains information on validating the archives with external MD5 checksums and external GPG certificates.

### GPG Certificates

=====

The lsof wrapper tar archive includes a GPG certificate file in its contained lsof\_4.71\_src.tar.sig file.

Binary files have detached GPG certificates that may be found in their directories with ".sig" extensions.

The certificates are signed with my GPG public key, which may be found in the file:

[ftp://lsof.itap.purdue.edu/pub/tools/unix/lsof/Victor\\_A\\_Abell.gpg](ftp://lsof.itap.purdue.edu/pub/tools/unix/lsof/Victor_A_Abell.gpg)

My key may also be available at some public key servers,

There is also authentication information in the CHECKSUMS file (a link to CHECKSUMS\_<rev>), found with the lsof distribution files. CHECKSUMS contains external MD5 checksums for the distribution files and information on using the external GPG certificates, found with the lsof distribution files.

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### Old Dialect Support

---

Remnants of source code and binaries for dialects for which I so far once provided support may be obtained by request. Send the request to [abe@purdue.edu](mailto:abe@purdue.edu).

Dialects no longer supported include:

CDC EP/IX

MIPS RISC/os

Motorola V/88

Pyramid DC/OSx

Pyramid Reliant UNIX

Sequent DYNIX

SGI IRIX

SunOS 4.1.x

Ultrix

Generally I drop support for a dialect when I no longer have access to a test system.

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Lsof Version 2

=====

The version 3 predecessor, revision 36 of version 2, is also available upon request. Send the request to [abe@purdue.edu](mailto:abe@purdue.edu).

I recommend you avoid lsof version 2. It's out of date and I no longer provide support for it. (Versions 3 and 4 support more dialects, and have many enhancements, bug fixes, and improvements.)

Version 2 was tested on the following UNIX dialects:

AIX 3.2.[1234] for the IBM RISC/System 6000

DEC OSF/1 1.[23] and 2.0 for the DEC Alpha

EP/IX 1.4.3 and 2.1.1 for the CDC 4680

ETAV 1.17 for the ETA-10P\*

FreeBSD 1.0e for x86-based systems

HP-UX [789].x for HP systems

IRIX 4.0.5 and 5.1.1 for SGI systems

NEXTSTEP 2.1, 3.0, 3.1 for NeXT systems

Sequent Dynix 3.0.12 for Sequent Symmetry systems

SunOS 4.1.[123] for Sun 3 and 4 systems

SunOS 5.[13] (Solaris 2.[13]) for Sun 4 systems

Ultrix 2.2 and 4.2 for DEC systems

(If you need a copy of gunzip, look for it at [prep.ai.mit.edu](http://prep.ai.mit.edu) in `pub/gnu`.)

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Version 2 Checksums

=====

MD5:

(OLD/lsof236tar.gz) = f8a1ab3971ea2f6a3ea16752f84409e8

sum(1):

39996 106 OLD/lsof236tar.gz

The file OLD/lsof236tar.gz.asc is a detached PGP certificate that may be used to authenticate OLD/lsof236tar.gz with my PGP public key. You may find my PGP public key at:

[ftp://lsof.itap.purdue.edu/pub/tools/unix/lsof/OLD/Victor\\_A\\_Abell.pgp](ftp://lsof.itap.purdue.edu/pub/tools/unix/lsof/OLD/Victor_A_Abell.pgp)

Lsof Version 3

=====

The last revision of lsof version 3, 3.88, may be obtained by request.

Send the request to [abe@purdue.edu](mailto:abe@purdue.edu).

I recommend version 4 over version 3. It is the version I actively support.

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Lsof version 3 was tested on these UNIX dialects:

AIX 3.2.5, 4.1.[1234], and 4.2

BSDI BSD/OS 2.0, 2.0.1, and 2.1 for x86-based systems

DC/OSx 1.1 for Pyramid systems

Digital UNIX (DEC OSF/1) 2.0, 3.0, 3.2, and 4.0

EP/IX 2.1.1 for the CDC 4680

FreeBSD 1.1.5.1, 2.0, 2.0.5, 2.1, 2.1.5 for x86-based  
systems

HP-UX 8.x, 9.x, 10.01, 10.10, and 10.20

IRIX 5.2, 5.3, 6.0, 6.0.1, and 6.[124]

Linux 2.0.3[01] and 2.1.57 for x86-based systems

NetBSD 1.0, 1.1, and 1.2 for x86 and SPARC-based  
systems

NEXTSTEP 2.1 and 3.[0123] for NEXTSTEP architectures

OpenBSD 1.2 and 2.0 for x86-based systems

Reliant UNIX 5.43 for Pyramid systems

RISC/os 4.52 for MIPS R2000-based systems

SCO OpenServer 1.1, 3.0, and 5.0.[024] for x86-based  
systems

SCO UnixWare 2.1 and 2.1.1 for x86-based systems

Sequent PTX 2.1.[1569], 4.0.[23], 4.1.[024], 4.2[.1],  
and 4.3

Solaris 2.[12345], 2.5.1, and 2.6-Beta

SunOS 4.1.x

Ultrix 4.2, 4.3, 4.4, and 4.5

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Vic Abell <abe@purdue.edu>

September 27, 2011

---

### LibXml2 (v2.7.8):

Except where otherwise noted in the source code (e.g. the files hash.c, list.c and the trio files, which are covered by a similar licence but with different Copyright notices) all the files are:

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---

### Memstat (v0.8):

This is Debian GNU/Linux's prepackaged version of Joshua M. Yelon's memstat, for a long time maintained upstream by Bernd Eckenfels <eck@debian.org> and now maintained by Michael Meskes <meskes@debian.org>.

