Catalog | September 2026

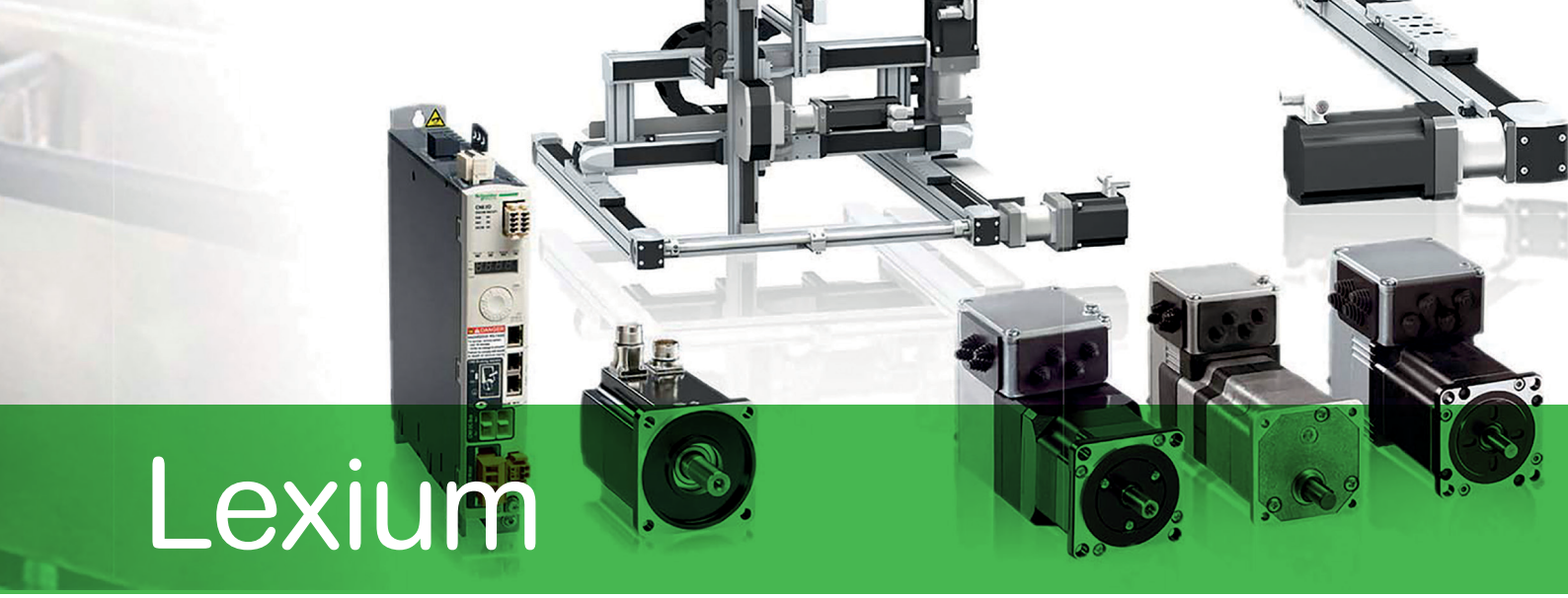


Lexium 26

Servo drives and servo motors for simple machines

www.se.com

Schneider Electric



Lexium

Discover Lexium

Advanced motion control and robotics

Lexium servo drives, motors, and robotics series are designed for a broad range of motion-centric machines. From single-axis to high-performance multi-axis machines, the **Lexium** range enables high-speed movements and precise positioning in packaging, material handling, material working, electronics, and food and beverage applications.

Explore our offer

- Lexium Servo Drives and Motors
- Lexium Integrated Servo Drives
- Lexium Robotics
- Lexium Stepper Drives

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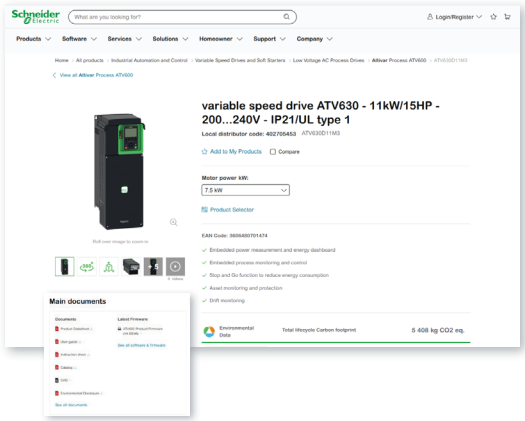


Quick access to product information

Get technical information about your product

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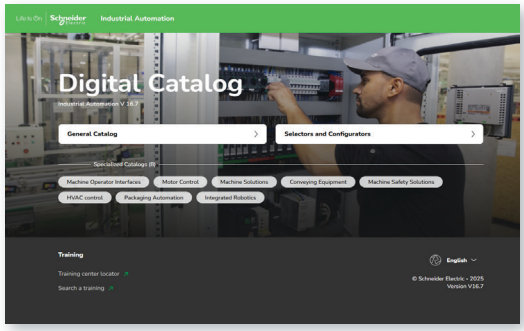
- Characteristics, Dimensions and drawings, Mounting and clearance, Connections and schemas, Performance curves
- Instruction sheets, User guides, Product certifications, End of life manuals, etc



View the Automation Catalog libraries

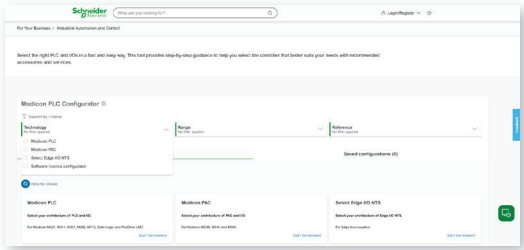
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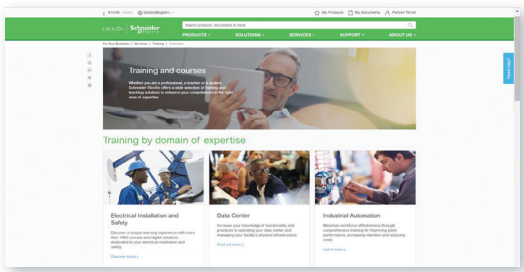
Direct access to Configurators Home pages

- Configure your motor control and protection solution
- Configure your control system with a PLC controller and I/O modules
- Configure your motion control and robotics system



Select your training

- Find the right Training for your needs on our Global website
- Locate the Training center with the selector tool



Schneider Electric

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Lexium 26

Lexium™ 26 servo drives and BCH2 servo motors

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Lexium 26

Lexium™ 26 servo drives and BCH2 servo motors

Introduction, applications



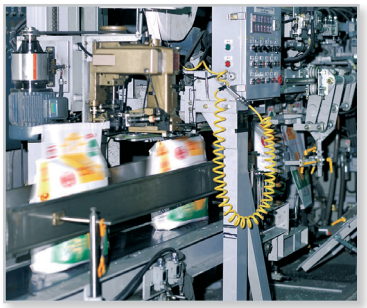
Lexium 26 servo drive + servo motor (example)



Material working application



Material handling application



Packaging application



Textile application



SoMove setup software



Multi-Loader tool

Introduction

The Lexium™ 26 range is defined by AC-servo drives Lexium 26 for combination with AC-servo motors BCH2 according to customer's application.

■ The Lexium 26 range offers predefined combinations to suit the requirements of motion control applications and optimize the installation's performance.

□ The combinations of servo motors with servo drives are based on the power class: both the servo motor and servo drive have the same power class *(1)*.

□ The combination of each servo drive with its related servo motor is designed to cover a nominal power range from 0.05 kW/*0.07 hp* up to 4.5 kW/*6.03 hp* with 200..240 V mains supply voltage *(1)*.

■ The Lexium 26 servo drives have degree of protection IP 20.

■ BCH2 motors provide a nominal torque from 0.16 Nm to 28.6 Nm and a nominal speed from 1,000 to 3,000 rpm, depending on the model. They are suitable for a wide variety of applications due to the different levels of motor inertia offered.

Applications

■ Material working (multi-axis machines, cutting machines, etc.)

■ Material handling (conveying, palletizers, warehousing, etc.)

■ Assembly line (clamping, etc.)

■ Packaging

■ Printing

■ Winding and unwinding

■ Textiles

■ Machine tools

■ Plastic and rubber

SoMove setup software: For commissioning and configuration

SoMove software is used for commissioning, parameter setting, diagnostics and maintenance.
The drives can be configured:

■ via their integrated HMI interface

■ or using the SoMove setup software

It can also be used for fast device replacement in existing machine installations.