This package was put together by me, Bernd Eckenfels <eck@debian.org>, from the sources, which I obtained from <http://charm.cs.uiuc.edu/~jyelon/software.html>

The debian/\* Files are based on Ian Jackson's hello Package.

All patches by me are subject to the GPL.

Original Copyright from memstat.c:

\* This software copyright 1997 Joshua M. Yelon.

\* Distribution subject to the terms of the GPL.

On Debian GNU/Linux systems, the complete text of the GNU General Public License can be found in `/usr/share/common-licenses/GPL'.

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### Ncurses (v5.7):

```
-----
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--                                                                    --
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-- without limitation the rights to use, copy, modify, merge, publish, --
-- distribute, distribute with modifications, sublicense, and/or sell copies --
-- of the Software, and to permit persons to whom the Software is furnished --
-- to do so, subject to the following conditions:                      --
--                                                                    --
-- The above copyright notice and this permission notice shall be included --
-- in all copies or substantial portions of the Software.            --
--                                                                    --
-- THE SOFTWARE IS PROVIDED "AS IS", WITHOUT WARRANTY OF ANY KIND, EXPRESS --
-- OR IMPLIED, INCLUDING BUT NOT LIMITED TO THE WARRANTIES OF        --
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-- DAMAGES OR OTHER LIABILITY, WHETHER IN AN ACTION OF CONTRACT, TORT OR --
-- OTHERWISE, ARISING FROM, OUT OF OR IN CONNECTION WITH THE SOFTWARE OR THE --
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--                                                                    --
-- Except as contained in this notice, the name(s) of the above copyright --
-- holders shall not be used in advertising or otherwise to promote the --
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-- authorization.                                                     --
```

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---

-- \$Id: README,v 1.23 2006/04/22 22:19:37 tom Exp \$

---

### README file for the ncurses package

See the file ANNOUNCE for a summary of ncurses features and ports.

See the file INSTALL for instructions on how to build and install ncurses.

See the file NEWS for a release history and bug-fix notes.

See the file TO-DO for things that still need doing, including known bugs.

Browse the file misc/ncurses-intro.html for narrative descriptions of how to use ncurses and the panel, menu, and form libraries.

Browse the file doc/html/hackguide.html for a tour of the package internals.

### ROADMAP AND PACKAGE OVERVIEW:

You should be reading this file in a directory called: ncurses-d.d, where d.d is the current version number (see the dist.mk file in this directory for that). There should be a number of subdirectories, including `c++', `form', `man', `menu', `misc', `ncurses', `panel', `progs', `test', `tack' and `Ada95'. (The `tack' program may be distributed separately).

A full build/install of this package typically installs several libraries, a handful of utilities, and a database hierarchy. Here is an inventory of the pieces:

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The libraries are:

libncurses.a     (normal)  
libncurses.so    (shared)  
libncurses\_g.a   (debug and trace code enabled)  
libncurses\_p.a   (profiling enabled)

libpanel.a       (normal)  
libpanel.so       (shared)  
libpanel\_g.a      (debug and trace code enabled)

libmenu.a        (normal)  
libmenu.so        (shared)  
libmenu\_g.a       (debug enabled)

libform.a        (normal)  
libform.so        (shared)  
libform\_g.a       (debug enabled)

If you configure using the `--enable-widex` option, a "w" is appended to the library names (e.g., `libncursesw.a`), and the resulting libraries support wide-characters, e.g., via a UTF-8 locale. The corresponding header files are compatible with the non-wide-character configuration; wide-character features are provided by `ifdef`'s in the header files. The wide-character library interfaces are not binary-compatible with the non-wide-character version.

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The ncurses libraries implement the curses API. The panel, menu and forms libraries implement clones of the SVr4 panel, menu and forms APIs. The source code for these lives in the ``ncurses'`, ``panel'`, ``menu'`, and ``form'` directories respectively.

In the ``c++'` directory, you'll find code that defines an interface to the curses, forms, menus and panels library packaged as C++ classes, and a demo program in C++ to test it. These class definition modules are not installed by the `'make install.libs'` rule as `libncurses++`.

In the ``Ada95'` directory, you'll find code and documentation for an Ada95 binding of the curses API, to be used with the GNAT compiler. This binding is built by a normal top-level `'make'` if configure detects an usable version of GNAT (3.11 or above). It is not installed automatically. See the Ada95 directory for more build and installation instructions and for documentation of the binding.

To do its job, the ncurses code needs your terminal type to be set in the environment variable `TERM` (normally set by your OS; under UNIX, `getty(1)` typically does this, but you can override it in your `.profile`); and, it needs a database of terminal descriptions in which to look up your terminal type's capabilities.

In older (V7/BSD) versions of curses, the database was a flat text file, `/etc/termcap`; in newer (USG/USL) versions, the database is a hierarchy of fast-loading binary description blocks under `/usr/lib/terminfo`. These binary blocks are compiled from an improved editable text representation called

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`terminfo' format (documented in man/terminfo.5). The ncurses library can use either /etc/termcap or the compiled binary terminfo blocks, but prefers the second form.

In the `misc' directory, there is a text file terminfo.src, in editable terminfo format, which can be used to generate the terminfo binaries (that's what make install.data does). If the package was built with the --enable-termcap option enabled, and the ncurses library cannot find a terminfo description for your terminal, it will fall back to the termcap file supplied with your system (which the ncurses package installation leaves strictly alone).