■ SoMove setup software is used in just the same way as it is in other Schneider Electric drives, for configuring and optimizing control loops in automatic or manual mode using the Oscilloscope function and for maintenance of the Lexium 26 drive.

■ It can be used with the USB/RJ45 connection cable TCSMCNAM3M002P (see our SoMove software catalog or on our website.

Multi-Loader tool

The Multi-Loader tool enables configurations to be copied from a PC or a servo drive and loaded onto another servo drive. The servo drives do not need to be powered up (see page 9).

Mounting and maintenance

Connecting the servo drives is simplified by identified plug-in connectors, which are easily accessed on the front panel of the drive (see Description page 8).

(1) See table of combinations page 6.

Lexium 26

Lexium™ 26 servo drives and BCH2 servo motors

A user-oriented range of products

Lexium 26 range: specially designed for simple machines

A user-oriented range of products

Lexium 26 servo drive and BCH2 servo motor combinations are specially designed for easy integration & commissioning in your machine. They provide the right level of performance for the majority of simple motion control machines.

Fit for purpose

- Lexium 26 servo drives have digital and analog I/O as standard.
- The servo drives incorporate numerous functions, including auto-tuning, position/speed/torque control and position sequence mode.
- The compact dimensions of Lexium 26 servo drives mean they fit very easily into small spaces, thus reducing the size of the installation and the cost of the equipment.

Lexium 26 throughout the whole life cycle

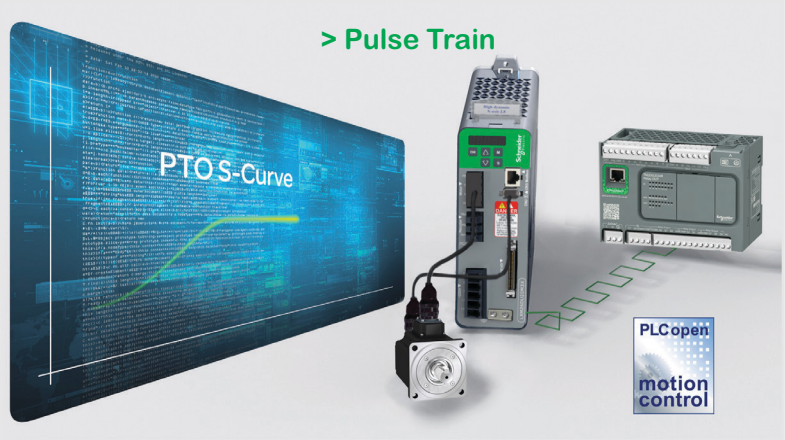
- Simple to select and order thanks to the “just enough” number of references
- Straightforward to mount and wire up
- Intuitive to set up and commission thanks to SoMove software
- Effortless to tune due to easy, comfortable and auto-adaptive tuning function
- Seamless to connect to our range of Modicon M200/M100 logic controllers

Robustness

- Motor shafts have degree of protection IP 65 as standard
- The motors can operate in temperatures from - 20 to 40 °C/*-4 to 104 °F*
- The drive printed circuit boards are coated for enhanced robustness in polluted environments

Widely available everywhere

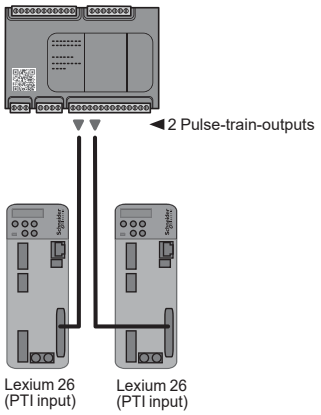
- Fast delivery through a large distribution network
- Fast access to information and support through the Partner Relationship Management tool and a dedicated network of engineers



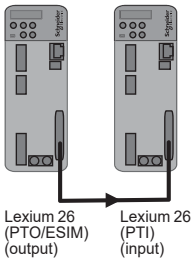
Lexium 26

Lexium™ 26 servo drives and BCH2 servo motors

Modicon M200 logic controller



Example of architecture with control by Modicon M200 logic controller



Example of a Lexium 26 drive controlling another Lexium 26 drive

Presentation of Lexium 26 servo drives

Lexium 26 servo drives feature numerous functions enabling them to be used in a wide range of motion control applications.

Main functions of Lexium 26 servo drives

- Automatic motor identification by the servo drive: the technical data related to the motor is provided from the motor to the drive via the encoder connection cable.
- Filtering: Anti-vibration function for suppression of resonance frequencies in the power train connected with the moving mass of the application
- Monitoring functions:
  - Status monitoring, I/O monitoring
  - Log function to memorize alarm and warning messages (in the drive)
  - Reset function for alarms and warnings
  - Monitoring of drive variables related to motor control and closed loop control

Additional functions of Lexium 26 servo drives

- Movement control with digital input interface directly in the servo drive:
  - Relative or absolute positioning mode
  - Velocity mode
  - Torque control mode
  - Position sequence mode: a sequence of up to 32 movements, controlled by a digital input interface

Control via I/O interface

The Lexium 26 servo drive is controlled with numerous digital and analog signals, accessible via the "CN1 IO" interface:

- 2 digital inputs for high-performance position capture
- 8 digital inputs
- 5 digital outputs
- 2 analog inputs
- 2 analog outputs

Drive functions activated by the commissioning software or directly by the HMI interface

- Jog mode: Velocity movement
- "Easy tuning" one-button tuning mode: this function is used to optimize application performance.
- 2 additional tuning functions, which can be activated by the SoMove commissioning software or by the HMI interface:
  - "Comfort tuning" with predefined settings for different mechanical systems such as spindle axes (e.g. portal axes), transportation belts, vertical axes (e.g. cantilever axes)
  - "Auto-adaptive tuning"

Operating modes for the Lexium 26 via the PTI interface

The movement of Lexium 26 drives can be managed by a machine controller (Modicon M200 logic controller) with pulse-train-input (PTO) interface or the ESIM (Encoder Simulator) interface from another (Lexium 26) servo drive.
The corresponding pulse-train-input (PTI) of the Lexium 26 drive is then electrically connected to the CN1 I/O interface.

Lexium 26

Lexium™ 26 servo drives and BCH2 servo motors



BCH2 servo motor with flying lead connection and terminal connectors



BCH2 servo motor with MIL connectors

Presentation of BCH2 servo motors

BCH2 motors are synchronous AC servo motors.

- They are equipped as standard with a high-resolution (20-bit) single-turn absolute encoder, ideal for high-performance applications such as material working, machine tools, etc.
- They are available in six flange sizes: 40 mm/*1.57 in.*, 60 mm/*2.36 in.*, 80 mm/*3.15 in.*, 100 mm/*3.94 in.*, 130 mm/*5.12 in.* and 180 mm/*7.09 in.*
- They are available with holding brake as an option.
- Depending on flange size, the BCH2 motors are supplied:
  - with flying leads and terminal connectors
  - or with MIL connectors

With the three types of motor inertia available, ranging from low to high inertia, the servo motors can be used in a very wide variety of applications:

- Low inertia: power between 0.2 kW/*0.27 hp* and 2 kW/*2.68 hp*, suitable for textile and packaging applications.
- Medium inertia: power between 0.05 kW/*0.07 hp* and 4.5 kW/*6.03 hp*, suitable for material working and machine tool applications.
- High inertia: 0.75 kW/*1.01 hp* power, suitable for metal working and printing applications.

Holding brake

BCH2 servo motors can be equipped with an electromagnetic holding brake.
⚠ *Do not use the holding brake as a dynamic brake for deceleration, as this will quickly damage the brake.*

Integrated encoder

BCH2 servo motors are equipped with a 20-bit single-turn absolute encoder.
This absolute encoder performs the following functions:

- measures the servo motor speed via the associated Lexium 26 servo drive (this information is used by the servo drive's position and speed controller)
- sends data from the servo motor to the servo drive, which provides automatic identification of the motor when the servo drive starts
- measures the motor angular position with a precision of ± 2.6 arc minutes.

Combinations: page 6 | Description/References for servo drives: page 8 | Accessories for servo drives: page 9 | Description/References for servo motors: page 14 | Accessories for servo motors: page 16

Lexium 26

Lexium™ 26 servo drives and BCH2 servo motors



Example of combination: one Lexium 26 servo drive (50 to 100 W), and one BCH2 servo motor with flying lead connection and 40 mm flange



Example of combination: one Lexium 26 servo drive (850 W to 1.5 kW) and one BCH2 servo motor with MIL connectors and 130 mm flange

Lexium 26 servo drive and BCH2 servo motor combinations

Power output	Nominal speed of rotation	Nominal torque	Max peak torque	With holding brake	Servo drive reference	Servo motor reference	Inertia (without holding brake)	Motor inertia type
kW/*hp*	min^{-1}	Nm	Nm				$kgcm^2$	
Single-phase and three-phase supply voltage: 200/240 VAC								
0.05/ ***0.07***	3,000	0.16	0.48	Yes	LXM26DUA5M3X	BCH2MBA533CF5C	0.054	Medium
				No		BCH2MBA533CA5C		
0.1/ ***0.13***	3,000	0.32	0.96	Yes	LXM26DU01M3X	BCH2MB0133CF5C	0.075	Medium
				No		BCH2MB0133CA5C		
0.2/ ***0.27***	3,000	0.64	1.92	Yes	LXM26DU02M3X	BCH2LD0233CF5C	0.16	Low
				No		BCH2LD0233CA5C		
0.3/ ***0.40***	1,000	2.86	8.59	Yes	LXM26DU04M3X	BCH2MM0313CF6C	6.63	Medium
				No		BCH2MM0313CA6C		
0.4/ ***0.54***	3,000	1.27	3.81	Yes	LXM26DU04M3X	BCH2LD0433CF5C	0.27	Low
				No		BCH2LD0433CA5C		
0.4/ ***0.54***	3,000	1.27	3.81	Yes	LXM26DU04M3X	BCH2LF0433CF5C	0.67	Low
				No		BCH2LF0433CA5C		
0.5/ ***0.67***	2,000	2.39	7.16	Yes	LXM26DU07M3X	BCH2MM0523CF6C	6.63	Medium
				No		BCH2MM0523CA6C		
0.6/ ***0.80***	1,000	5.73	17.19	Yes	LXM26DU07M3X	BCH2MM0613CF6C	6.63	Medium
				No		BCH2MM0613CA6C		
0.75/ ***1.01***	3,000	2.39	7.16	Yes	LXM26DU07M3X	BCH2LF0733CF5C	1.19	Low
				No		BCH2LF0733CA5C		
0.75/ ***1.01***	3,000	2.39	7.16	Yes	LXM26DU07M3X	BCH2HF0733CF5C	1.54	High
				No		BCH2HF0733CA5C		
0.85/ ***1.14***	1,500	5.39	13.8	Yes	LXM26DU10M3X	BCH2MM0813CF6C	13.5	Medium
				No		BCH2MM0813CA6C		
0.9/ ***1.21***	1,000	8.59	25.77	Yes	LXM26DU10M3X	BCH2MM0913CF6C	9.7	Medium
				No		BCH2MM0913CA6C		
1/ ***1.34***	3,000	3.18	9.54	Yes	LXM26DU10M3X	BCH2LH1033CF6C	2.4	Low
				No		BCH2LH1033CA6C		
1/ ***1.34***	2,000	4.77	14.3	Yes	LXM26DU10M3X	BCH2HM1023CF6C	8.41	High
				No		BCH2HM1023CA6C		
1.5/ ***2.01***	2,000	7.16	21.48	Yes	LXM26DU15M3X	BCH2MM1523CF6C	9.7	Medium
				No		BCH2MM1523CA6C		

Lexium 26

Lexium™ 26 servo drives and BCH2 servo motors



Example of combination: one Lexium 26 servo drive (2 kW) and one BCH2 servo motor with MIL connectors and 130 mm flange



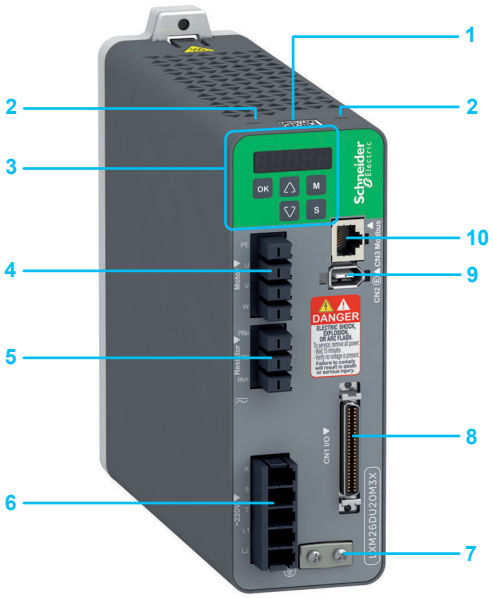
Example of combination: one Lexium 26 servo drive (4.5 kW) and one BCH2 servo motor with MIL connector and 180 mm flange

Lexium 26 servo drive and BCH2 servo motor combinations

Power output	Nominal speed of rotation	Nominal torque	Max peak torque	With holding brake	Servo drive reference	Servo motor reference	Inertia (without holding brake)	Motor inertia type
kW/*hp*	**min^{-1}**	**Nm**	**Nm**				**$kgcm^2$**	
Three-phase supply voltage: 200/240 VAC								
2.0/ *2.68*	3,000	6.37	19.11	Yes	LXM26DU20M3X	**BCH2LH2033CF6C**	4.26	Low
				No		**BCH2LH2033CA6C**		
2.0/ *2.68*	2,000	9.55	28.65	Yes	LXM26DU20M3X	**BCH2MM2023CF6C**	13.5	Medium
				No		**BCH2MM2023CA6C**		
2.0/ *2.68*	2,000	9.55	28.65	Yes	LXM26DU20M3X	**BCH2HR2023CF6C**	34.68	High
				No		**BCH2HR2023CA6C**		
3.0/ *4.02*	1,500	14.32	42.97	Yes	LXM26DU30M3X	**BCH2MR3023CF6C**	53.56	Medium
				No		**BCH2MR3023CA6C**		
3.0/ *4.02*	2,000	19.1	57.29	Yes	LXM26DU30M3X	**BCH2MR3013CF6C**	53.56	Medium
				No		**BCH2MR3013CA6C**		
3.5/ *4.69*	2,000	16.7	50.3	Yes	LXM26DU45M3X	**BCH2MR3523CF6C**	53.56	Medium
				No		**BCH2MR3523CA6C**		
4.5/ *6.03*	1,500	26.65	71.62	Yes	LXM26DU45M3X	**BCH2MR4513CF6C**	73.32	Medium
				No		**BCH2MR4513CA6C**		

Lexium 26

Lexium™ 26 servo drives and BCH2 servo motors



Description

On top of the drive:

1 QR code for access to detailed technical data, wiring guide and installation guide

2 Slot for application name plate

On the drive front:

3 HMI interface, 7-segment display, 5 buttons (OK, mode, set, value up, value down) and servo drive status LED

4 Removable terminal block *(1)*, 4 terminals (PE, U, V, W) for motor connection (marked Motor)

5 Removable terminal block *(1)*, 3 terminals (PBe, PBi, PA/+) for braking resistor connection (marked Resistor)

6 Removable terminal block *(1)*, 5 terminals (R, S, T, L1, L2) for connecting the 220 V ∿ power supply (marked ∿ 220 V)

7 Protected earth connector (marked ⏚)

8 Input/output interface connector (marked CN1 I/O)

9 Connector for motor encoder: 20-bit single-turn absolute encoder (marked CN2 Ⓔ)

10 RJ45 connector for Modbus serial link (marked CNE Modbus)

(1) Removable spring terminals are supplied with each servo drive.