The utilities are as follows:

|         |                                                    |
|---------|----------------------------------------------------|
| tic     | -- terminfo source to binary compiler              |
| infocmp | -- terminfo binary to source decompiler/comparator |
| clear   | -- emits clear-screen for current terminal         |
| tput    | -- shell-script access to terminal capabilities.   |
| toe     | -- table of entries utility                        |
| tset    | -- terminal-initialization utility                 |

The first two (tic and infocmp) are used for manipulating terminfo descriptions; the next two (clear and tput) are for use in shell scripts. The last (tset) is provided for 4.4BSD compatibility. The source code for all of these lives in the `progs' directory.

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Detailed documentation for all libraries and utilities can be found in the  
`man' and `doc' directories. An HTML introduction to ncurses, panels, and  
menus programming lives in the `doc/html' directory. Manpages in HTML format  
are under `doc/html/man'.

The `test' directory contains programs that can be used to verify or  
demonstrate the functions of the ncurses libraries. See test/README for  
descriptions of these programs. Notably, the `ncurses' utility is designed to  
help you systematically exercise the library functions.

### AUTHORS:

Pavel Curtis:

wrote the original ncurses

Zeyd M. Ben-Halim:

port of original to Linux and many enhancements.

Thomas Dickey (maintainer for 1.9.9g through 4.1, resuming with FSF's 5.0):

configuration scripts, porting, mods to adhere to XSI Curses in the  
areas of background color, terminal modes. Also memory leak testing,  
the wresize, default colors and key definition extensions and numerous  
bug fixes (more than half of those enumerated in NEWS beginning with  
the internal release 1.8.9).

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Florian La Roche (official maintainer for FSF's ncurses 4.2)

Beginning with release 4.2, ncurses is distributed under an MIT-style license.

Eric S. Raymond:

the man pages, infocmp(1), tput(1), clear(1), captinfo(1), tset(1), toe(1), most of tic(1), trace levels, the HTML intro, wgetnstr() and many other entry points, the cursor-movement optimization, the scroll-pack optimizer for vertical motions, the mouse interface and xterm mouse support, and the ncurses test program.

Juergen Pfeifer

The menu and form libraries, C++ bindings for ncurses, menus, forms and panels, as well as the Ada95 binding. Ongoing support for panel.

### CONTRIBUTORS:

Alexander V. Lukyanov

for numerous fixes and improvements to the optimization logic.

David MacKenzie

for first-class bug-chasing and methodical testing.

Ross Ridge

for the code that hacks termcap parameterized strings into terminfo.

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Warren Tucker and Gerhard Fuernkranz,

for writing and sending the panel library.

Hellmuth Michaelis,

for many patches and testing the optimization code.

Eric Newton, Ulrich Drepper, and Anatoly Ivasyuk:

the C++ code.

Jonathan Ross,

for lessons in using sed.

Keith Bostic (maintainer of 4.4BSD curses)

for help, criticism, comments, bug-finding, and being willing to  
deep-six BSD curses for this one when it grew up.

Richard Stallman,

for his commitment to making ncurses free software.

Countless other people have contributed by reporting bugs, sending fixes,  
suggesting improvements, and generally whining about ncurses :-)

### BUGS:

See the INSTALL file for bug and developer-list addresses.

The Hacker's Guide in the doc directory includes some guidelines  
on how to report bugs in ways that will get them fixed most quickly.

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### OpenSSL (v1.0.1g):

#### LICENSE ISSUES

=====

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#### OpenSSL License

-----

```
/* =====  
  
* Copyright (c) 1998-2011 The OpenSSL Project. All rights reserved.  
  
*  
  
* Redistribution and use in source and binary forms, with or without  
* modification, are permitted provided that the following conditions  
* are met:  
  
*  
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* notice, this list of conditions and the following disclaimer.  
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* 2. Redistributions in binary form must reproduce the above copyright  
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* software must display the following acknowledgment:  
* "This product includes software developed by the OpenSSL Project  
* for use in the OpenSSL Toolkit. (http://www.openssl.org/)"
```

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\* =====

\*

\* This product includes cryptographic software written by Eric Young

\* (eay@cryptsoft.com). This product includes software written by Tim

\* Hudson (tjh@cryptsoft.com).

\*

\*/

Original SSLeay License

-----

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\* All rights reserved.

\*

\* This package is an SSL implementation written

\* by Eric Young (eay@cryptsoft.com).

\* The implementation was written so as to conform with Netscapes SSL.

\*

\* This library is free for commercial and non-commercial use as long as

\* the following conditions are aheared to. The following conditions

\* apply to all code found in this distribution, be it the RC4, RSA,

\* lhash, DES, etc., code; not just the SSL code. The SSL documentation

\* included with this distribution is covered by the same copyright terms

\* except that the holder is Tim Hudson (tjh@cryptsoft.com).

\*

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- \* as the author of the parts of the library used.
- \* This can be in the form of a textual message at program startup or
- \* in documentation (online or textual) provided with the package.
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- \*/

---

### Pcre (v8.30):

#### PCRE LICENCE

-----

PCRE is a library of functions to support regular expressions whose syntax and semantics are as close as possible to those of the Perl 5 language.

Release 8 of PCRE is distributed under the terms of the "BSD" licence, as specified below. The documentation for PCRE, supplied in the "doc" directory, is distributed under the same terms as the software itself.

The basic library functions are written in C and are freestanding. Also included in the distribution is a set of C++ wrapper functions, and a just-in-time compiler that can be used to optimize pattern matching. These are both optional features that can be omitted when the library is built.