References

To order a Lexium 26 servo drive, make up the reference as follows:

Example		**L**	**X**	**M**	**2**	**6**	**D**	**U**	**0**	**7**	**M**	**3**	**X**
Lexium 26 AC servo drive		**L**	**X**	**M**	**2**	**6**							
Interface	I/O interface						**D**						
Power	0.05 kW/*0.07 hp*							**U**	**A**	**5**			
	0.1 kW/*0.13 hp*							**U**	**0**	**1**			
	0.2 kW/*0.27 hp*							**U**	**0**	**2**			
	0.4 kW/*0.54 hp*							**U**	**0**	**4**			
	0.75 kW/*1.01 hp*							**U**	**0**	**7**			
	1 kW/*1.34 hp*							**U**	**1**	**0**			
	1.5 kW/*2.01 hp*							**U**	**1**	**5**			
	2 kW/*2.68 hp*							**U**	**2**	**0**			
	3 kW/*4.02 hp*							**U**	**3**	**0**			
	4.5 kW/*6.03 hp*							**U**	**4**	**5**			
Supply voltage	200…240 V ∿										**M**	**3**	**X**

Dimensions, weight

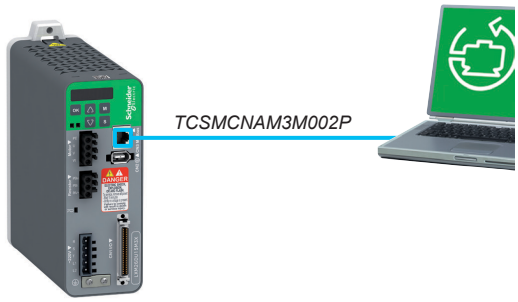
		Servo drives LXM26DU●●M3X			
		DUA5, DU01, DU02, DU04, DU07	**DU10, DU15**	**DU20**	**DU30, DU45**
Overall dimensions					
Width x Height	mm *in.*	55 x 150 *2.17 x 5.91*	55 x 150 *2.17 x 5.91*	62 x 170 *2.44 x 6.69*	117.4 x 234 *4.62 x 9.21*
Depth	mm *in.*	146 *5.75*	177 *6.97*	191.6 *7.54*	193 *7.60*
Weight					
kg / *lb*		1.000 / *2.190*	1.200 / *2.630*	1.700 / *3.720*	3.200 / *7.010*

Lexium 26

Lexium™ 26 servo drives and BCH2 servo motors

Configuration tools

PF140886



Configuration with the SoMove setup software

SoMove setup software

SoMove setup software is used on Lexium 26 servo drives in the same way as it is on other Schneider Electric drives and starters, to configure, adjust, debug, and maintain the drive.
A configuration can be transferred from a PC to the Lexium 26 servo drive via the USB/RJ45 cordset TCSMCNAM3M002P (used between the PC and the Lexium 26, on the CN3 interface).
SoMove setup software can be downloaded from our website www.schneider-electric.com.
For presentation, description, and references, see catalogue SoMove software on our website www.schneider-electric.com.

PF121331



TCSMCNAM3M002P

Reference		
Description	**Reference**	**Weight kg/*lb***
USB/RJ45 cordset Used to connect a PC to the device (Lexium 26): this cable is 2.5 m/*8.20 ft* long and has a USB connector (PC end) and an RJ45 connector (device end)	TCSMCNAM3M002P	–

PF140851



Configuration of a Lexium 26 in its packaging with the VW3A8121 Multi-Loader tool + VW3A8126 cordset

Multi-Loader configuration tool

The Multi-Loader tool enables several configurations to be copied from a PC or a servo drive and loaded onto another servo drive.
The Lexium 26 servo drives do not need to be powered up.

References		
Description	**Reference**	**Weight kg/*lb***
Multi-Loader configuration tool Supplied with: ■ 1 cordset equipped with 2 RJ45 connectors ■ 1 cordset equipped with one type A USB connector and one mini B USB connector ■ 1 x 2 GB SD memory card ■ 1 x female/female RJ 45 adapter ■ 4 AA 1.5 V LR6 round batteries	VW3A8121	–
Cordset for Multi-Loader tool For connecting the Multi-Loader tool to the Lexium 26 servo drive in its packaging. Equipped with: ■ A non-locking RJ45 connector with special mechanical catch on the drive end and ■ An RJ45 connector on the Multi-Loader end	VW3A8126	–

PF080629



VW3A8121

PF140849



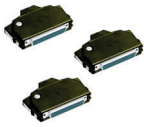
VW3A8126

Lexium 26

Lexium™ 26 servo drives and BCH2 servo motors

Connection accessories, accessories

PF140838



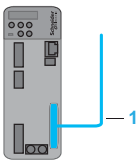
VW3M1C12

PF140847



VW3M1C13





VW3M1C10R●●

PF140840



VW3M2501

PF140852



Servo drive with application name plate VW3M2501

Connection accessories

Connectors

Designation	For use with	Description	Unit reference	Weight kg/*lb*
I/O connector (sold in lots of 3)	Lexium 26	Sub-D 50-pin connector for CN1 I/O interface	VW3M1C12	0.100/ *0.220*
I/O terminal block module	Lexium 26	Terminal block + Cordset (consisting of 2 Sub-D 50-pin connectors type VW3M1C12 and 0.5 m/*1.640 ft.* cable) for CN1 I/O interface connection	VW3M1C13	0.380/ *0.838*

I/O connection cordsets

Description	Use	Length m/*ft*	Reference	Weight kg/*lb*
Equipped with one SUB-D 50-pin connector for connection to the CN1 interface (drive end), and open end (controller end) (item 1)	This cable is dedicated to Schneider Electric PLCs, type Modicon M218/M221/M241/M200, for controlling Lexium 26 servo drives with pulse-train-output (PTO) and pulse-train-input (PTI) signals.	1/ *3.28*	VW3M1C10R10	0.100/ *0.220*
		2/ *6.56*	VW3M1C10R20	0.200/ *0.441*
		3/ *9.84*	VW3M1C10R30	0.300/ *0.661*

Accessories

Description	Use	Dimensions mm /*in.*	Unit reference	Weight kg/*lb*
Application name plate (sold in lots of 50)	This contains information about the servo drive. To be inserted in a dedicated slot on top of the servo drive	38.5 x 13/ *1.516 x 0.512*	VW3M2501	0.100/ *0.220*

Lexium 26

Lexium™ 26 servo drives and BCH2 servo motors

Options: braking resistors for servo drives

Presentation

Internal braking resistor

A braking resistor is built into the servo drive to absorb the braking energy. If the DC bus voltage in the servo drive exceeds a specified value, this braking resistor is activated. The restored energy is converted into heat by the braking resistor.
It enables maximum transient braking torque.

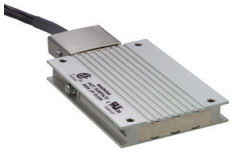
External braking resistor

When the servo motor has to be braked frequently, an external braking resistor is required to dissipate the excess braking energy. In this case, the internal braking resistor must be deactivated.
Several external braking resistors can be connected in parallel. The servo drive monitors the power dissipated in the braking resistor.
The casing degree of protection is IP 65 for VW3A7601R●● to VW3A7607R●● braking resistors and IP 20 for VW3A77●● braking resistors.
The operating temperature around the unit can be between 0 and + 50°C/+ *32 and + 122 °F*.
To optimize the size of the braking resistor, the DC buses on Lexium 26 servo drives in the same installation can be connected in parallel.

Applications

Machines with high inertia, driving loads, and machines with fast cycles.

PF106005



VW3A760●R●●

PF151240A



VW3A7734

References

External braking resistor

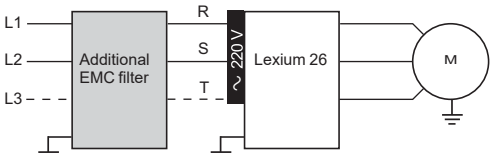
Ohmic value	Continuous power	Peak energy 230 V	Length of connection cable	Reference	Weight
Ω	W	Ws	m/*ft*		kg/*lb*
10	400	13,300	0.75/ *2.46*	VW3A7601R07	1.420/ *3.131*
			2/ *6.56*	VW3A7601R20	1.470/ *3.241*
			3/ *9.84*	VW3A7601R30	1.620/ *3.571*
10	956	–	–	VW3A7734	5.500/ *12.125*
16	956	–	–	VW3A7733	4.000/ *8.818*
27	100	3,800	0.75/ *2.46*	VW3A7602R07	0.630/ *1.389*
			2/ *6.56*	VW3A7602R20	0.780/ *1.720*
	200	7,400	0.75/ *2.46*	VW3A7603R07	0.930/ *2.050*
			3/ *9.84*	VW3A7603R30	1.200/ *2.646*
	400	18,100	0.75/ *2.46*	VW3A7604R07	1.420/ *3.131*
			2/ *6.56*	VW3A7604R20	1.470/ *3.241*
			3/ *9.84*	VW3A7604R30	1.620/ *3.571*
72	200	9,600	0.75/ *2.46*	VW3A7606R07	0.930/ *2.050*
			2/ *6.56*	VW3A7606R20	1.080/ *2.381*
			3/ *9.84*	VW3A7606R30	1.200/ *2.646*
	400	24,700	0.75/ *2.46*	VW3A7607R07	1.420/ *3.131*
			2/ *6.56*	VW3A7607R20	1.470/ *3.241*
			3/ *9.84*	VW3A7607R30	1.620/ *3.571*

***Note**: The total continuous power dissipated in the external braking resistor(s) must be less than or equal to the nominal power of the Lexium 26 servo drive.*

Lexium 26

Lexium™ 26 servo drives and BCH2 servo motors

Additional EMC input filters for servo drives



Lexium 26 servo drive with additional EMC filter

PF140850



EMC filter (VW3A4420) and Lexium 26 servo drive

PF095115



VW3A4422

Presentation

Lexium 26 servo drives require external input filters to comply with the EMC standard for variable speed electrical power drive “products” IEC/EN 61800-3, edition 2, category C3 in environment 2, and to comply with the European directive on EMC (electromagnetic compatibility).

Applications

Additional EMC filters are mounted next to the device. They have tapped holes for mounting in an enclosure.
The maximum servo motor cable length conforming to IEC/EN 61800-3 category C3 (1) in environment 2 is 20 m/*65.62 ft*.

Use according to the type of line supply

Integrated or additional EMC filters can only be used on TN (neutral connection) or TT (neutral to ground) systems.
Lexium 26 servo drives cannot be used on IT (impedance grounded or isolated neutral) systems. Standard IEC/EN 61800-3, appendix D2.1, states that on IT systems, filters can cause permanent insulation monitors to operate in a random manner.
If a machine has to be installed on an IT system, an isolation transformer must be inserted in order to recreate a TT system on the secondary side.

References

Additional EMC input filters

For servo drives (max. nominal power) *Combination*	Line current (A)	Reference	Weight kg/*lb*
Single-phase supply voltage			
50 W to 750 W servo drives *1 x EMC filter and a single Lexium 26 servo drive*	9	VW3A4420	0.600/ *1.323*
1 kW and 1.5 kW servo drives *1 x EMC filter and a single Lexium 26 servo drive*	16	VW3A4421	0.775/ *1.709*
Three-phase supply voltage			
50 W to 1.5 kW, 2kW and 3kW servo drives *1 x EMC filter and a single Lexium 26 servo drive*	15	VW3A4422	0.900/ *1.984*
4.5 kW servo drives *1 x EMC filter and a single Lexium 26 servo drive*	25	VW3A4423	1.350/ *2.976*

(1) Standard IEC/EN 61800-3: EMC immunity and conducted and radiated EMC emissions:
- Category C3 in environment 2: industrial premises.

Lexium 26

Lexium™ 26 servo drives and BCH2 servo motors

Motor starters

Protection using fuses



GV2P●●

+



LC1K●●●●



LC1D●●●●

+



LXM26DU●●M3X

Applications

The combinations listed below can be used to create a complete motor starter unit comprising a circuit-breaker, a contactor and a Lexium 26 servo drive.

■ The circuit-breaker provides protection against accidental short-circuits, disconnection and, if necessary, isolation.

■ The contactor activates and manages any safety functions, as well as isolating the servo motor on stopping.

The servo drive controls the servo motor, provides protection against short-circuits between the servo drive and the servo motor and protects the motor cable against overloads. Overload protection is provided by the servo drive's motor thermal protection.

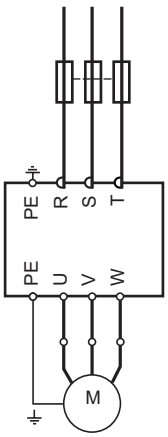
Combinations

Servo drive			Circuit-breaker		Contactor
Reference	**Nominal power (kW/*hp*)**	**Mains number of phases**	**Reference**	**Rating (A)**	**Reference** *(1) (2)*
Circuit-breakers for single drive installation according to IEC 60364-5-52					
Mains supply voltage: 200…240 V ∿ 50/60Hz					
LXM26DUA5M3X	0.05/*0.07*	1 or 3 phases	GV2P14	10	LC1K0610●●
LXM26DU01M3X	0.1/*0.13*	1 or 3 phases	GV2P14	10	LC1K0610●●
LXM26DUA5M3X	0.2/*0.27*	1 or 3 phases	GV2P14	10	LC1K0610●●
LXM26DU04M3X	0.4/*0.54*	1 or 3 phases	GV2P14	10	LC1K09●●
LXM26DU07M3X	0.75/*1.01*	1 or 3 phases	GV2P14	10	LC1K09●●
LXM26DU10M3X	1/*1.34*	1 or 3 phases	GV2P14	10	LC1K12●●
LXM26DU15M3X	1.5/*2.01*	1 or 3 phases	GV2P16	14	LC1D18●●
LXM26DU20M3X	2/*2.68*	3 phases	GV2P20	18	LC1D32●●
LXM26DU30M3X	3/*4.02*	3 phases	GV2P20	18	LC1D32●●
LXM26DU45M3X	4.5/*6.03*	3 phases	GV2P21	23	LC1D65●●

(1) Composition of the contactors:
LC1 K06: 3 poles + 1 N/O auxiliary contact
LC1 D●●: 3 poles + 1 N/O auxiliary contact + 1 N/C auxiliary contact
Please refer to the "Control and protection components" catalog.
(2) Replace ●● with the control circuit voltage code given in the table below:

	Volts ∿	**220**	**230**	**240**
LC1K	50/60 Hz	**M7**	**P7**	**U7**
	Volts ∿	**220/230**	**230**	**230/240**
LC1D	50 Hz	**M5**	**P5**	**U5**
	60 Hz	**M6**	**–**	**U6**
	50/60 Hz	**M7**	**P7**	**U7**

For other available voltages between 24 V and 660 V, or a DC control circuit, please contact our Customer Care Center.



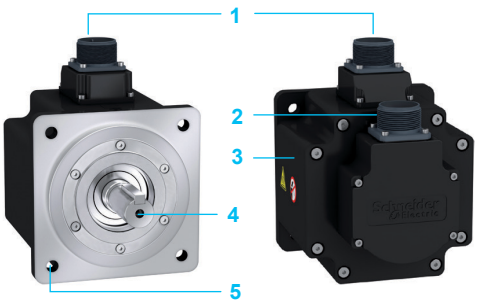
LXM26 servo drive, BCH2 servo motor with fuse protection

Protection using class J fuses (UL certification)

Servo drive		Fuse to be placed upstream (A)
Reference	**Nominal power (kW/*hp*)**	
Mains supply voltage: 200…240 V ∿ 50/60Hz		
LXM26DUA5M3X	0.05/*0.07*	5
LXM26DU01M3X	0.1/*0.13*	5
LXM26DU02M3X	0.2/*0.27*	5
LXM26DU04M3X	0.4/*0.54*	20
LXM26DU07M3X	0.75/*1.01*	20
LXM26DU10M3X	1/*1.34*	25
LXM26DU15M3X	1.5/*2.01*	40
LXM26DU20M3X	2/*2.68*	60
LXM26DU30M3X	3/*4.02*	80
LXM26DU45M3X	4.5/*6.03*	160

Lexium 26

Lexium™ 26 servo drives and BCH2 servo motors

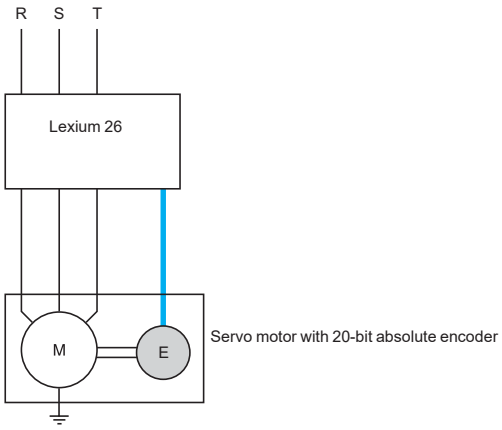


BCH2 servo motors

BCH2 servo motors, with a 3-phase stator and a rotor with rare earth permanent magnets, consist of:

1 A connector for the power cable
2 A connector for the encoder cable
3 Casing with RAL 9005 opaque black paint coating
4 A keyed shaft end with oil seal
5 4-point axial mounting flange (flange is mechanically compatible with Asian style servo motors)

Cables and connectors to be ordered separately, for connection to Lexium 26 servo drives. Schneider Electric has taken particular care over the compatibility of BCH2 servo motors and Lexium 26 servo drives. This compatibility is only possible when using cables and connectors sold by Schneider Electric (see page 17).