#### THE BASIC LIBRARY FUNCTIONS

-----

Written by: Philip Hazel

Email local part: ph10

Email domain: cam.ac.uk

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University of Cambridge Computing Service,

Cambridge, England.

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### PCRE JUST-IN-TIME COMPILATION SUPPORT

-----

Written by: Zoltan Herczeg

Email local part: hzmester

Email domain: freemail.hu

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### STACK-LESS JUST-IN-TIME COMPILER

-----

Written by: Zoltan Herczeg

Email local part: hzmester

Email domain: freemail.hu

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### THE C++ WRAPPER FUNCTIONS

-----

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### Popt (v1.16):

This is the popt(3) command line option parsing library. While it is similar to getopt(3), it contains a number of enhancements, including:

- 1) popt is fully reentrant
- 2) popt can parse arbitrary argv[] style arrays while  
getopt(3) makes this quite difficult
- 3) popt allows users to alias command line arguments
- 4) popt provides convenience functions for parsing strings  
into argv[] style arrays

Complete documentation on popt(3) is available in popt.ps (included in this tarball), which is excerpted with permission from the book "Linux Application Development" by Michael K. Johnson and Erik Troan (available from Addison Wesley in May, 1998).

Comments on popt should be addressed to [popt-devel@rpm5.org](mailto:popt-devel@rpm5.org).

---

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### ROM-Bootloader:

Boot strategies

AT91 chips embed a boot ROM code. It is enabled depending on BMS (Boot Mode Select) pin state on reset.

The ROM code scans the contents of different media like serial FLASH, NAND FLASH, SD/MMC Card and serial EEPROM.

If a valid application is available then it downloads this application into the chip internal SRAM and runs it.

To determine if a valid application is present the ROM code checks the eight ARM exception vectors.

If no valid application is available then SAM-BA Monitor is executed. It waits for transactions either on the USB device, or on the DBGU serial port, then the SAM-BA tool can be used to program FLASH or EEPROM present on your board.

For more information on this topic, please check the corresponding SAM product datasheet section Boot Strategies.

---

### GNU Tar (v1.17):

README for GNU tar

See the end of file for copying conditions.

\* Introduction

Please glance through \*all\* sections of this

'README' file before starting configuration. Also make sure you read files

'ABOUT-NLS' and 'INSTALL' if you are not familiar with them already.

If you got the 'tar' distribution in 'shar' format, time stamps ought to be

properly restored; do not ignore such complaints at 'unshar' time.

GNU 'tar' saves many files together into a single tape or disk

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archive, and can restore individual files from the archive. It includes multivolume support, the ability to archive sparse files, automatic archive compression/decompression, remote archives and special features that allow 'tar' to be used for incremental and full backups. This distribution also includes 'rmt', the remote tape server. The 'mt' tape drive control program is in the GNU 'cpio' distribution.

GNU 'tar' is derived from John Gilmore's public domain 'tar'.

See file 'ABOUT-NLS' for how to customize this program to your language.

See file 'COPYING' for copying conditions.

See file 'INSTALL' for compilation and installation instructions.

See file 'PORTS' for various ports of GNU tar to non-Unix systems.

See file 'NEWS' for a list of major changes in the current release.

See file 'THANKS' for a list of contributors.

Besides those configure options documented in files 'INSTALL' and 'ABOUT-NLS', an extra option may be accepted after './configure':

\* Install

\*\* Selecting the default archive format.

The default archive format is GNU, this can be overridden by presetting `DEFAULT_ARCHIVE_FORMAT` while configuring. The allowed values are GNU, V7, OLDGNU, USTAR and POSIX.

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**\*\* Selecting the default archive device**

The default archive device is now 'stdin' on read and 'stdout' on write.

The installer can still override this by presetting 'DEFAULT\_ARCHIVE'

in the environment before configuring (the behavior of '-[0-7]' or

'-[0-7]lmh' options in 'tar' are then derived automatically). Similarly,

'DEFAULT\_BLOCKING' can be preset to something else than 20.

**\*\* Selecting full pathname of the "rmt" binary.**

Previous versions of tar always looked for "rmt" binary in the

directory "/etc/rmt". However, the "rmt" program included

in the distribution was installed under "\$prefix/libexec/rmt".

To fix this discrepancy, tar now looks for "\$prefix/libexec/rmt".

If you do not want this behavior, specify full path name of

"rmt" binary using DEFAULT\_RMT\_DIR variable, e.g.:

```
./configure DEFAULT_RMT_DIR=/etc
```

If you already have a copy of "rmt" installed and wish to use it

instead of the version supplied with the distribution, use --with-rmt

option:

```
./configure --with-rmt=/etc/rmt
```

This will also disable building the included version of rmt.

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**\*\* Installing backup scripts.**

This version of tar is shipped with the shell scripts for producing incremental backups (dumps) and restoring filesystems from them.

The name of the backup script is "backup". The name of the restore script is "restore". They are installed in "\$prefix/sbin" directory.

Use option --enable-backup-scripts to compile and install these scripts.

**\*\* '--disable-largefile'** omits support for large files, even if the operating system supports large files. Typically, large files are those larger than 2 GB on a 32-bit host.

**\* Installation hints**

Here are a few hints which might help installing 'tar' on some systems.