Integrated encoder in BCH2 servo motors

The standard measurement device for motor position and motor velocity is a 20-bit single-turn absolute encoder integrated in BCH2 servo motors. This measurement device is particularly suited to the Lexium 26 range of servo drives.
Use of this interface enables:

- Automatic identification of BCH2 servo motor data by the servo drive
- Automatic initialization of the servo drive control loops, thus simplifying installation and drive commissionning at the machine

BCH2 servo motors

References

To order a BCH2 servo motor, make up the reference as follows:

Brushless servo motor		**B**	**C**	**H**	**2**	**●**	**●**	**●●**	**●**	**●**	**C**	**●**	**●**	**C**
Inertia	Low inertia					**L**								
	Medium inertia					**M**								
	High inertia					**H**								
Flange size	40 mm (*1.58 in.*)						**B**							
	60 mm (*2.36 in.*)						**D**							
	80 mm (*3.15 in.*)						**F**							
	100 mm (*3.94 in.*)						**H**							
	130 mm (*5.12 in.*)						**M**							
	180 mm (*7.08 in.*)						**R**							
Rated output	50 W (*0.067 hp*)							**A5**						
	100 W (*0.13 hp*)							**01**						
	200 W (*0.26 hp*)							**02**						
	300 W (*0.41 hp*)							**03**						
	400 W (*0.53 hp*)							**04**						
	500 W (*0.67 hp*)							**05**						
	600 W (*0.80 hp*)							**06**						
	750 W (*1.00 hp*)							**07**						
	850 W (*1.13 hp*)							**08**						
	1 kW (*1.34 hp*)							**10**						
	1.5 kW (*2.01 hp*)							**15**						
	2 kW (*2.68 hp*)							**20**						
	3 kW (*4.02 hp*)							**30**						
	3.5 kW (*4.69 hp*)							**35**						
	4.5 kW (*6.03 hp*)							**45**						
Power supply ∼ 220 V Winding type	1000/1500 rpm								**1**					
	2000 rpm								**2**					
	3000 rpm								**3**					
Shaft end	Keyed shaft (shaft & housing IP 65)									**3**				
Encoder	High resolution single-turn absolute encoder, 20-bit resolution										**C**			
Holding brake	Without brake											**A**		
	With brake (option)											**F**		
Connections	Free leads with connectors (BCH2●B/●D/●F motors only)												**5**	
	MIL connectors (BCH2●H/●M/●R motors only)												**6**	
Mechanical motor design	Motor compatible with Asian style mounting standards													**C**

Dimensions and weight

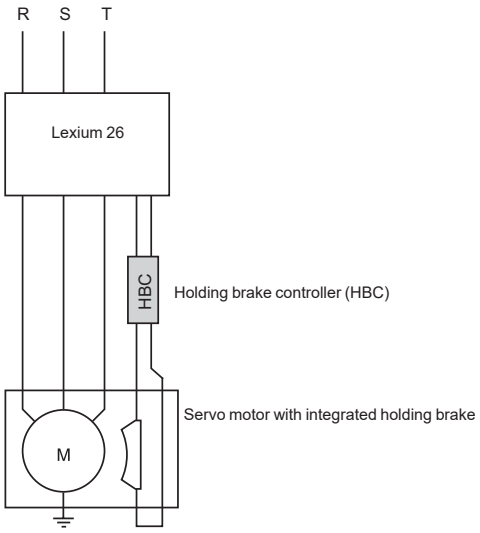
Servo motor	**Pn**	**Flange**		**Dimensions** (overall) **Servo motor without brake** Width x Height x Depth (W x H x D)		**Servo motor with brake** Width x Height x Depth (W x H x D)		**Weight without brake**		**with brake**	
	W	**mm**	***in.***	**mm**	***in.***	**mm**	***in.***	**kg**	***lb***	**kg**	***lb***
BCH2MBA533●●5C	50	40	*1.57*	40 x 58.5 x 82	*1.57 x 2.30 x 3.23*	40 x 58.5 x 112	*1.57 x 2.30 x 4.41*	0.400	*0.880*	0.600	*1.320*
BCH2MB0133●●5C	100	40	*1.57*	40 x 58.5 x 100	*1.57 x 2.30 x 3.94*	40 x 58.5 x 130	*1.57 x 2.30 x 5.12*	0.560	*1.230*	0.770	*1.700*
BCH2LD0233●●5C	200	60	*2.36*	60 x 78.5 x 104	*2.36 x 3.09 x 4.09*	60 x 78.5 x 140	*2.36 x 3.09 x 5.51*	1.020	*2.250*	1.500	*3.310*
BCH2LD0433●●5C	400	60	*2.36*	60 x 78.5 x 129	*2.36 x 3.09 x 5.08*	60 x 78.5 x 165	*2.36 x 3.09 x 6.50*	1.450	*3.200*	2.000	*4.410*
BCH2LF0433●●5C	400	80	*3.15*	80 x 98.5 x 112	*3.15 x 3.88 x 4.41*	80 x 98.5 x 152	*3.15 x 3.88 x 4.41*	2.000	*4.410*	2.800	*6.170*
BCH2HF0733●●5C	750	80	*3.15*	80 x 98.5 x 138	*3.15 x 3.88 x 5.43*	80 x 98.5 x 178	*3.15 x 3.88 x 7.01*	2.900	*6.390*	3.700	*8.160*
BCH2LF0733●●5C	750	80	*3.15*	80 x 98.5 x 138	*3.15 x 3.88 x 5.43*	80 x 98.5 x 178	*3.15 x 3.88 x 7.01*	2.800	*6.170*	3.600	*7.940*
BCH2LH1033●●6C	1000	100	*3.94*	100 x 145.6 x 153.5	*3.94 x 5.73 x 6.04*	100 x 145.6 x 180.5	*3.94 x 5.73 x 7.11*	4.600	*10.140*	5.100	*11.240*
BCH2LH2033●●6C	2000	100	*3.94*	100 x 145.6 x 198.5	*3.94 x 5.73 x 7.81*	100 x 145.6 x 225.5	*3.94 x 5.73 x 8.88*	6.700	*14.770*	7.200	*15.870*
BCH2MM0313●●6C	300	130	*5.12*	130 x 175.6 x 147	*5.12 x 6.91 x 5.79*	130 x 175.6 x 183	*5.12 x 6.91 x 7.20*	7.000	*15.430*	8.200	*18.080*
BCH2MM0523●●6C	500	130	*5.12*	130 x 175.6 x 147	*5.12 x 6.91 x 5.79*	130 x 175.6 x 183	*5.12 x 6.91 x 7.20*	7.000	*15.430*	8.200	*18.080*
BCH2HM1023●●6C	1000	130	*5.12*	130 x 175.6 x 147	*5.12 x 6.91 x 5.79*	130 x 175.6 x 183	*5.12 x 6.91 x 7.20*	7.000	*15.430*	8.200	*18.080*
BCH2MM0813●●6C	850	130	*5.12*	130 x 175.6 x 187	*5.12 x 6.91 x 7.36*	130 x 175.6 x 216	*5.12 x 6.91 x 8.50*	9.600	*21.160*	10.900	*24.030*
BCH2MM0913●●6C	900	130	*5.12*	130 x 175.6 x 163	*5.12 x 6.91 x 6.42*	130 x 175.6 x 198	*5.12 x 6.91 x 7.80*	7.600	*16.760*	8.800	*19.400*
BCH2MM1523●●6C	1500	130	*5.12*	130 x 175.6 x 167	*5.12 x 6.91 x 6.57*	130 x 175.6 x 202	*5.12 x 6.91 x 7.95*	7.600	*16.760*	8.800	*19.400*
BCH2MM2023●●6C	2000	130	*5.12*	130 x 175.6 x 187	*5.12 x 6.91 x 7.36*	130 x 175.6 x 216	*5.12 x 6.91 x 8.50*	9.700	*21.380*	11.000	*24.250*
BCH2HR2023●●6C	2000	180	*7.09*	180 x 245.1 x 169	*7.09 x 9.65 x 6.65*	180 x 245.1 x 203	*7.09 x 9.65 x 7.99*	13.000	*28.660*	18.000	*39.680*
BCH2MR3013●●6C	3000	180	*7.09*	180 x 245.1 x 202	*7.09 x 9.65 x 7.95*	180 x 245.1 x 235	*7.09 x 9.65 x 9.25*	18.500	*40.790*	23.000	*50.710*
BCH2MR3023●●6C	3000	180	*7.09*	180 x 245.1 x 202	*7.09 x 9.65 x 7.95*	180 x 245.1 x 235	*7.09 x 9.65 x 9.25*	18.500	*40.790*	23.000	*50.710*
BCH2MR3523●●6C	3500	180	*7.09*	180 x 245.1 x 202	*7.09 x 9.65 x 7.95*	180 x 245.1 x 235	*7.09 x 9.65 x 9.25*	18.500	*40.790*	23.000	*50.710*
BCH2MR4513●●6C	4500	180	*7.09*	180 x 245.1 x 235	*7.09 x 9.65 x 9.25*	180 x 245.1 x 279	*7.09 x 9.65 x 10.98*	23.640	*52.120*	28.000	*61.730*

Presentation: page 2 | Combinations: page 6 | Description/References for servo drives: page 8 | Accessories for servo drives: page 9 | Accessories for servo motors: page 16

Lexium 26

Lexium™ 26 servo drives and BCH2 servo motors

Option: holding brake controller



Holding brake controller

Presentation

If a servo motor has a holding brake, it is necessary to provide an appropriate control logic (HBC, Holding Brake Controller), which releases the brake when power is supplied to the servo motor and immobilizes the servo motor shaft when it is stationary. The holding brake controller amplifies the braking control signal **(**Digital output**)** transmitted by the Lexium 26 servo drive, so that the brake is deactivated quickly. It then reduces this control signal so as to decrease the power dissipated by the holding brake.

DF536284



VW3M3103

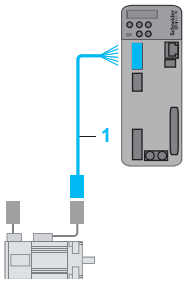
References

Description	Description	Reference	Weight kg/lb
Holding brake controller	24 V ⎓ power supply Max. power 0.05 kW/*0.07 hp* IP 20, for mounting on 55 mm/*2.17 in.* ⊔ rail	VW3M3103	0.600/ *1.323*

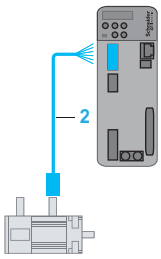
Lexium 26

Lexium™ 26 servo drives and BCH2 servo motors

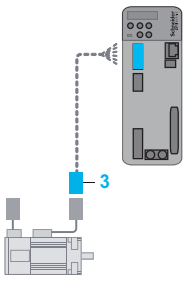
Connection components:
Motor power cordsets, Connector kits



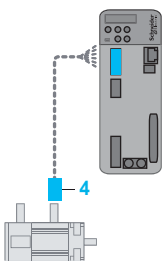
VW3M5D1●R●●



VW3M5D2●R●●
VW3M5D4●R●●
VW3M5D6●R●●



VW3M5D1●



VW3M5D2●

Connection components for BCH2 servo motors

Power cable type

Connector	AWG	mm²	Length m/*ft*	Reference	Weight kg/*lb*
Shielded power cordsets for BCH2 motors without brake					
Equipped with one quick connector (servo motor end), and open end (servo drive end) (item 1)	AWG18	4 x 1	1.5/ *4.92*	VW3M5D1AR15	0.200/ *0.441*
			3/ *9.84*	VW3M5D1AR30	0.300/ *0.661*
			5/ *16.40*	VW3M5D1AR50	0.450/ *0.992*
Equipped with one MIL connector (servo motor end), and open end (servo drive end) (item 2)	AWG16	4 x 1.5	3/ *9.84*	VW3M5D2AR30	0.450/ *0.992*
			5/ *16.40*	VW3M5D2AR50	0.700/ *1.543*
	AWG12	4 x 4	3/ *9.84*	VW3M5D4AR30	0.750/ *1.653*
			5/ *16.40*	VW3M5D4AR50	1.250/ *2.756*
	AWG10	4 x 6	3/ *9.84*	VW3M5D6AR30	2.100/ *4.630*
			5/ *16.40*	VW3M5D6AR50	3.400/ *7.496*
Shielded power cordsets for BCH2 motors with brake					
Equipped with one quick connector (servo motor end), and open end (servo drive end) (item 1)	AWG18	(4 x 1) + (2 x 1)	3/ *9.84*	VW3M5D1FR30	0.300/ *0.661*
			5/ *16.40*	VW3M5D1FR50	0.450/ *0.992*
Equipped with one MIL connector (servo motor end), and a free lead (servo drive end) (item 2)	AWG16	(4 x 1.5) + (2 x 1)	3/ *9.84*	VW3M5D2FR30	0.650/ *1.433*
			5/ *16.40*	VW3M5D2FR50	0.900/ *1.984*
	AWG12	(4 x 4) + (2 x 1.5)	3/ *9.84*	VW3M5D4FR30	0.950/ *2.094*
			5/ *16.40*	VW3M5D4FR50	1.450/ *3.197*
	AWG10	(4 x 6) + (2 x 1.5)	3/ *9.84*	VW3M5D6FR30	3.000/ *6.614*
			5/ *16.40*	VW3M5D6FR50	5.000/ *11.023*

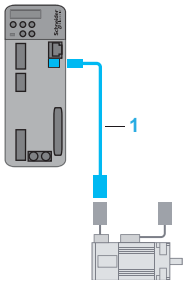
Motor power connector kits

Description	For use with	Unit reference	Weight kg/*lb*
Motor power connector kits (sold in lots of 3) (item 3)	BCH2●B/●D/●F motors (flange size: 40/60/80 mm) with flying lead connection, without brake	VW3M5D1A	0.150/ *0.331*
	BCH2●B/●D/●F motors (flange size: 40/60/80 mm) with flying lead connection, with brake	VW3M5D1F	0.150/ *0.331*
Power MIL connector kits (item 4)	BCH2●H/●M motors (flange size: 100/130 mm) with or without brake	VW3M5D2A	0.300/ *0.661*
	BCH2●R motors (flange size: 180 mm, from 2.0 kW to 4.5 kW) with or without brake	VW3M5D2B	0.300/ *0.661*

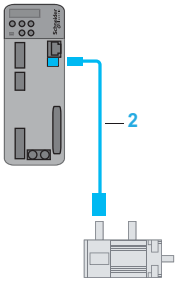
Lexium 26

Lexium™ 26 servo drives and BCH2 servo motors

Connection components:
Shielded encoder cordsets, Encoder connector kits



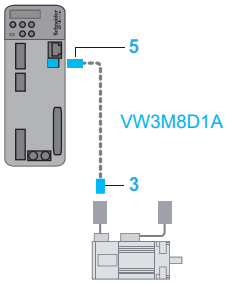
VW3M8D1AR●●



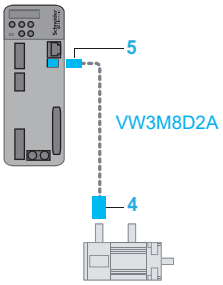
VW3M8D2AR●●

Connection components for BCH2 servo motors

Description	For use with	Composition	Length m/*ft*	Reference	Weight kg/*lb*
Shielded encoder cordsets					
Equipped with one plastic connector (servo motor end), and a firewire connector (servo drive end) (item 1)	BCH2●B/●D/●F motors, for connection to CN2 interface	10 x 0.13 mm²/ *10 x 26 AWG*	1.5/ *4.92*	VW3M8D1AR15	0.500/ *1.102*
			3/ *9.84*	VW3M8D1AR30	1.000/ *2.205*
			5/ *16.40*	VW3M8D1AR50	1.200/ *2.646*
Equipped with one MIL connector (servo motor end), and a firewire connector (servo drive end) (item 2)	BCH2●H/●M/●R motors, for connection to CN2 interface	10 x 0.13 mm²/ *10 x 26 AWG*	3/ *9.84*	VW3M8D2AR30	1.300/ *2.866*
			5/ *16.40*	VW3M8D2AR50	1.500/ *3.307*



BCH2●●●●●C●5C with single-turn encoder



BCH2●●●●C●6C with single-turn encoder

Encoder connector kits					
Encoder connector kits including one plastic connector (servo motor end), (item 3) **and a firewire connector (servo drive end)** (item 5) **(sold in lots of 2)**	BCH2●B/●D/●F motors (flange: 40/60/80 mm) with flying lead connection		–	VW3M8D1A	0.150/ *0.331*
Encoder connector kits including one MIL connector (servo motor end), (item 4) **and a firewire connector (servo drive end)** (item 5) **(sold in lots of 2)**	BCH2●H/●M/●R motors (flange: 100/130/180 mm) with MIL connector		–	VW3M8D2A	0.150/ *0.331*

Lexium 26

Lexium™ 26 servo drives and BCH2 servo motors

Connection components:
Motor connector kits, encoder connector kits

Selection of motor connector kit or encoder connector kit, according to BCH2 motor type