**\*\* gzip and bzip2.**

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GNU tar uses the gzip and bzip2 programs to read and write compressed archives. If you don't have these programs already, you need to install them. Their sources can be found at:

<ftp://ftp.gnu.org/gnu/gzip/>

<http://sourceware.cygnus.com/bzip2/>

If you see the following symptoms:

```
$ tar -xzf file.tar.gz
```

```
gzip: stdin: decompression OK, trailing garbage ignored
```

```
tar: Child returned status 2
```

then you have encountered a gzip incompatibility that should be fixed

in gzip test version 1.3, which as of this writing is available at

[<ftp://alpha.gnu.org/gnu/gzip/>](ftp://alpha.gnu.org/gnu/gzip/). You can work around the

incompatibility by using a shell command like

```
'gzip -d <file.tar.gz | tar -xzf -'.
```

**\*\* Solaris issues.**

GNU tar exercises many features that can cause problems with older GCC

versions. In particular, GCC 2.8.1 (sparc, -O1 or -O2) is known to

miscompile GNU tar. No compiler-related problems have been reported

when using GCC 2.95.2 or later.

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Recent versions of Solaris tar sport a new -E option to generate extended headers in an undocumented format. GNU tar does not understand these headers.

**\*\* Static linking.**

Some platform will, by default, prepare a smaller 'tar' executable which depends on shared libraries. Since GNU 'tar' may be used for system-level backups and disaster recovery, installers might prefer to force static linking, making a bigger 'tar' executable maybe, but able to work standalone, in situations where shared libraries are not available. The way to achieve static linking varies between systems. Set LDFLAGS to a value from the table below, before configuration (see 'INSTALL').

| Platform  | Compiler | LDFLAGS                     |
|-----------|----------|-----------------------------|
| (any)     | Gnu C    | -static                     |
| AIX       | (vendor) | -bnso -bI:/lib/syscalls.exp |
| HPUX      | (vendor) | -Wl,-a,archive              |
| IRIX      | (vendor) | -non_shared                 |
| OSF       | (vendor) | -non_shared                 |
| SCO 3.2v5 | (vendor) | -dn                         |
| Solaris   | (vendor) | -Bstatic                    |
| SunOS     | (vendor) | -Bstatic                    |

**\*\* Failed tests 'ignfail.sh' or 'incremen.sh'.**

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In an NFS environment, lack of synchronization between machine clocks might create difficulties to any tool comparing dates and file time stamps, like 'tar' in incremental dumps. This has been a recurrent problem with GNU Make for the last few years. We would like a general solution.

**\*\* BSD compatibility matters.**

Set LIBS to '-lbsd' before configuration (see 'INSTALL') if the linker complains about 'bsd\_ioctl' (Slackware). Also set CPPFLAGS to '-I/usr/include/bsd' if <sgtty.h> is not found (Slackware).

**\*\* OPENStep 4.2 swap files**

Tar cannot read the file /private/vm/swapfile.front (even as root).

This file is not a real file, but some kind of uncompressed view of the real compressed swap file; there is no reason to back it up, so the simplest workaround is to avoid tarring this file.

**\* Special topics**

Here are a few special matters about GNU 'tar', not related to build matters. See previous section for such.

**\*\* File attributes.**

About *\*security\**, it is probable that future releases of 'tar' will have some behavior changed. There are many pending suggestions to choose from.

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Today, extracting an archive not being 'root', 'tar' will restore suid/sgid bits on files but owned by the extracting user. 'root' automatically gets a lot of special privileges, '-p' might later become required to get them.

GNU 'tar' does not properly restore symlink attributes. Various systems implement flavors of symbolic links showing different behavior and properties. We did not successfully sorted all these out yet. Currently, the 'lchown' call will be used if available, but that's all.

\*\* POSIX compliance.

GNU 'tar' is able to create archive in the following formats:

\*\*\* The format of UNIX version 7

\*\*\* POSIX.1-1988 format, also known as "ustar format"

\*\*\* POSIX.1-2001 format, also known as "pax format"

\*\*\* Old GNU format (described below)

In addition to those, GNU 'tar' is also able to read archives produced by 'star' archiver.

A so called 'Old GNU' format is based on an early draft of the POSIX 1003.1 'ustar' standard which is different from the final standard. It defines its extensions (such as incremental backups and handling of the long file names) in a way incompatible with any existing tar archive format, therefore the use of old GNU format is strongly discouraged.

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Please read the file NEWS for more information about POSIX compliance and new 'tar' features.

\* What's next?

GNU tar will be merged into GNU paxutils: a project containing several utilities related to creating and handling archives in various formats. The project will include tar, cpio and pax utilities.

\* Bug reporting.

Send bug reports to <bug-tar@gnu.org>. A bug report should contain an adequate description of the problem, your input, what you expected, what you got, and why this is wrong. Diffs are welcome, but they only describe a solution, from which the problem might be uneasy to infer.

If needed, submit actual data files with your report. Small data files are preferred. Big files may sometimes be necessary, but do not send them to the report address; rather take special arrangement with the maintainer.

Your feedback will help us to make a better and more portable package.

Consider documentation errors as bugs, and report them as such. If you develop anything pertaining to 'tar' or have suggestions, let us know and share your findings by writing to <bug-tar@gnu.org>.

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\* Copying

Copyright 1990-1992, 1994, 1997-2001, 2003-2004, 2007, 2012-2013 Free  
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### NOTE ON COPYRIGHT YEARS

In copyright notices where the copyright holder is the Free Software Foundation, then where a range of years appears, this is an inclusive range that applies to every year in the range. For example: 2005-2008 represents the years 2005, 2006, 2007, and 2008.

Local Variables:

mode: outline

paragraph-separate: "[]\*\$"

version-control: never

End:

---

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### u-boot (v2010.09):

U-Boot is Free Software. It is copyrighted by Wolfgang Denk and many others who contributed code (see the actual source code and the git commit messages for details). You can redistribute U-Boot and/or modify it under the terms of version 2 of the GNU General Public License as published by the Free Software Foundation. Most of it can also be distributed, at your option, under any later version of the GNU General Public License -- see individual files for exceptions.

NOTE! This license does not cover the so-called "standalone" applications that use U-Boot services by means of the jump table provided by U-Boot exactly for this purpose - this is merely considered normal use of U-Boot, and does not fall under the heading of "derived work" -- see file Licenses/Exceptions for details.

Also note that the GPL and the other licenses are copyrighted by the Free Software Foundation and other organizations, but the instance of code that they refer to (the U-Boot source code) is copyrighted by me and others who actually wrote it.

-- Wolfgang Denk

Like many other projects, U-Boot had a tradition of including big blocks of License headers in all files. This not only blew up the source code with mostly redundant information, but also made it very difficult to generate License Clearing Reports. An additional problem was that even the same licenses were referred to by a number of slightly varying text blocks (full, abbreviated, different indentation, line wrapping and/or white space, with obsolete address information, ...) which made automatic processing a nightmare.

To make this easier, such license headers in the source files have been replaced with a single line reference to Unique License Identifiers as defined by the Linux Foundation's SPDX project [1]. For example, in a source file the full "GPL v2.0 or later" header text was replaced by a single line:

SPDX-License-Identifier:     GPL-2.0+

We use the SPDX Unique License Identifiers here; these are available at [2].

[1] <http://spdx.org/>

[2] <http://spdx.org/licenses/>

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### uClibc (v0.9.31.1):

A C library for embedded Linux

uClibc (aka  $\mu$ Clibc/pronounced yew-see-lib-see) is a C library for developing embedded Linux systems. It is much smaller than the GNU C Library, but nearly all applications supported by glibc also work perfectly with uClibc. Porting applications from glibc to uClibc typically involves just recompiling the source code. uClibc even supports shared libraries and threading. It currently runs on standard Linux and MMU-less (also known as  $\mu$ Clinux) systems with support for alpha, amd64, ARM, Blackfin, cris, h8300, hppa, i386, i960, ia64, m68k, mips/mipsel, PowerPC, SH, SPARC, and v850 processors.

If you are building an embedded Linux system and you find that glibc is eating up too much space, you may want to consider using uClibc. If you are building a huge fileserver with 12 Terabytes of storage, then using glibc may make more sense. Unless, for example, that 12 Terabytes will be Network Attached Storage and you plan to burn Linux into the system's firmware...

uClibc is maintained by Erik Andersen and is licensed under the GNU LESSER GENERAL PUBLIC LICENSE . This license allows you to make closed source commercial applications using uClibc. (Please consider sharing some of the money you make ;-). You do not need to give away all your source code just because you use uClibc and/or run on Linux. See the list of Frequently Asked Questions for details.

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Do you like uClibc? Do you need support? Do you need some features added? Then why not help out? We are happy to accept donations (such as bandwidth, mirrors sites, and hardware for the various architectures). We can also provide support contracts, and implement funded feature requests. To contribute, you can either click on the Donate image to donate using PayPal, or you can contact Erik at CodePoet Consulting (we have a credit card machine so you can avoid PayPal if you wish).

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### Udev (v058):

udev - a userspace implementation of devfs

For more information on the design, and structure of this project, see the files in the docs/ directory.

To use:

- You must be running a 2.6 version of the Linux kernel.
- Your 2.6 kernel must have had CONFIG\_HOTPLUG enabled when it was built.
- Make sure sysfs is mounted. udev will figure out where sysfs is mounted, but the traditional place for it is at /sys. You can mount it by hand by running:

```
mount -t sysfs none /sys
```

- Make sure you have the latest version of the linux-hotplug scripts. They are available at [linux-hotplug.sf.net](http://linux-hotplug.sf.net) or from your local kernel.org mirror at:

```
kernel.org/pub/linux/utils/kernel/hotplug/
```

They are required in order for udev to work properly.

If for some reason you do not install the hotplug scripts, you must tell the kernel to point the hotplug binary at wherever you install udev at. This can be done by:

```
echo "/sbin/udev" > /proc/sys/kernel/hotplug
```

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- Build the project:

```
make
```

Note:

There are a number of different flags that you can use when building udev. They are as follows:

`prefix`

set this to the default root that you want udev to be installed into. This works just like the 'configure --prefix' script does. Default value is ". Only override this if you really know what you are doing.

`USE_KLIBC`

if set to 'true', udev is built and linked against the included version of klibc. Default value is 'false'.

`USE_LOG`

if set to 'true', udev will emit messages to the syslog when it creates or removes device nodes. This is helpful to see what udev is doing. This is enabled by default. Note, if you are building udev against klibc it is recommended that you disable this option (due to klibc's syslog implementation.)

`USE_SELINUX`

if set to 'true', udev will be built with SELinux support enabled. This is disabled by default.

`DEBUG`

if set to 'true', debugging messages will be sent to the syslog as udev is run. Default value is 'false'.

`KERNEL_DIR`

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If this is not set it will default to `/lib/modules/`uname -r`/build`

This is used if `USE_KLIBC=true` to find the kernel include

directory that klibc needs to build against. This must be set

if you are not building udev while running a 2.6 kernel.

So, if you want to build udev using klibc with debugging messages, you would do:

```
make USE_KLIBC=true DEBUG=true
```

- Install the project:

```
make install
```

This will put the udev binary in `/sbin`, create the `/udev` and `/etc/udev` directories, and place the udev configuration files in `/etc/udev`. You will probably want to edit the `*.rules` files to create custom naming rules. More info on how the config files are set up are contained in comments in the files, and is located in the documentation.