Motor	Motor power cable connector kit		Encoder connector kit	Motor power cable		Encoder cable
	Without brake	With brake		Without brake	With brake	
BCH2MBA53●●5C	VW3M5D1A	VW3M5D1F	VW3M8D1A	VW3M5D1AR15 VW3M5D1AR30 VW3M5D1AR50	VW3M5D1FR30 VW3M5D1FR50	VW3M8D1AR15 VW3M8D1AR30 VW3M8D1AR50
BCH2MB0133●●5C						
BCH2LD0233●●5C						
BCH2LD0433●●5C						
BCH2LF0433●●5C						
BCH2HF0733●●5C						
BCH2LF0733●●5C						
BCH2LH1033●●6C	VW3M5D2A	VW3M5D2A	VW3M8D2A	VW3M5D2AR30 VW3M5D2AR50	VW3M5D2FR30 VW3M5D2FR50	VW3M8D2AR30 VW3M8D2AR50
BCH2LH2033●●6C						
BCH2MM0813●●6C						
BCH2MM0313●●6C						
BCH2MM0523●●6C						
BCH2MM0613●●6C						
BCH2HM1023●●6C						
BCH2MM0913●●6C						
BCH2MM1523●●6C						
BCH2MM2023●●6C						
BCH2HR2023●●6C	VW3M5D2B	VW3M5D2B	VW3M8D2A	VW3M5D4AR30 VW3M5D4AR50	VW3M5D4FR30 VW3M5D4FR50	VW3M8D2AR30 VW3M8D2AR50
BCH2MR3013●●6C				VW3M5D6AR30 VW3M5D6AR50	VW3M5D6FR30 VW3M5D6FR50	
BCH2MR3023●●6C						
BCH2MR3523●●6C						
BCH2MR4513●●6C						

Lexium 26

Lexium™ 26 servo drives and BCH2 servo motors

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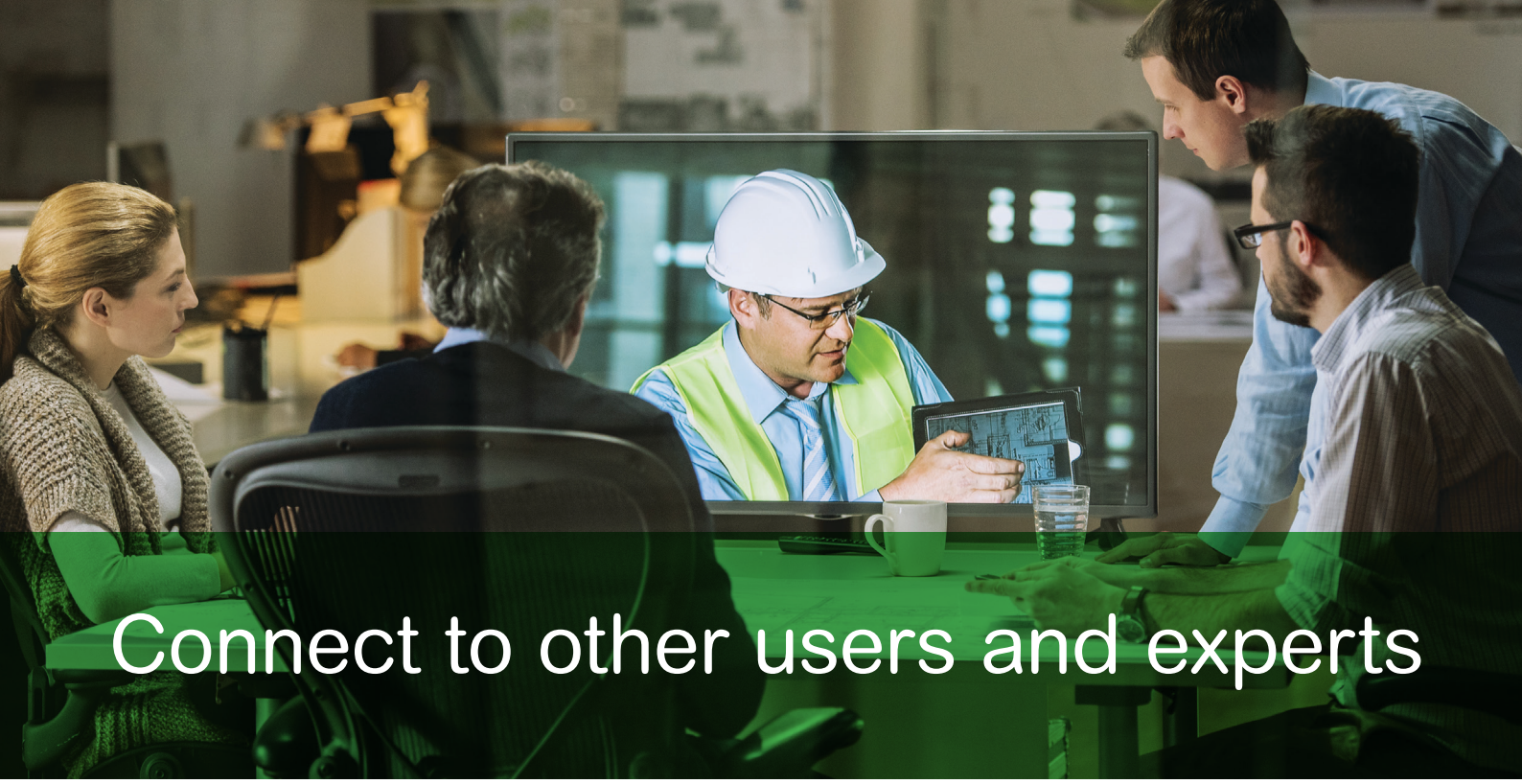
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VW3M1C10R20 10
VW3M1C10R30 10
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Schneider Electric support forum for **Motion Control solutions** from design, implementation to troubleshooting and more, including:

- Multicarrier systems
- Robotics
- Integrated Drives
- Servo Drives and Motors
- Stepper Drives and Motors
- Motion Controllers
- Programmable Logic Controllers
- Safety PLC Controllers
- Input/Output (I/O) modules
- Engineering software

Access the community forum

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Advantage Service Plan for Robotics

Keep the movement on

Keep your Lexium Robots, Cobots, MC12 Multi Carrier, SCARA, Cartesian, and associated controllers running smoothly and efficiently with a service contract. Maintain productivity by reducing unexpected downtime. Get peace of mind from knowing that you have access to experienced service technicians and spare parts when and where you need them.



Key benefits

- **Reduce costs** by identifying and correcting potential issues before they cause unplanned downtime.
- **Access to experts** helps you maintain production, reduce downtime and get the most out of your robotic systems.
- **Minimize unplanned downtime** with ready access to wear and spare parts.
- **Extend asset life** with properly maintained robotics.

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Schneider Electric



Advantage Service Plan for Robotics

Key features

Preventive maintenance visit

Periodic maintenance, based on the operations performed by the robot, is essential to prevent unplanned downtime and extend asset life. During the included preventive maintenance visit, our service representatives perform a routine check-up, and all the maintenance activities needed, based on the number of operations or operating time performed.

Remote technical support

Your Advantage Service Plan provides you with access to our advanced technical support team, who can answer your robotics questions and troubleshoot a problem via phone or email during normal business hours.

On site corrective maintenance service

In the event of an incident that results in unplanned downtime for your robot that cannot be resolved remotely, our service representatives can respond on site for diagnostic and corrective maintenance activities. Programming and commissioning are not included in this service.

Preferred rate for parts

For simplified ordering, we offer parts needed for the upkeep of your robots. These parts are offered at preferential rates for our contract customers.

Extended warranty (optional service)

When ordered with the contract, you can extend the warranty for one year beyond the standard warranty.

Support coverage

Support is available for the following ranges of Schneider Electric™ robots:

- Lexium Delta P
- Lexium Delta T
- Lexium Cobots
- Lexium MC12 Multi Carrier
- Lexium SCARA
- Lexium Cartesian

Service Plans (Available with TWO tiers)

Advantage Service Plan for Robotics	Duration	Essential	Advanced
Remote technical support (8X5) - Premium	1 year	Yes	Yes
Access to MySchneider portal - Premium	1 year	Yes	Yes
Preventive Maintenance visit	1 year		Yes
Preferred rate for parts	1 year		Yes
Onsite corrective Maintenance	1 year		Yes
Optional Service			
Extended warranty - 1 year	1 year		

For more information, please contact your Schneider Electric Representative.

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