- Add and remove devices from the system and marvel as nodes are created and removed in `/udev/` based on the device types.

- If you later get sick of it, uninstall it:

```
make uninstall
```

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Things are still quite rough, but it should work properly. If nothing seems to happen, make sure your build worked properly by running the udev-test.pl script as root in the test/ subdirectory of the udev source tree.

Development and documentation help is very much appreciated, see the TODO file for a list of things left to be done.

Any comment/questions/concerns please let me and the other udev developers know by sending a message to the linux-hotplug-devel mailing list at:

`linux-hotplug-devel@lists.sourceforge.net`

greg k-h

`greg@kroah.com`

---

### Util-Linux (v2.20.1):

util-linux

util-linux is a random collection of Linux utilities

Note that in years 2006-2010 this project used the name "util-linux-ng".

WEB PAGE:

<http://kernel.org/~kzak/util-linux/>

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### MAILING LIST:

E-MAIL: [util-linux@vger.kernel.org](mailto:util-linux@vger.kernel.org)

URL: <http://vger.kernel.org/vger-lists.html#util-linux>

### DOWNLOAD:

<ftp://ftp.kernel.org/pub/linux/utils/util-linux/>

### SOURCE CODE:

Web interface:

<http://git.kernel.org/?p=utils/util-linux/util-linux.git>

Checkout:

```
git clone git://git.kernel.org/pub/scm/utils/util-linux/util-linux.git util-linux
```

### NLS (PO TRANSLATIONS):

PO files are maintained by:

<http://translationproject.org/domain/util-linux-ng.html>

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### NEUTRALITY:

The stuff in util-linux should be rather distribution-neutral.

No RPMs/DEBs/... are provided - get yours from your distributor.

### VERSION SCHEMA:

Standard releases:

`<major>.<minor>[.<maint>[.<bugfix>]]`

major = fatal and deep changes

minor = typical release with new features

maint = maintenance releases; bug fixes only

bugfix = unplanned releases for critical/security bugs

Development releases:

`<major>.<minor>-rc<N>`

### COMPILATION:

See the INSTALL file for more details.

Notes:

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\* use SUID\_CFLAGS and SUID\_LDFLAGS when you want to define special compiler options for typical suid programs, for example:

```
./configure SUID_CFLAGS="-fpie" SUID_LDFLAGS="-pie"
```

This feature is currently supported for chfn, chsh, newgrp, write, mount, and umount.

### STATIC LINKING:

Use `--enable-static-programs[=LIST]` configure option when you want to use statically linked programs.

Note, `mount(8)` uses `get{pw,gr}nam()` and `getpwuid()` functions for translation from username and groupname to UID and GID. These functions could be implemented by dynamically loaded independent modules (NSS) in your libc (e.g. glibc). These modules are not statically linked to `mount(8)` and `mount.static` is still using `dlopen()` like dynamically linked version.

The translation won't work in environment where NSS modules are not installed.

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For example normal system (NSS modules are available):

```
# ./mount.static -v -f -n -oid=kzak /mnt/foo
```

```
LABEL=/mnt/foo on /mnt/foo type vfat (rw,uid=500)
```

^^^^^^

and without NSS modules:

```
# chroot . ./mount.static -v -f -n -oid=kzak /mnt/win
```

```
LABEL=/mnt/win on /mnt/win type vfat (rw,uid=kzak)
```

^^^^^^

---

### XML-RPC++ (v0.7):

```
#ifndef _XMLRPC_H_
```

```
#define _XMLRPC_H_
```

```
//
```

```
// XmlRpc++ Copyright (c) 2002-2003 by Chris Morley
```

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//
```

```
/* changed by ise GmbH 2013 */
```

```
#if defined(_MSC_VER)  
# pragma warning(disable:4786) // identifier was truncated in debug info  
#endif
```

```
#ifndef MAKEDEPEND  
# include <string>  
#endif
```

```
#include "dllexport.h"  
#include "XmlRpcClient.h"  
#include "XmlRpcException.h"  
#include "XmlRpcServer.h"  
#include "XmlRpcServerProxy.h"  
#include "XmlRpcServerMethod.h"  
#include "XmlRpcValue.h"  
#include "XmlRpcUtil.h"
```

```
namespace XmlRpc {
```

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//! An interface allowing custom handling of error message reporting.

```
class XMLRPC_DLLEXPORT XmlRpcErrorHandler {
```

```
public:
```

//! Returns a pointer to the currently installed error handling object.

```
static XmlRpcErrorHandler* getErrorHandler()
```

```
{ return _errorHandler; }
```

//! Specifies the error handler.

```
static void setErrorHandler(XmlRpcErrorHandler* eh)
```

```
{ _errorHandler = eh; }
```

//! Report an error. Custom error handlers should define this method.

```
virtual void error(const char* msg) = 0;
```

//! Define virtual destructor to avoid compiler warnings

```
virtual ~XmlRpcErrorHandler(){};
```

```
protected:
```

```
static XmlRpcErrorHandler* _errorHandler;
```

```
};
```

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//! An interface allowing custom handling of informational message reporting.

```
class XMLRPC_DLLEXPORT XmlRpcLogHandler {
```

```
public:
```

//! Returns a pointer to the currently installed message reporting object.

```
static XmlRpcLogHandler* getLogHandler()
```

```
{ return _logHandler; }
```

//! Specifies the message handler.

```
static void setLogHandler(XmlRpcLogHandler* lh)
```

```
{ _logHandler = lh; }
```

//! Returns the level of verbosity of informational messages. 0 is no output, 5 is very verbose.

```
static int getVerbosity()
```

```
{ return _verbosity; }
```

//! Specify the level of verbosity of informational messages. 0 is no output, 5 is very verbose.

```
static void setVerbosity(int v)
```

```
{ _verbosity = v; }
```

//! Output a message. Custom error handlers should define this method.

```
virtual void log(int level, const char* msg) = 0;
```

//! Define virtual destructor to avoid compiler warnings

```
virtual ~XmlRpcLogHandler(){};
```

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protected:

```
static XmlRpcLogHandler* _logHandler;

static int _verbosity;

};

//! Returns log message verbosity. This is short for XmlRpcLogHandler::getVerbosity()

int XMLRPC_DLLEXPORT getVerbosity();

//! Sets log message verbosity. This is short for XmlRpcLogHandler::setVerbosity(level)

void XMLRPC_DLLEXPORT setVerbosity(int level);

//! Version identifier

extern const char XMLRPC_VERSION[];

} // namespace XmlRpc

#endif // _XMLRPC_H_
```

---

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### Zlib (v1.2.6):

#### ZLIB DATA COMPRESSION LIBRARY

zlib 1.2.6 is a general purpose data compression library. All the code is thread safe. The data format used by the zlib library is described by RFCs (Request for Comments) 1950 to 1952 in the files <http://tools.ietf.org/html/rfc1950> (zlib format), rfc1951 (deflate format) and rfc1952 (gzip format).

All functions of the compression library are documented in the file `zlib.h` (volunteer to write man pages welcome, contact [zlib@gzip.org](mailto:zlib@gzip.org)). A usage example of the library is given in the file `test/example.c` which also tests that the library is working correctly. Another example is given in the file `test/minigzip.c`. The compression library itself is composed of all source files in the root directory.

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To compile all files and run the test program, follow the instructions given at the top of Makefile.in. In short `./configure; make test`, and if that goes well, `make install` should work for most flavors of Unix. For Windows, use one of the special makefiles in `win32/` or `contrib/vstudio/`. For VMS, use `make_vms.com`.

Questions about zlib should be sent to [<zlib@gzip.org>](mailto:zlib@gzip.org), or to Gilles Vollant [<info@winimage.com>](mailto:info@winimage.com) for the Windows DLL version. The zlib home page is <http://zlib.net/>. Before reporting a problem, please check this site to verify that you have the latest version of zlib; otherwise get the latest version and check whether the problem still exists or not.

PLEASE read the zlib FAQ [http://zlib.net/zlib\\_faq.html](http://zlib.net/zlib_faq.html) before asking for help.

Mark Nelson [<markn@ieee.org>](mailto:markn@ieee.org) wrote an article about zlib for the Jan. 1997 issue of Dr. Dobbs's Journal; a copy of the article is available at <http://marknelson.us/1997/01/01/zlib-engine/>.

The changes made in version 1.2.6 are documented in the file `ChangeLog`.

Unsupported third party contributions are provided in directory `contrib/`.

zlib is available in Java using the `java.util.zip` package, documented at <http://java.sun.com/developer/technicalArticles/Programming/compression/>.

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A Perl interface to zlib written by Paul Marquess <pmqs@cpan.org> is available at CPAN (Comprehensive Perl Archive Network) sites, including <http://search.cpan.org/~pmqs/IO-Compress-Zlib/> .

A Python interface to zlib written by A.M. Kuchling <amk@amk.ca> is available in Python 1.5 and later versions, see <http://docs.python.org/library/zlib.html> .

zlib is built into tcl: <http://wiki.tcl.tk/4610> .

An experimental package to read and write files in .zip format, written on top of zlib by Gilles Vollant <info@winimage.com>, is available in the contrib/minizip directory of zlib.

Notes for some targets:

- For Windows DLL versions, please see win32/DLL\_FAQ.txt
- For 64-bit Irix, deflate.c must be compiled without any optimization. With -O, one libpng test fails. The test works in 32 bit mode (with the -n32 compiler flag). The compiler bug has been reported to SGI.
- zlib doesn't work with gcc 2.6.3 on a DEC 3000/300LX under OSF/1 2.1 it works when compiled with cc.

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- On Digital Unix 4.0D (formerly OSF/1) on AlphaServer, the cc option -std1 is necessary to get gzprintf working correctly. This is done by configure.
- zlib doesn't work on HP-UX 9.05 with some versions of /bin/cc. It works with other compilers. Use "make test" to check your compiler.
- gzopen is not supported on RISCOS or BEOS.
- For PalmOs, see <http://palmzlib.sourceforge.net/>

### Acknowledgments:

The deflate format used by zlib was defined by Phil Katz. The deflate and zlib specifications were written by L. Peter Deutsch. Thanks to all the people who reported problems and suggested various improvements in zlib; they are too numerous to cite here.

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Jean-loup Gailly      Mark Adler  
jloup@gzip.org      madler@alumni.caltech.edu

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(For example, a function in a library to compute square roots has a purpose that is entirely well-defined independent of the application. Therefore, Subsection 2d requires that any application-supplied function or table used by this function must be optional: if the application does not supply it, the square root function must still compute square roots.)

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(For example, a function in a library to compute square roots has a purpose that is entirely well-defined independent of the application. Therefore, Subsection 2d requires that any application-supplied function or table used by this function must be optional: if the application does not supply it, the square root function must still compute square roots.)

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### **GCC Runtime Library Exception (RLE), Version 3.1**

#### **GCC RUNTIME LIBRARY EXCEPTION**

Version 3.1, 31 March 2009

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